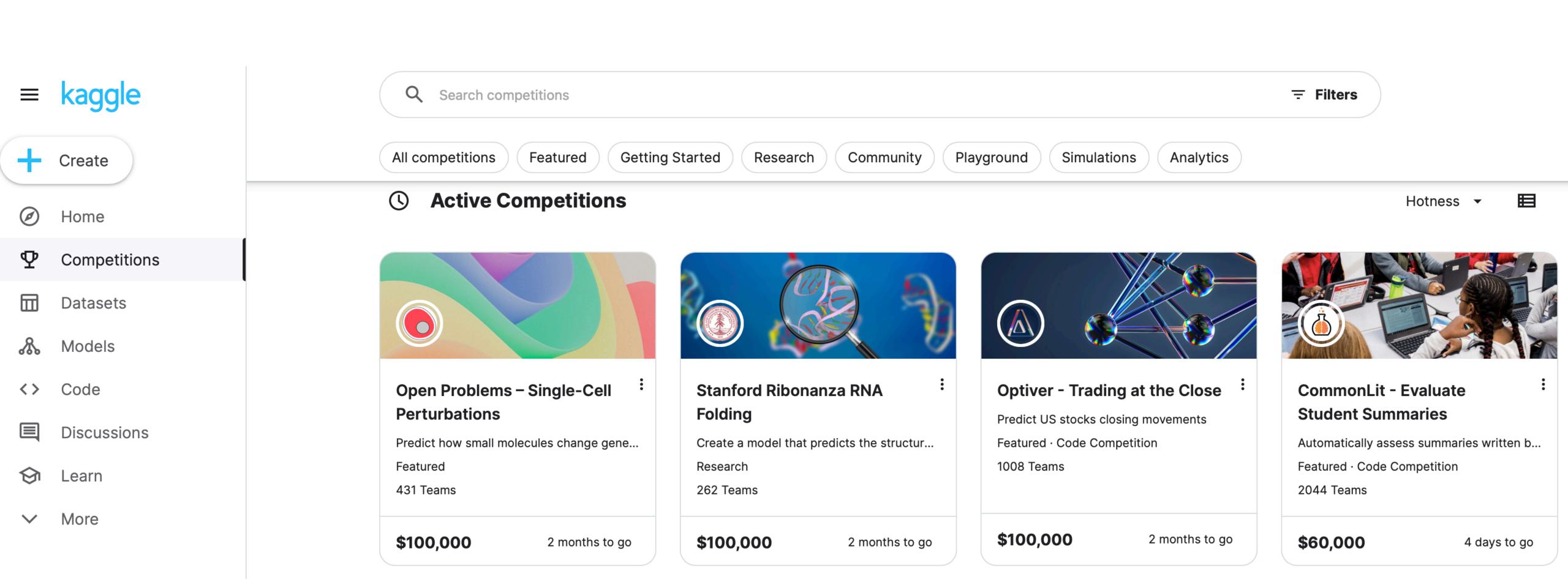
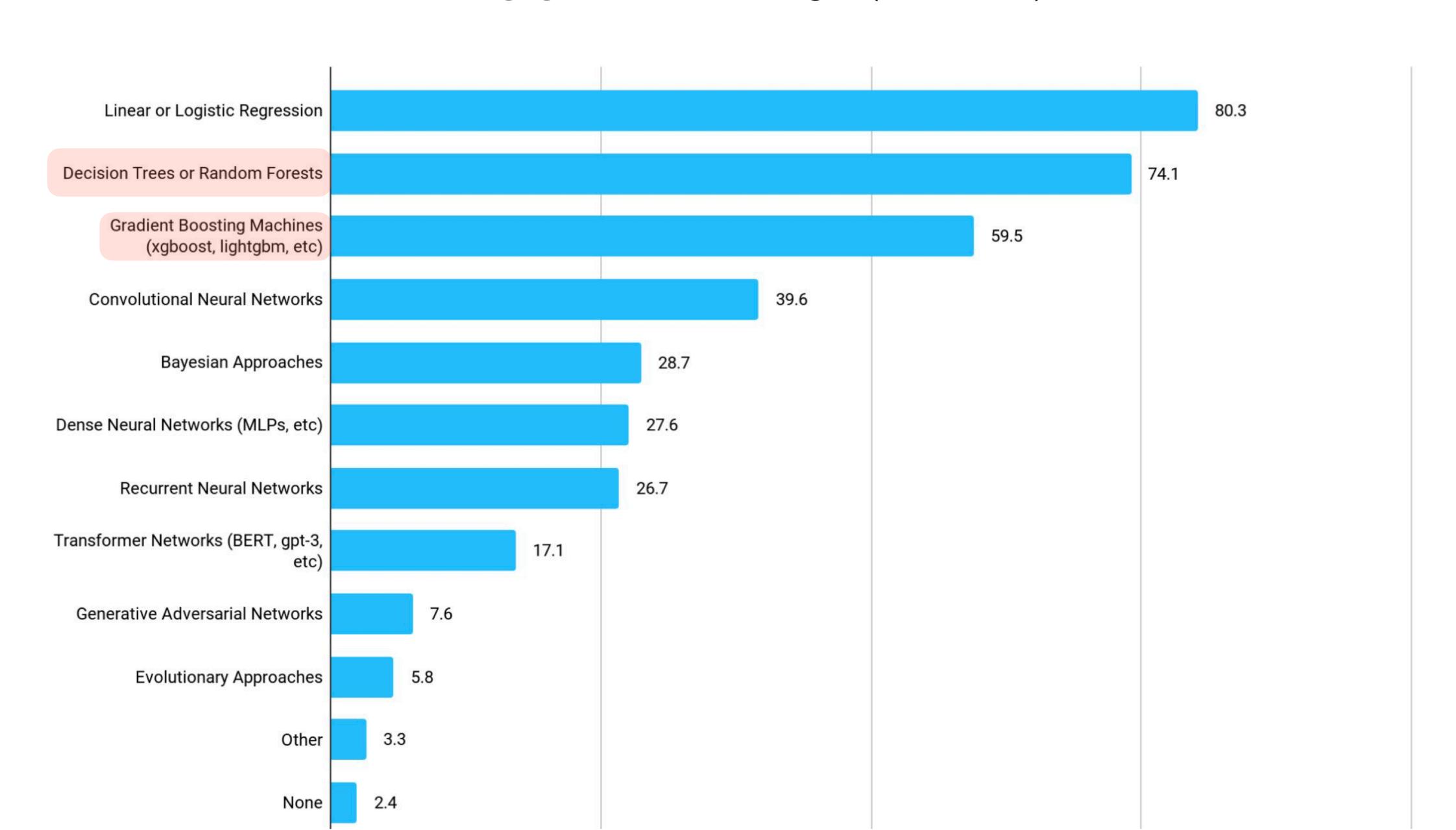
# Decision Trees

#### Motivation

- Kaggle. A competition platform for ML and data science
  - People upload data and put bounty to it
  - You solve it



## Kaggle Survey (2021)

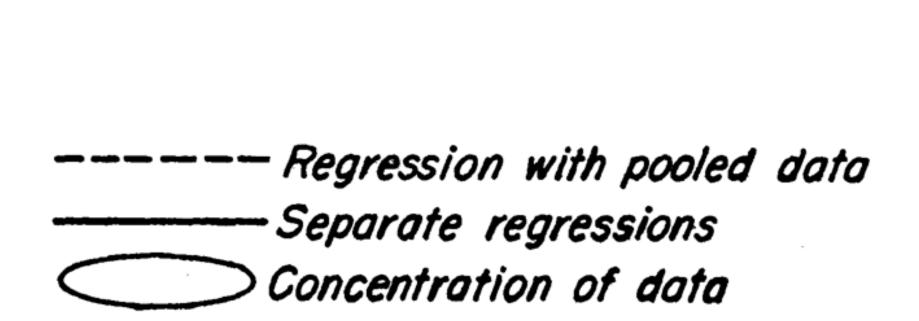


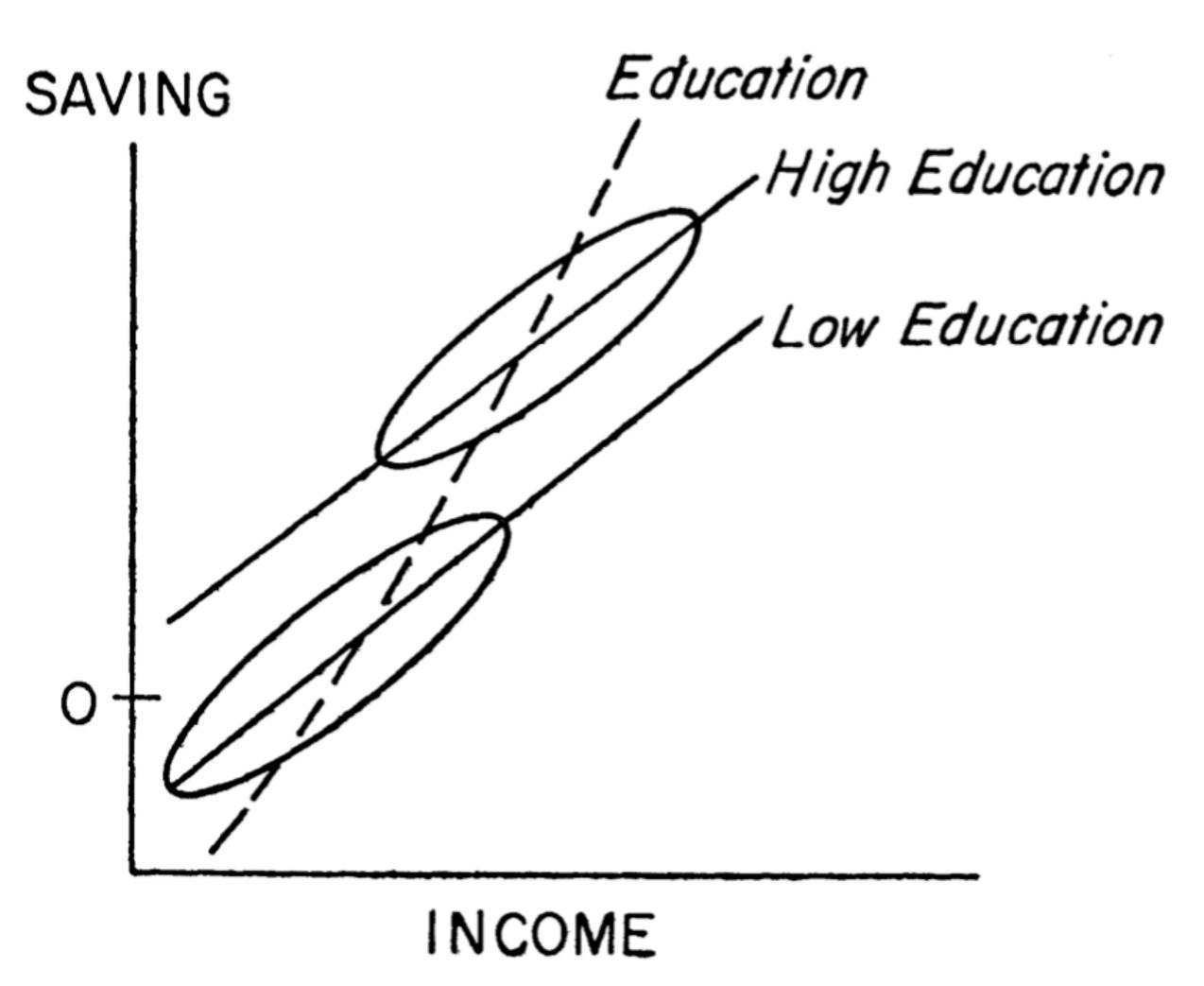
- Use in modern ML traces back to Morgan & Sonquist (1963)
  - Analyzing survey data on income & savings
    - Data included many demographic subgroups
  - Turned out that the trend was highly nonlinear

TABLE 1. SPENDING UNIT INCOME AND THE NUMBER IN THE UNIT WITHIN VARIOUS SUBGROUPS

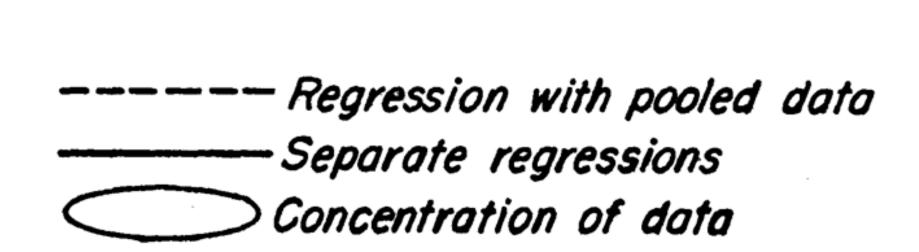
Spending unit average (1958) income	Number in unit	Number of cases
\$ 2489	3.3	191
5005	3.4	67
2217	1.7	272
4520	1.7	72
3950	3.6	87
6750	3.6	24
	average (1958) income \$ 2489 5005 2217 4520	average (1958)     in unit       \$ 2489     3.3       5005     3.4       2217     1.7       4520     1.7       3950     3.6

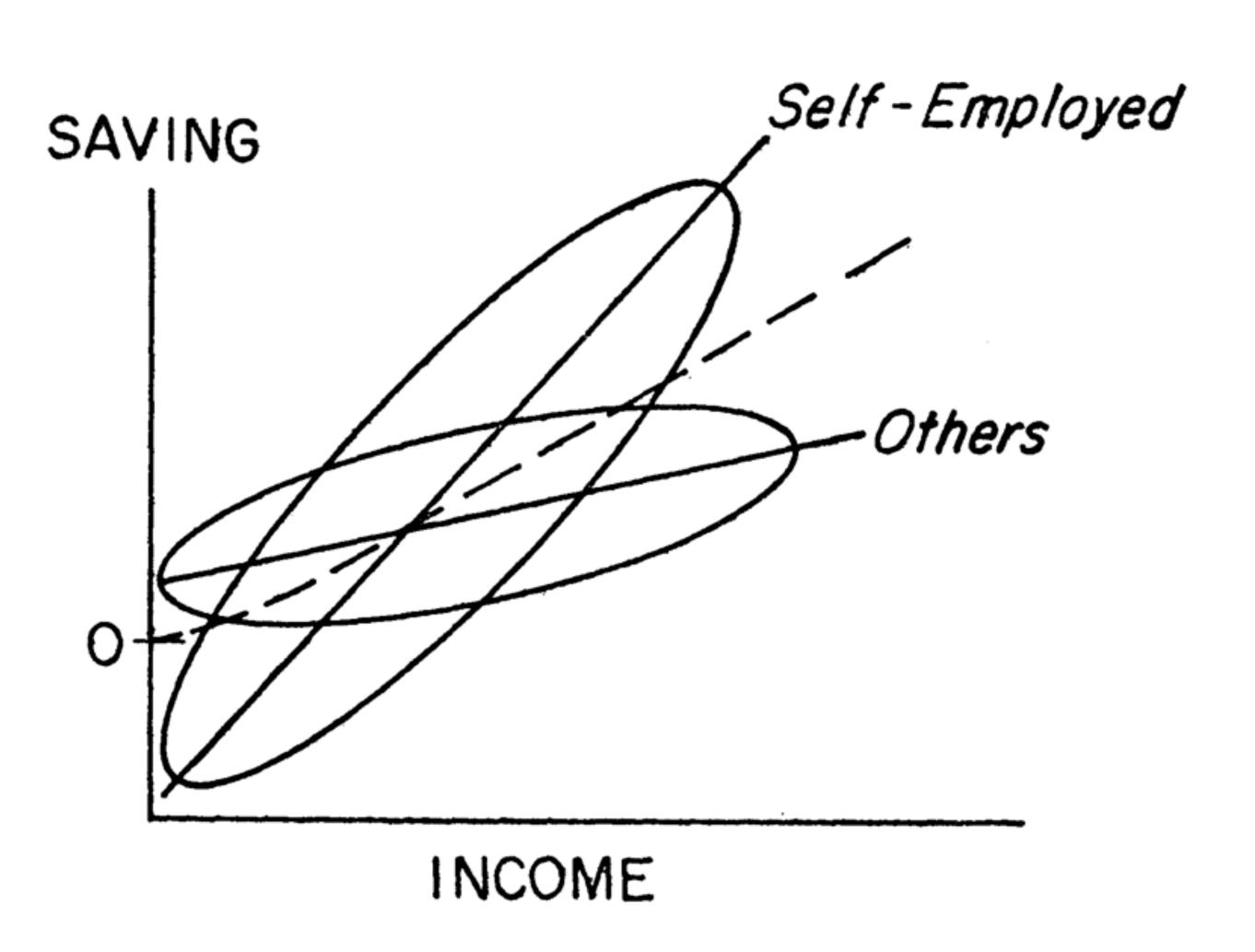
- Case 1. Multi-collinearity
  - Correlation between income & education, but no interaction



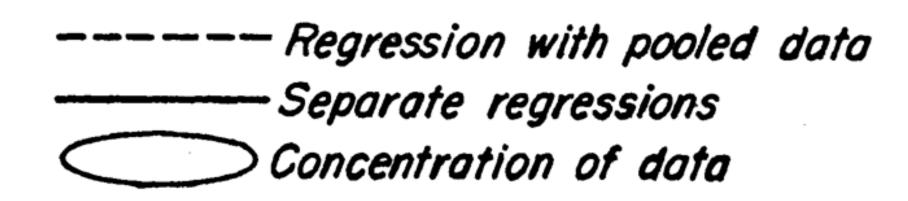


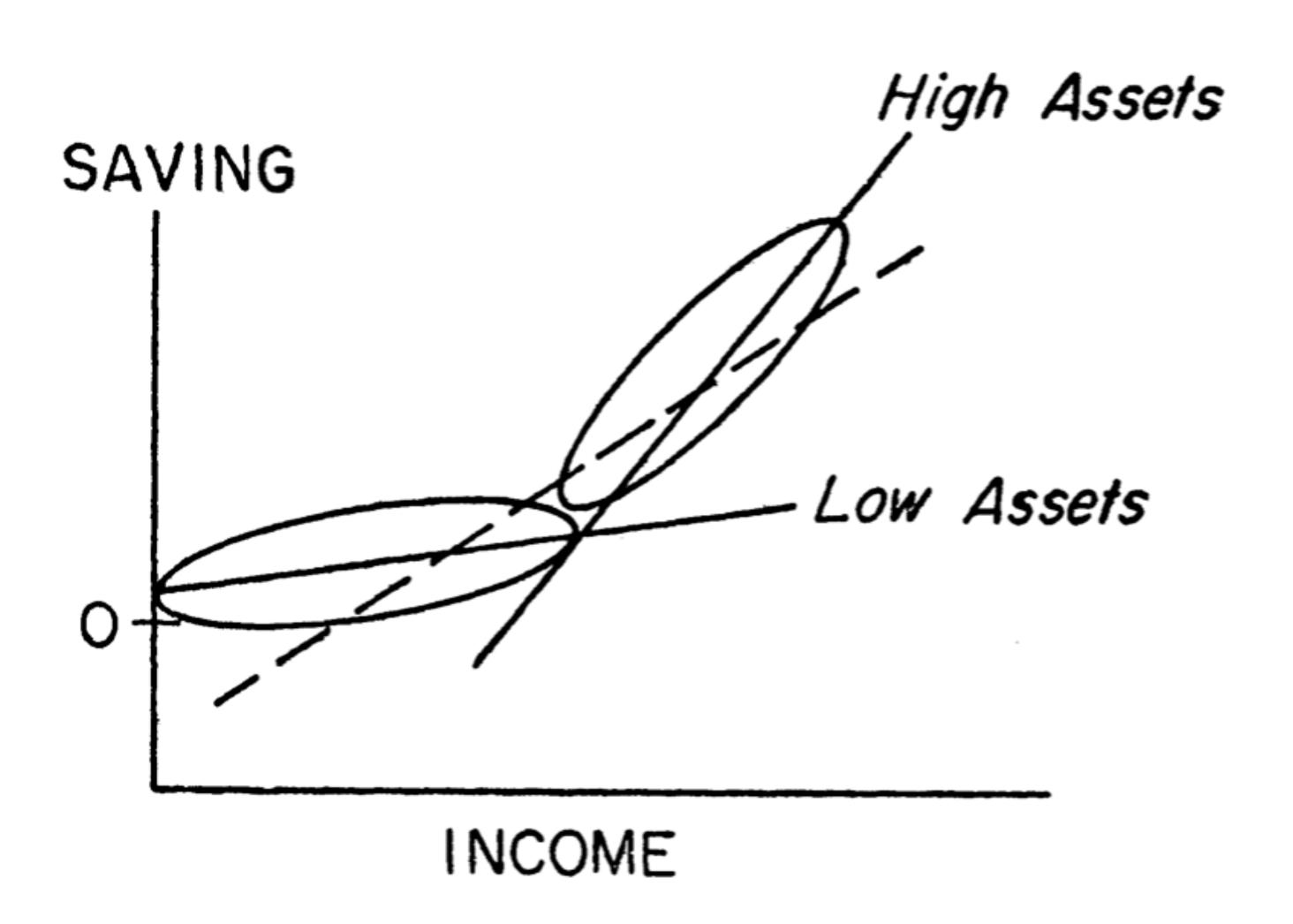
- Case 2. Interaction between features
  - No correlation between income & self-employment



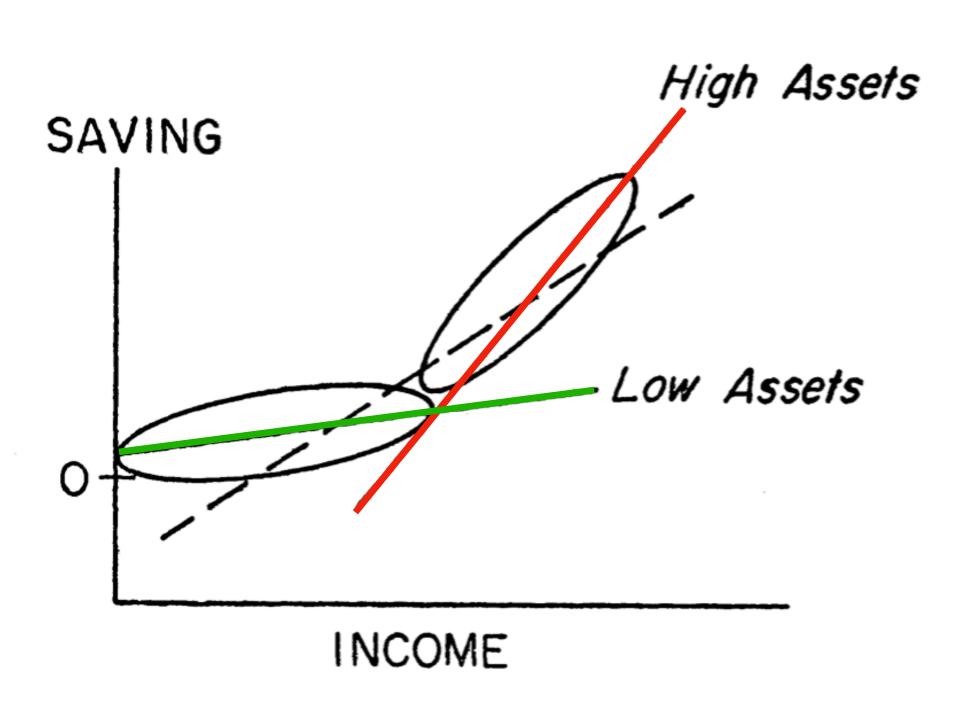


• Case 3. Both





- In each of these examples, having a single linear model doesn't work well
- Idea. Take a sequential approach
  - <u>Divide</u>. Partition the data into many subgroups
  - Conquer. Have a simple model for each subgroup (e.g., linear)
- Example. High asset?
  - Yes  $\rightarrow$  use curve 1
  - No  $\rightarrow$  use curve 2



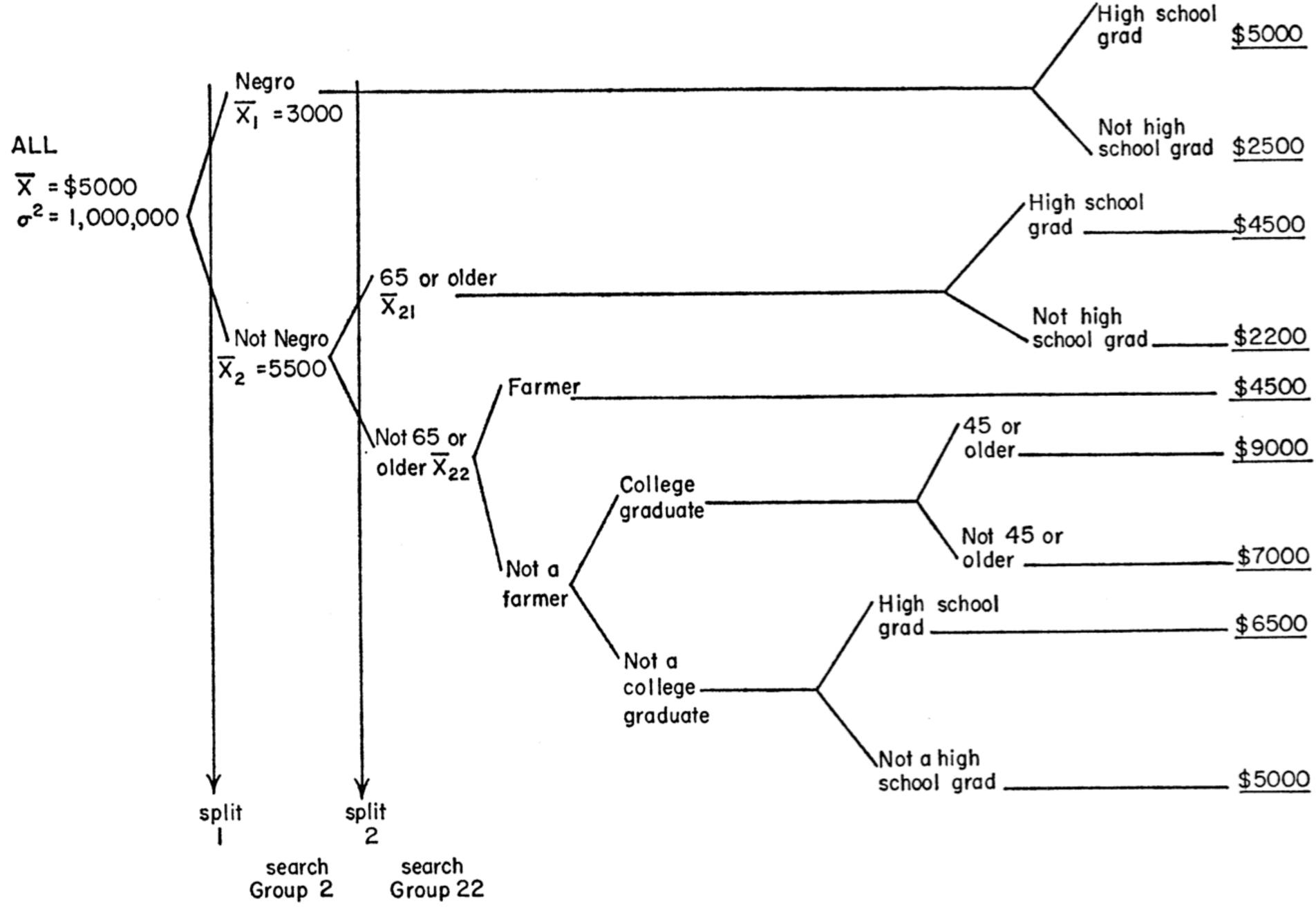
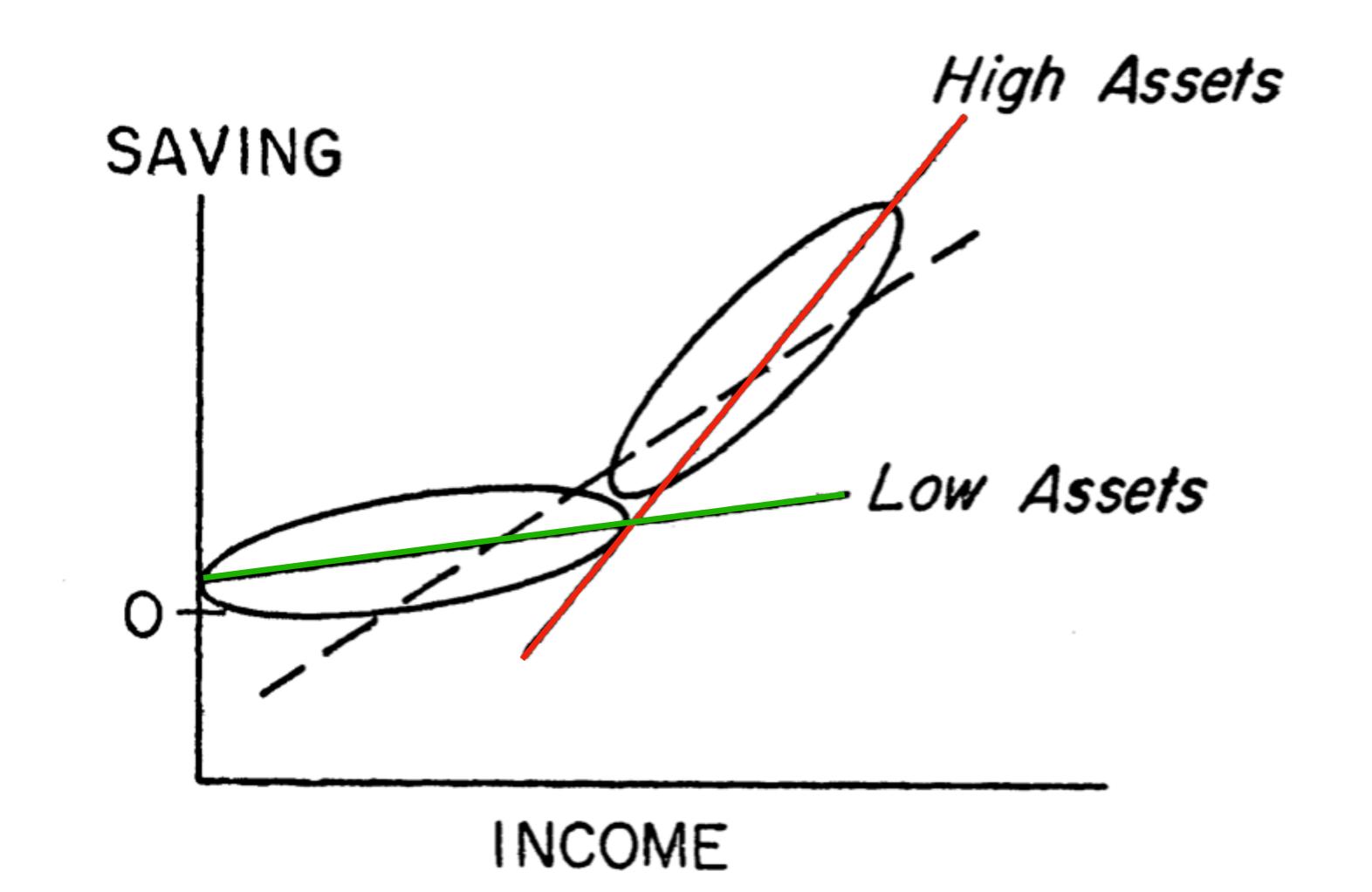


CHART II. Annual Earnings.

## Key question

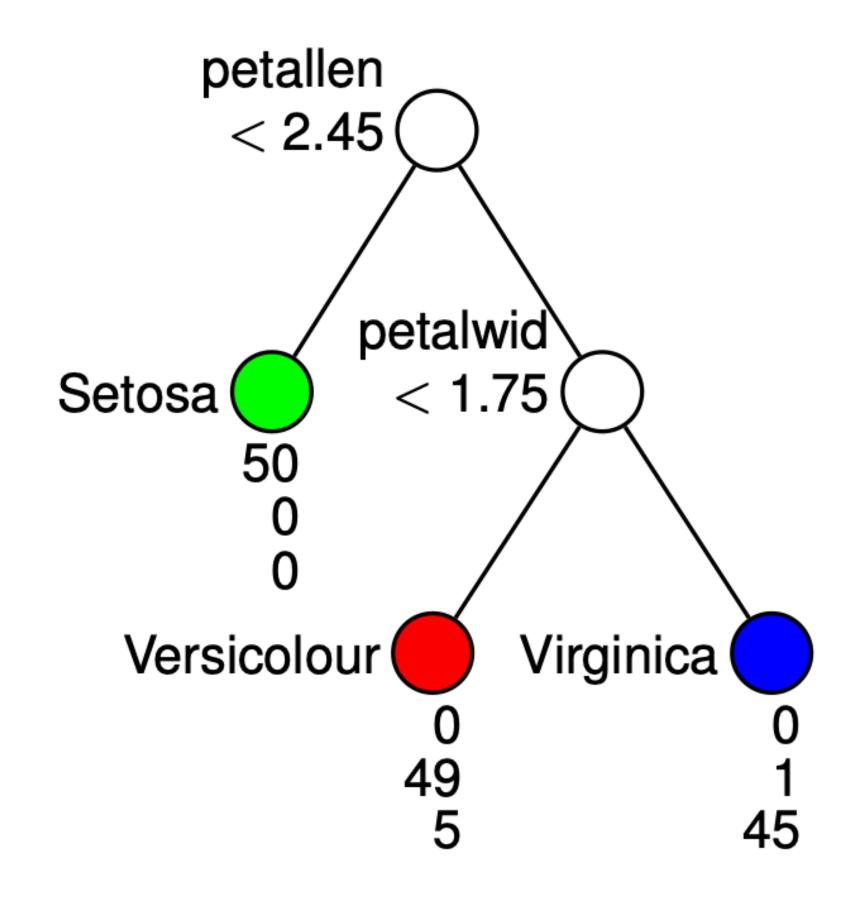
- How do we know if a subgroup needs division?
  - If we know, exactly how do we divide?



## Decision Trees

#### Overview

- Basically a nested if-else statement
- A binary tree which recursively partitions and refines the input space
  - Leaf. Associated with some label  $\hat{y}$ 
    - If discrete, classification
    - If continuous, regression
  - Tree. Associated with some splitting rule  $g:\mathcal{X} \to \{0,1\}$



#### Inference

- Given x, recurse down the tree until a leaf is reached
  - Then, output the label of the leaf

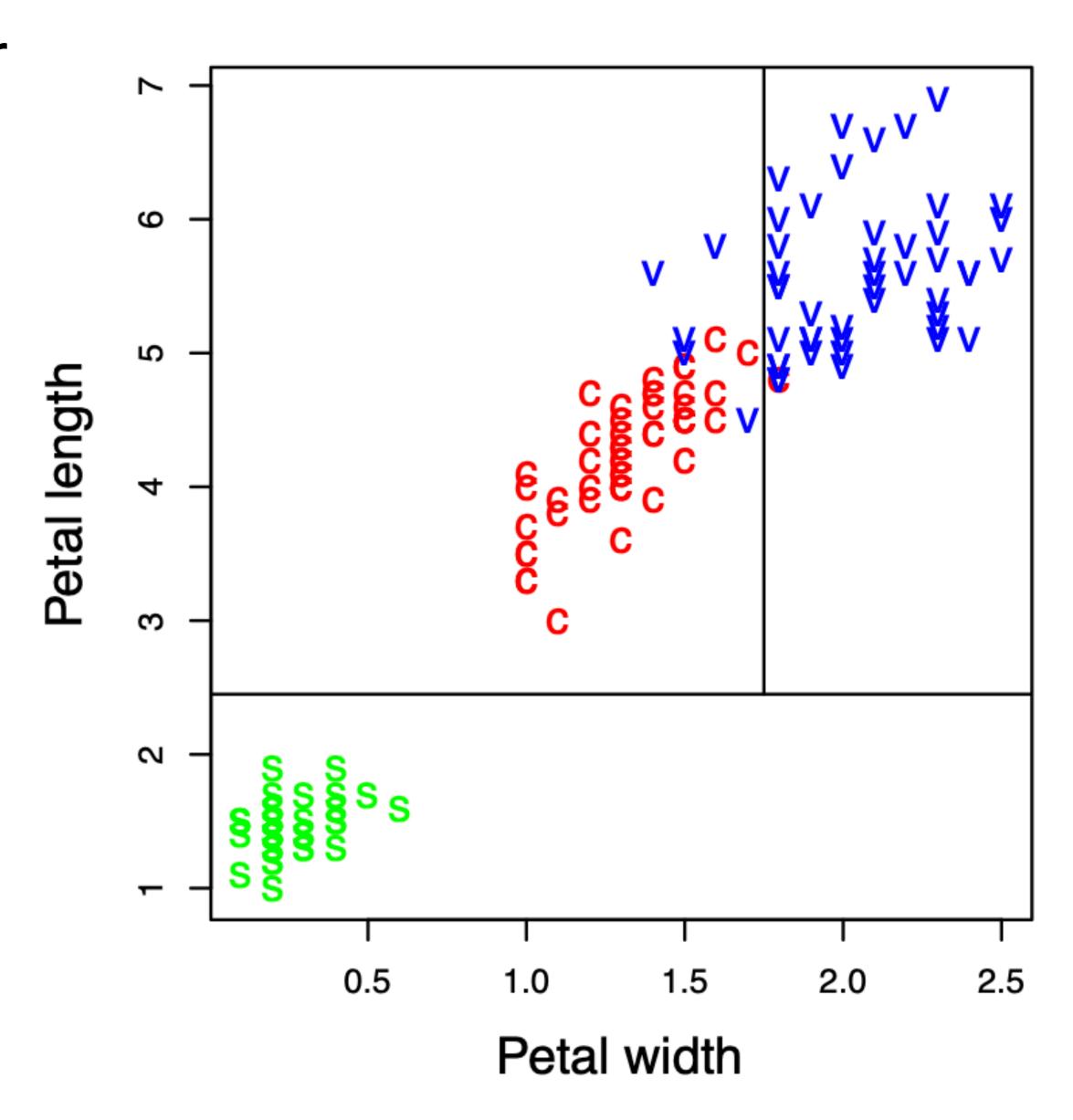
```
while(true):
   if(node == leaf): output label(node)
   else:
      if(condition == true): node = right_child(node)
      else: node = left_child(node)
```

#### Inference

• When  $\mathcal{X} = \mathbb{R}^d$ , it is typical to consider only the axis-aligned splits

$$g(\mathbf{x}) = \mathbf{1}[x_i \ge t]$$

- Computationally efficient
  - Single index lookup
- Human-interpretable decisions



### Training

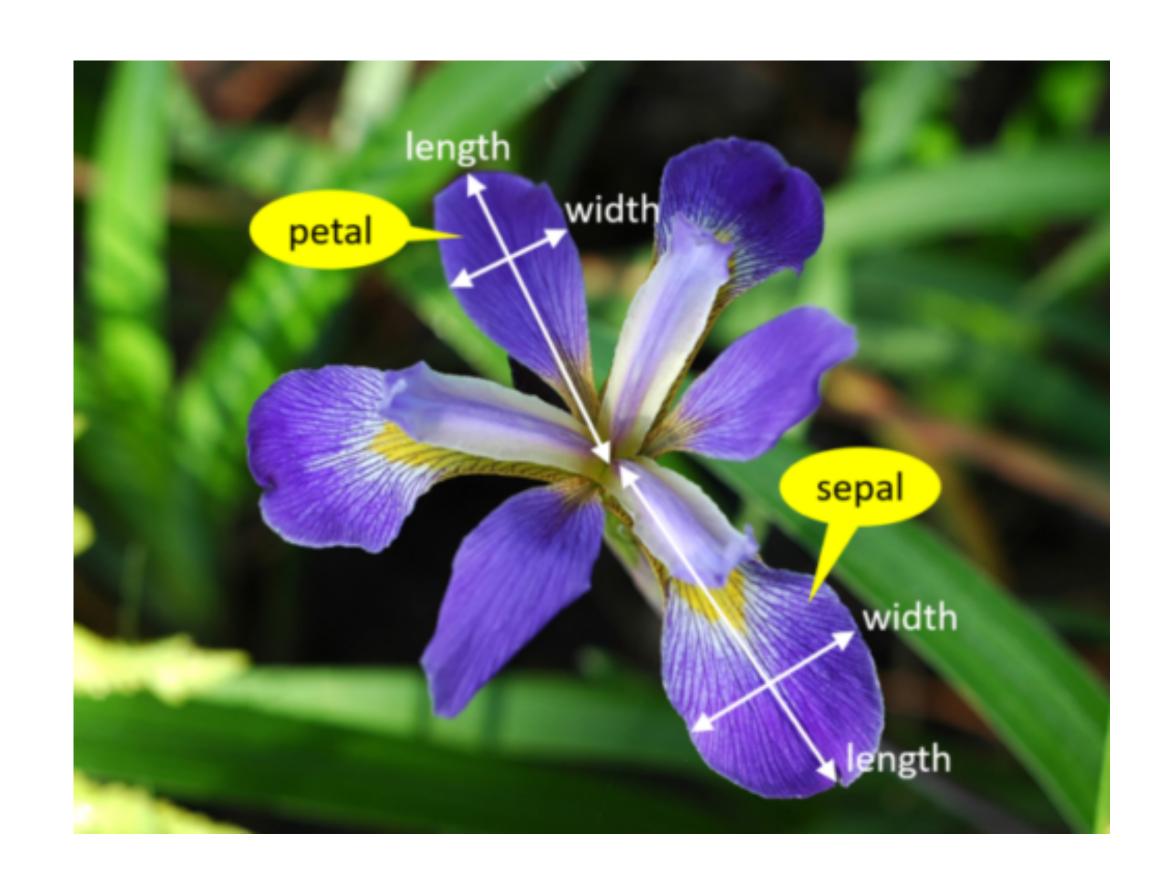
- Constructing a decision tree requires specifying three elements
  - Prediction rule
  - Stopping rule
  - Splitting rule

```
until all leaf node is stopped:
    visit a leaf node

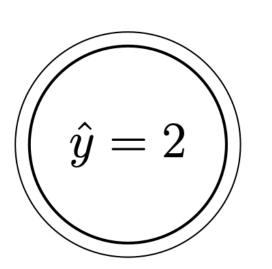
if(stopping_rule(node) = True):
        apply prediction rule to label the node
        stop the node

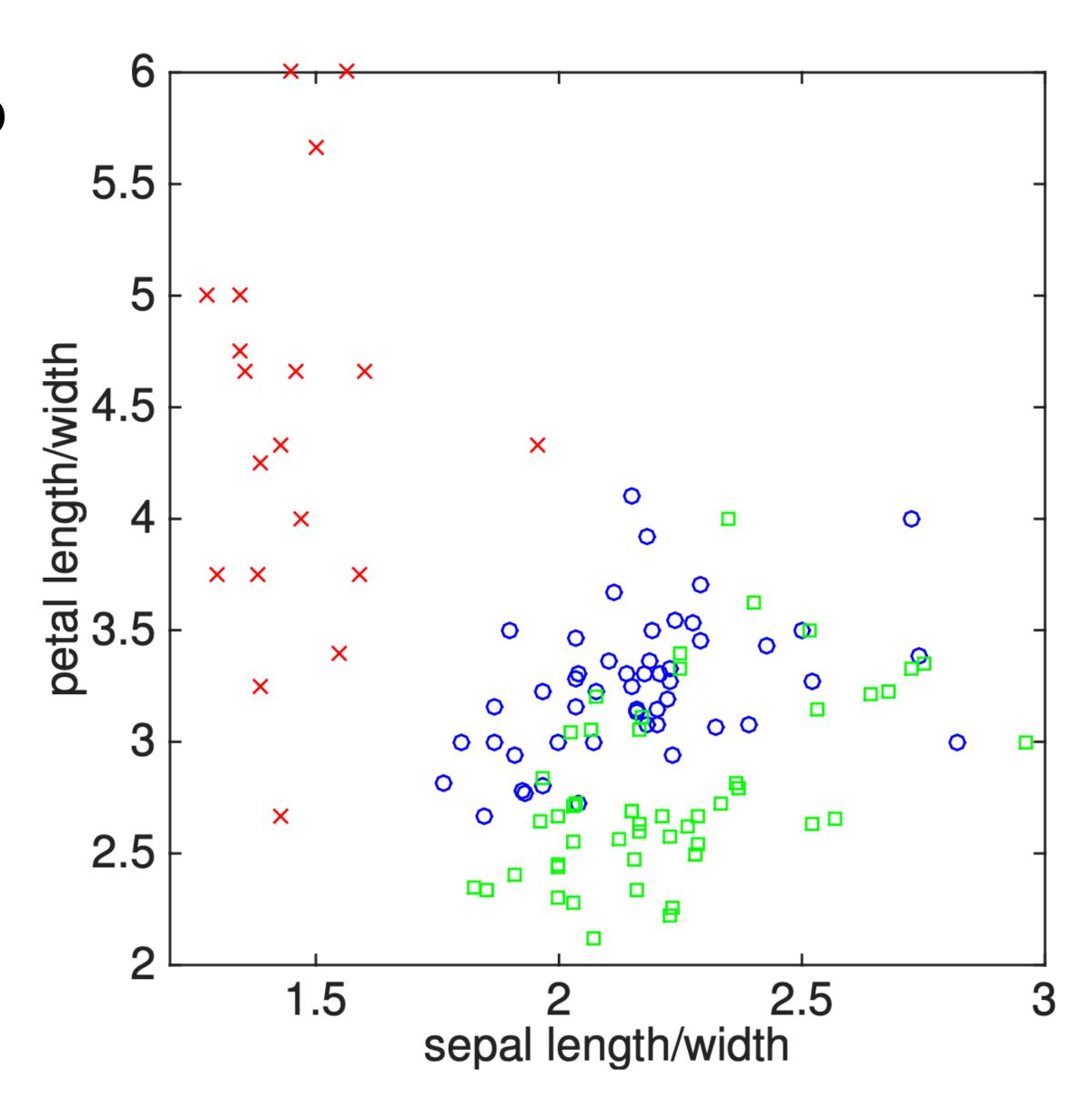
else:
        split the node, using the splitting rule
```

- For example, consider an iris classification task
  - Input features  $\mathcal{X} = \mathbb{R}^2$ 
    - $x_1$ : length-width ratio of sepal
    - $x_2$ : length-width ratio of petal
  - Output labels  $\mathcal{Y} = \{1, 2, 3\}$

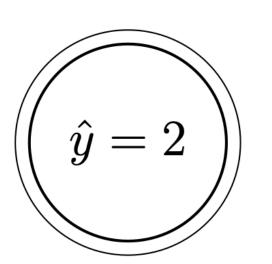


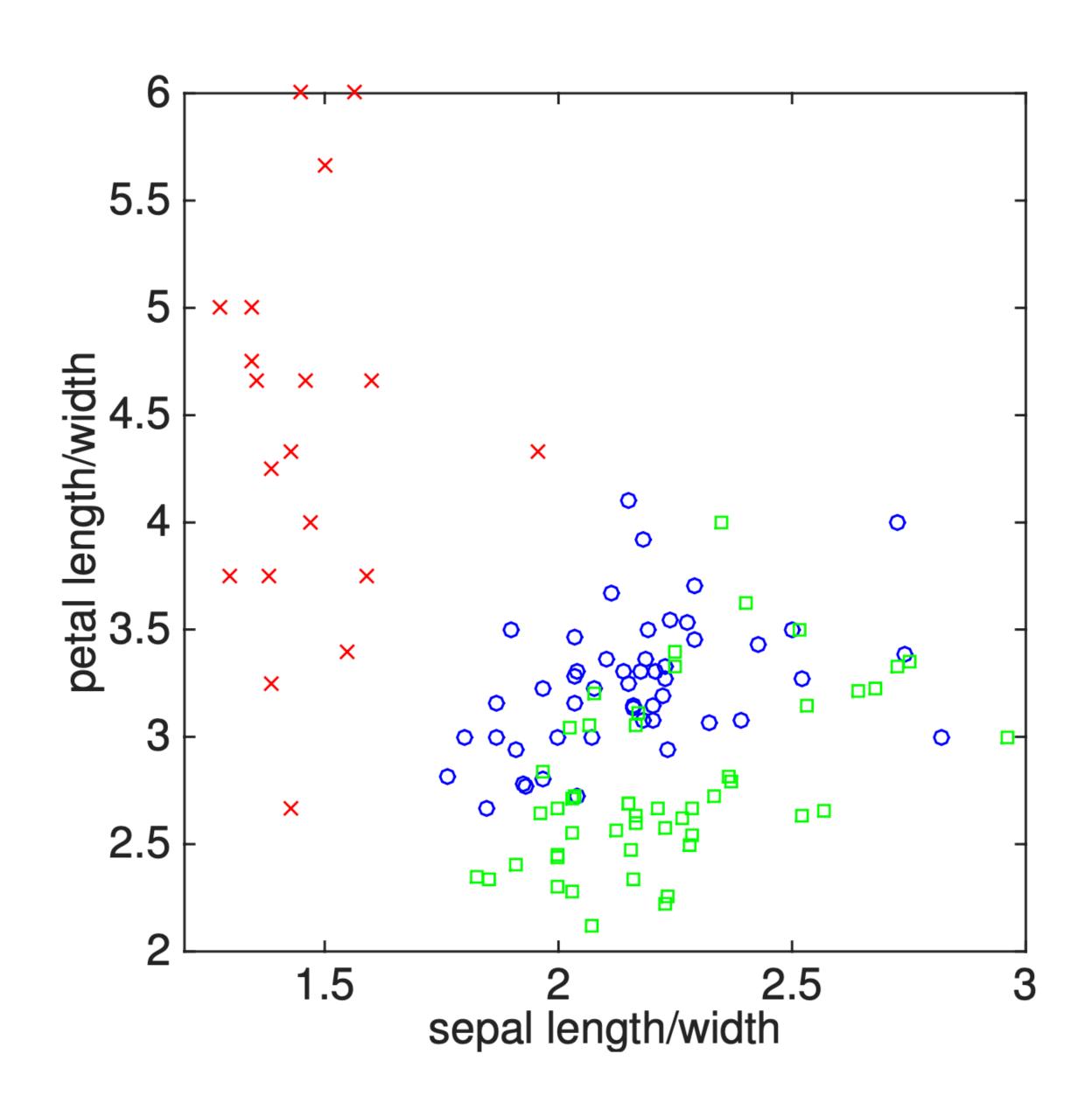
 First, construct a single leaf node, using a prediction rule that applies to the whole set



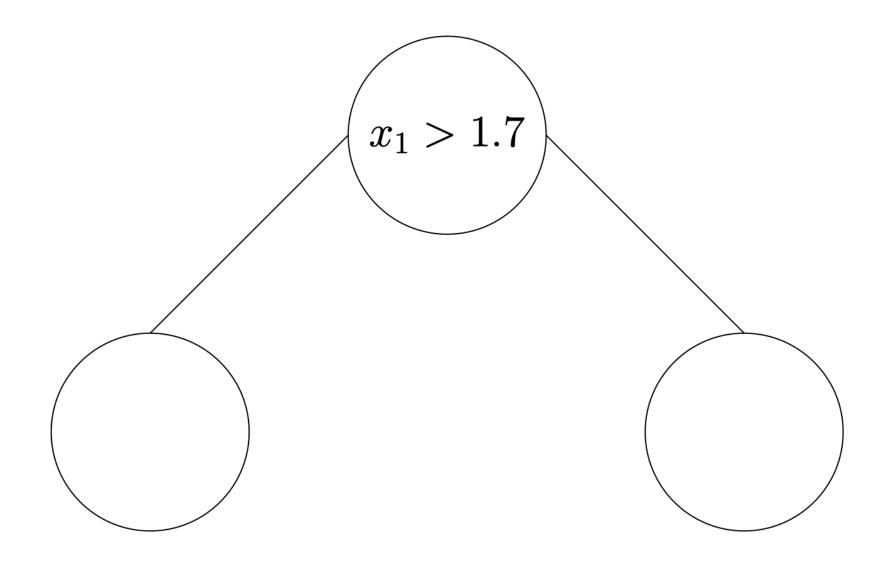


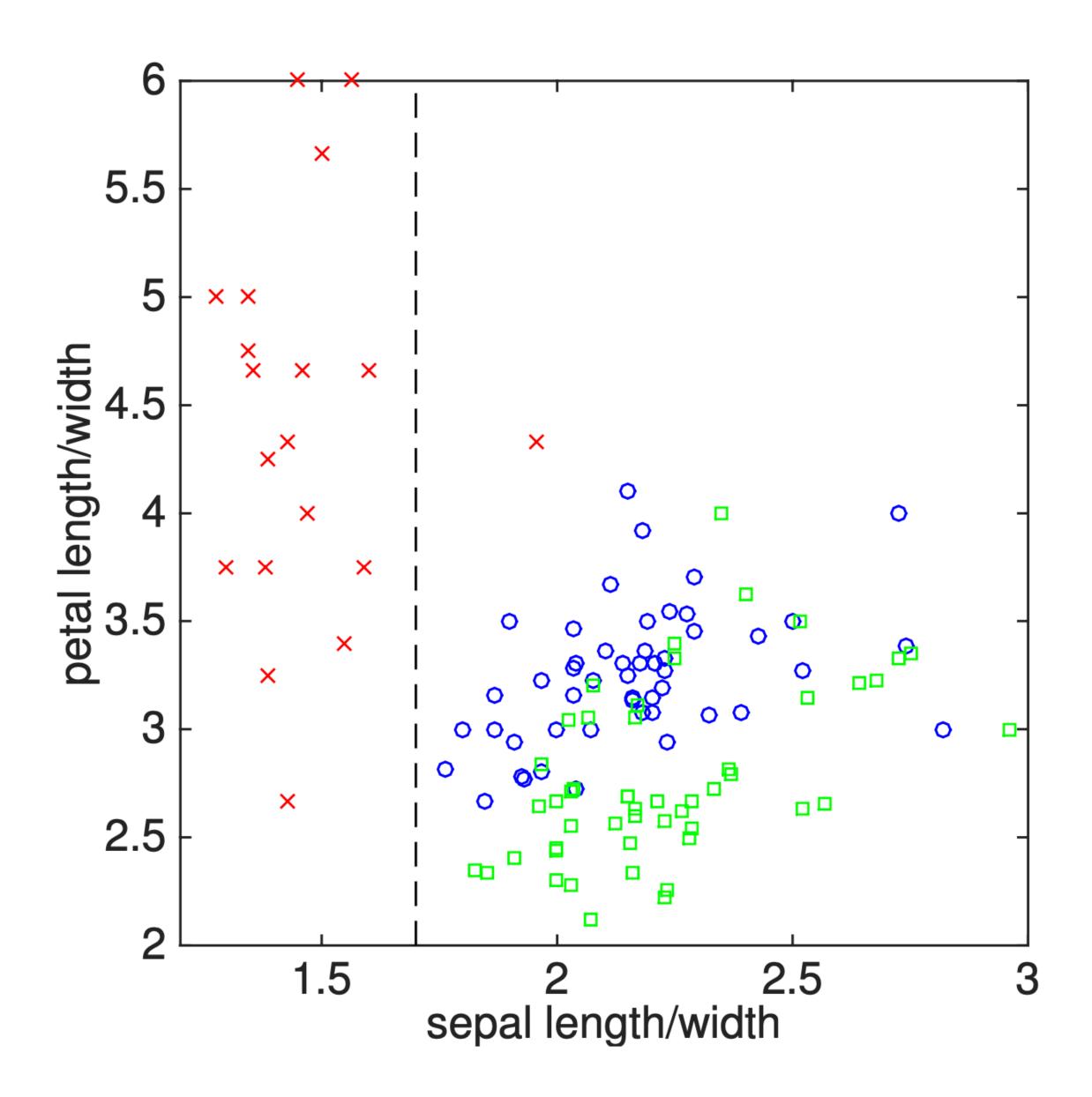
- See if the stopping rule is met
  - Very unhomogeneous; continue



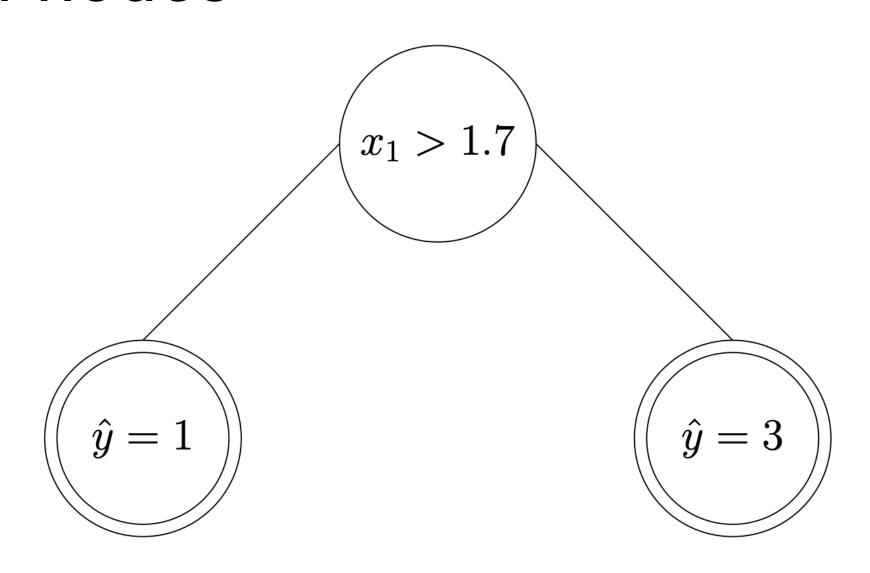


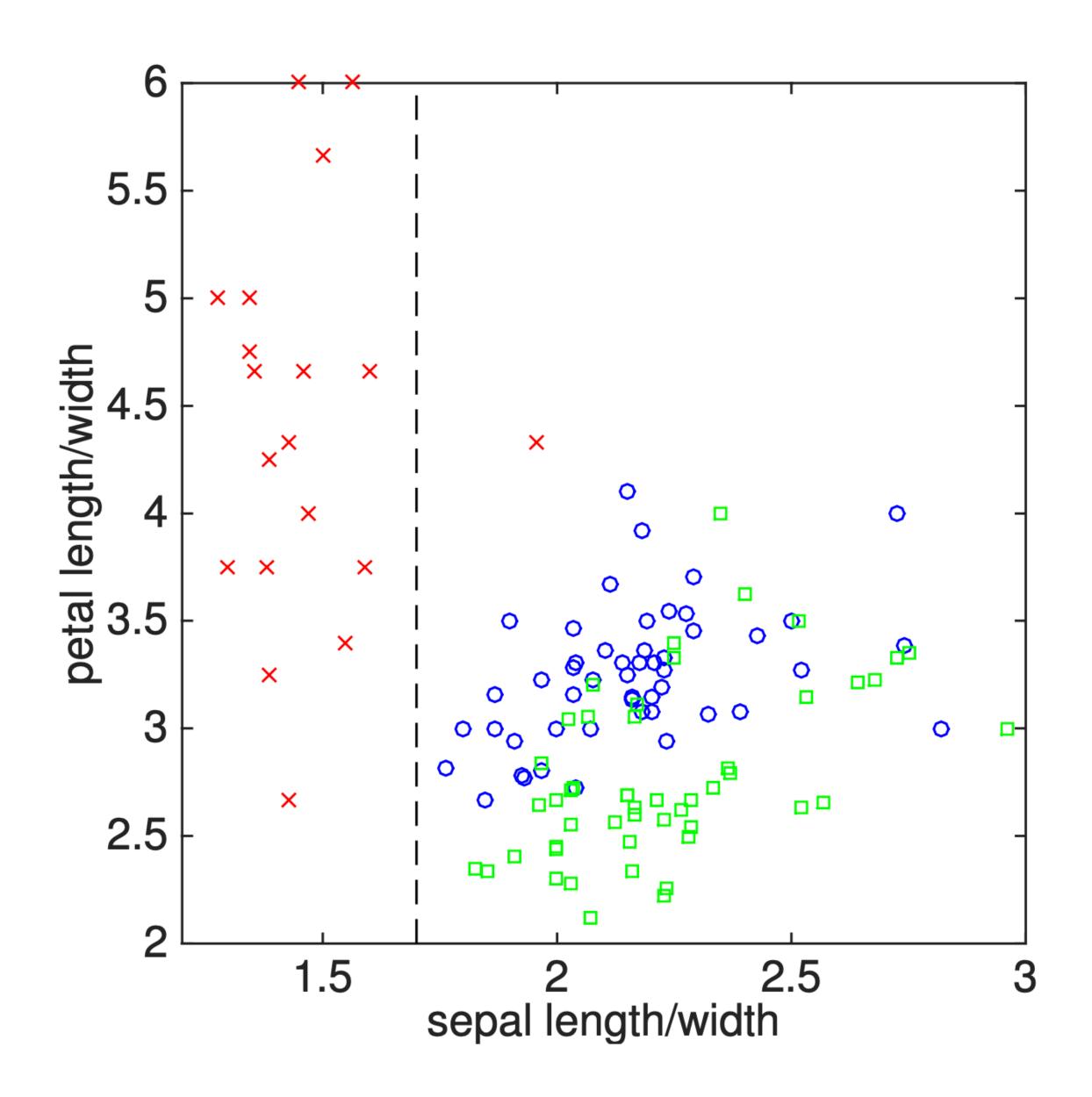
 According to the splitting rule, split the leaf to partition the input space for the node



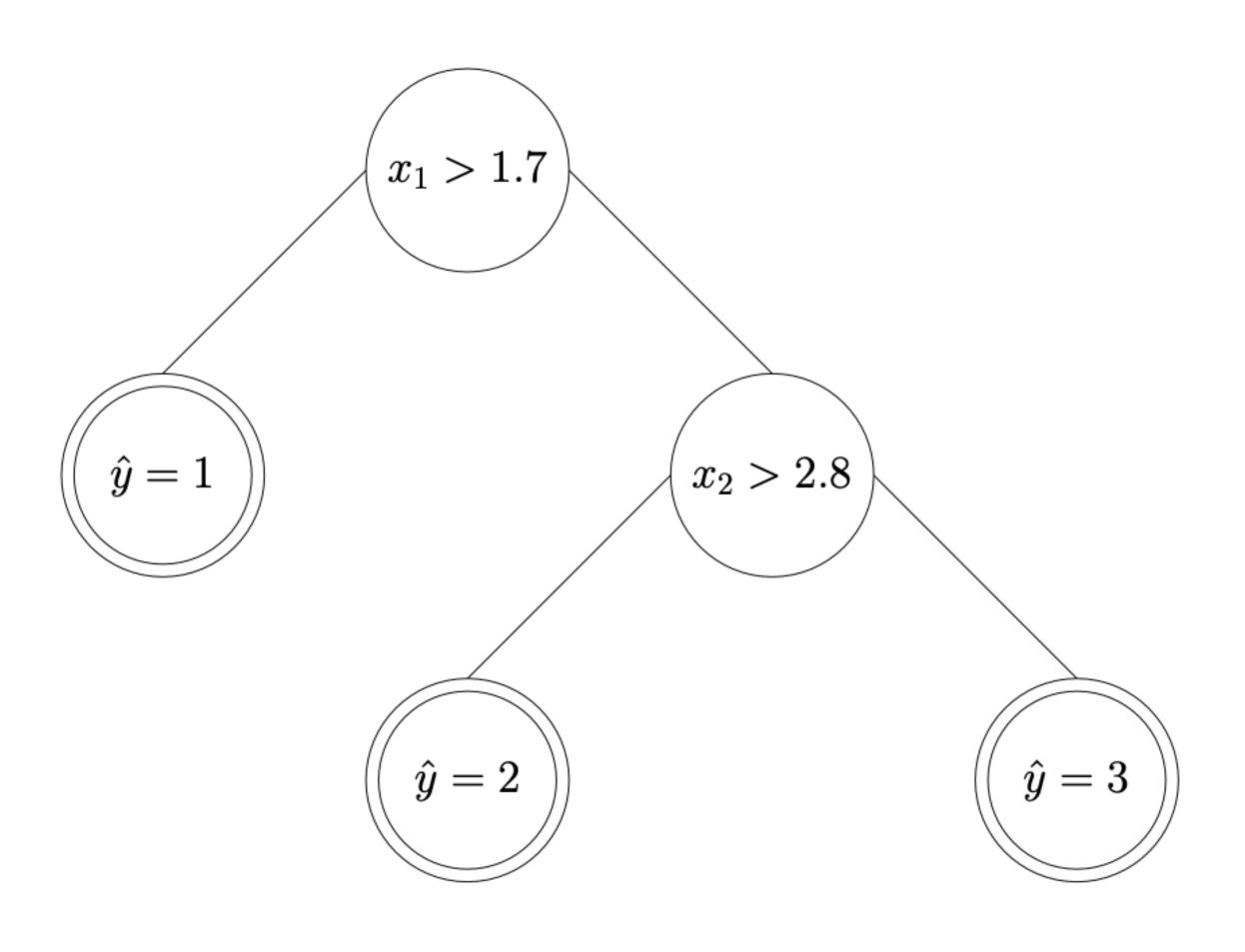


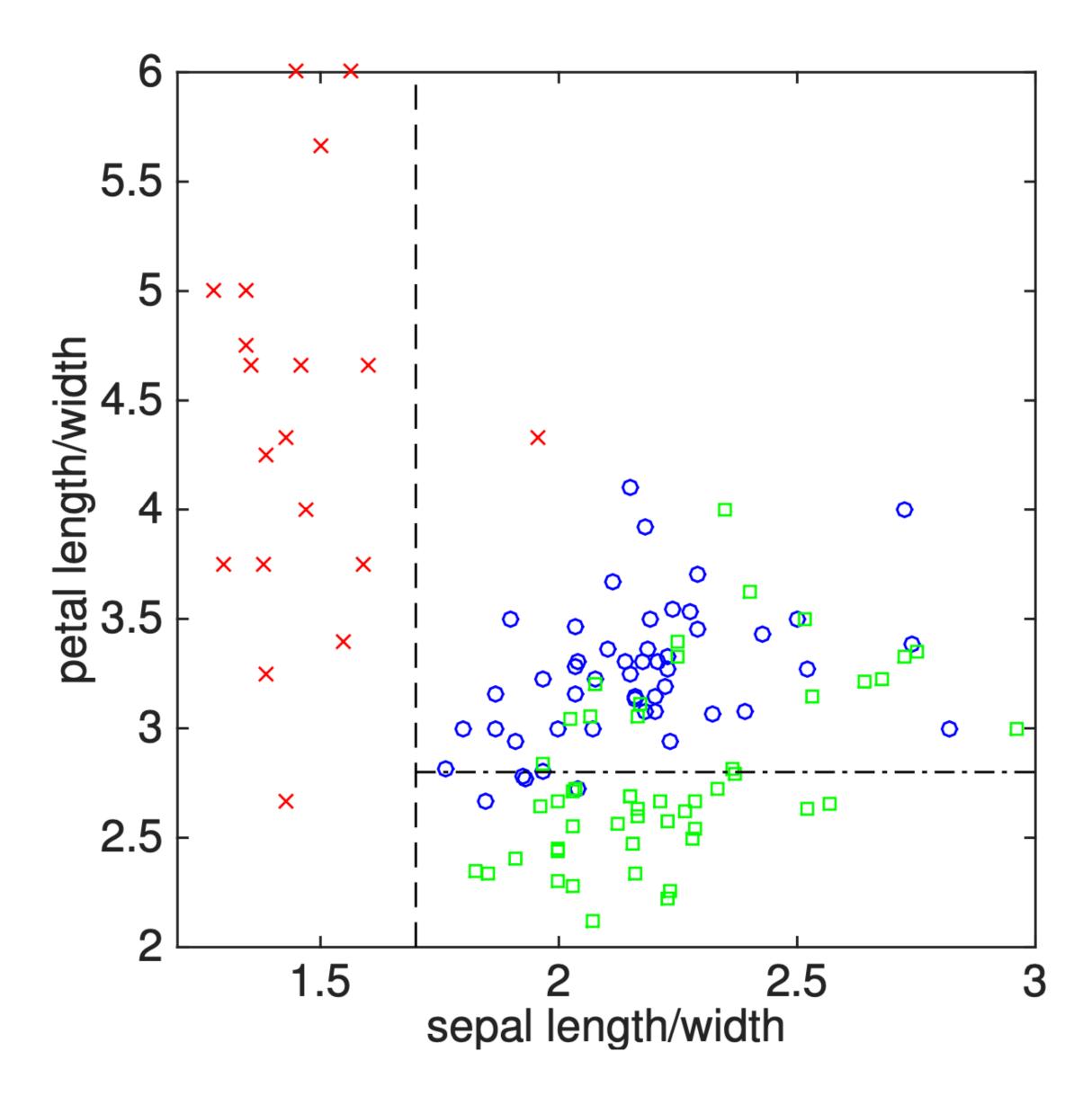
 According to the prediction rule, determine the prediction of new leaf nodes





 Continue until some stopping rule is satisfied for all leaf nodes

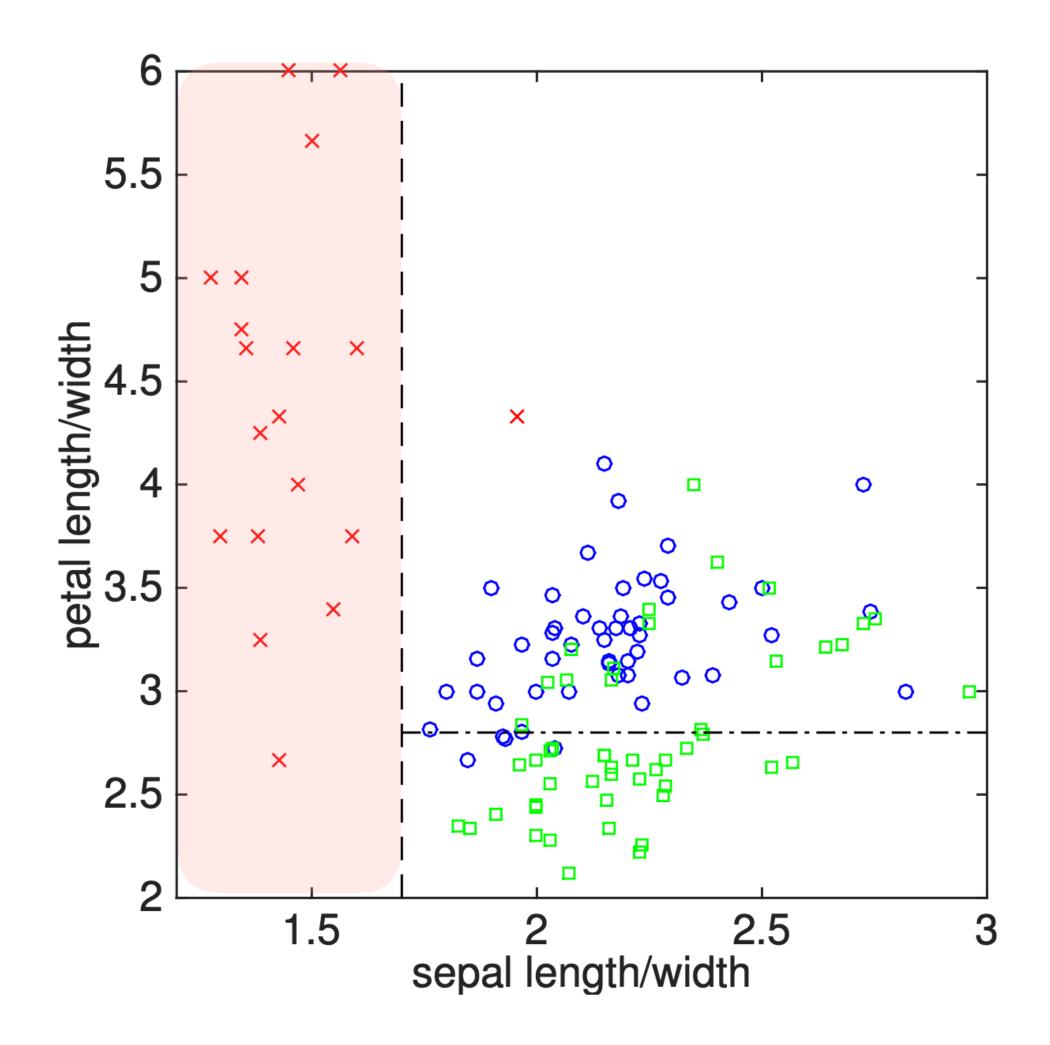




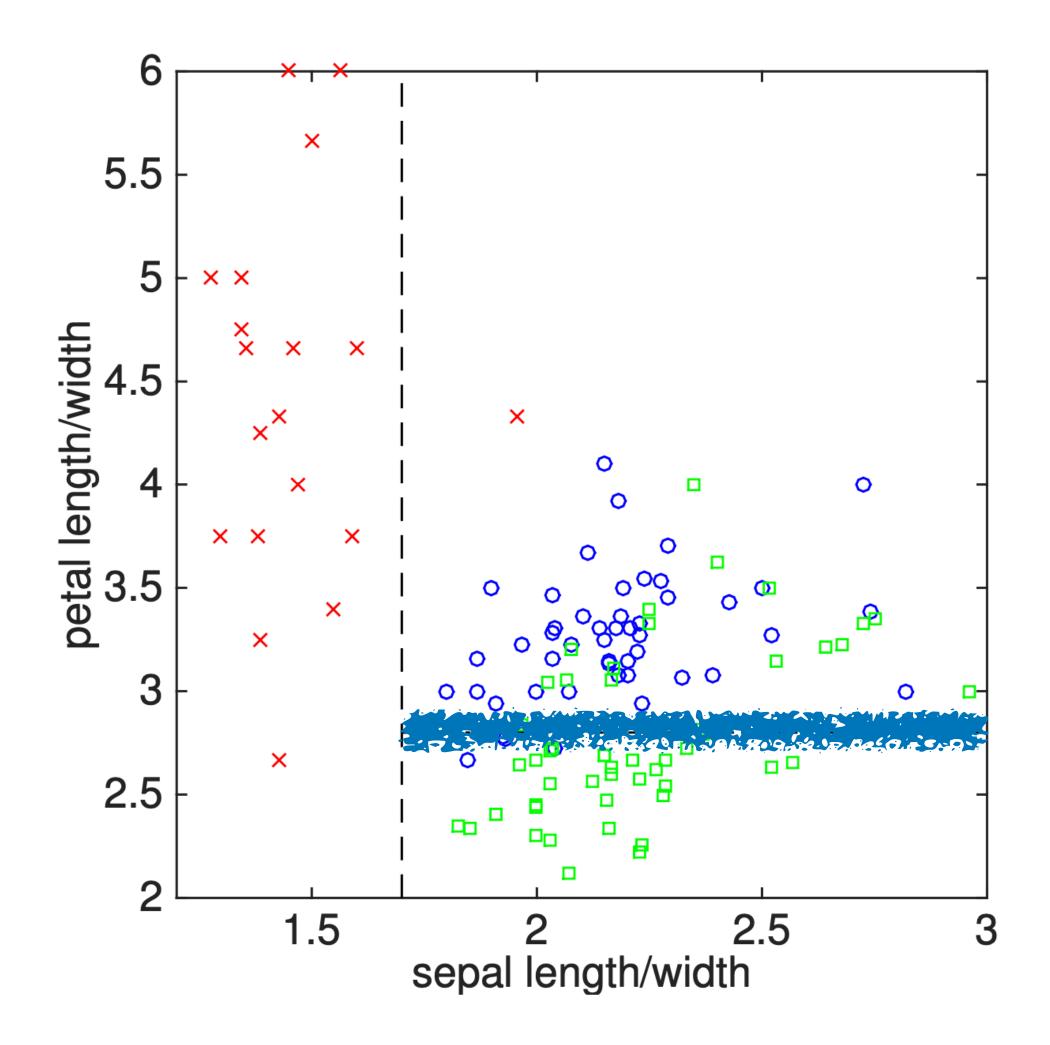
## Elements

#### Training: Prediction Rule

- Generating a label for a partitioned set
- Typically very simple
  - Classification. Majority voting
  - Regression. Average, Median, ...



- Generating how to partition a set
  - Which axis?
  - Which line?



Idea. Minimize some notion of uncertainty (a.k.a. impurities)
 after partitioning the set

• In other words, by dividing some set S into  $S_1, S_2$ , we want to solve:

$$\min_{S_1, S_2: S_1 \cup S_2 = S, S_1 \cap S_2 = \phi} \left( |S_1| \cdot u(S_1) + |S_2| \cdot u(S_2) \right)$$

• Here,  $u(\cdot)$  is some measure of uncertainty

#### **Example (Binary Classification)**

- Suppose that we are given a set S, with  $p \mid S \mid$  samples labeled as +1
  - Classification Error

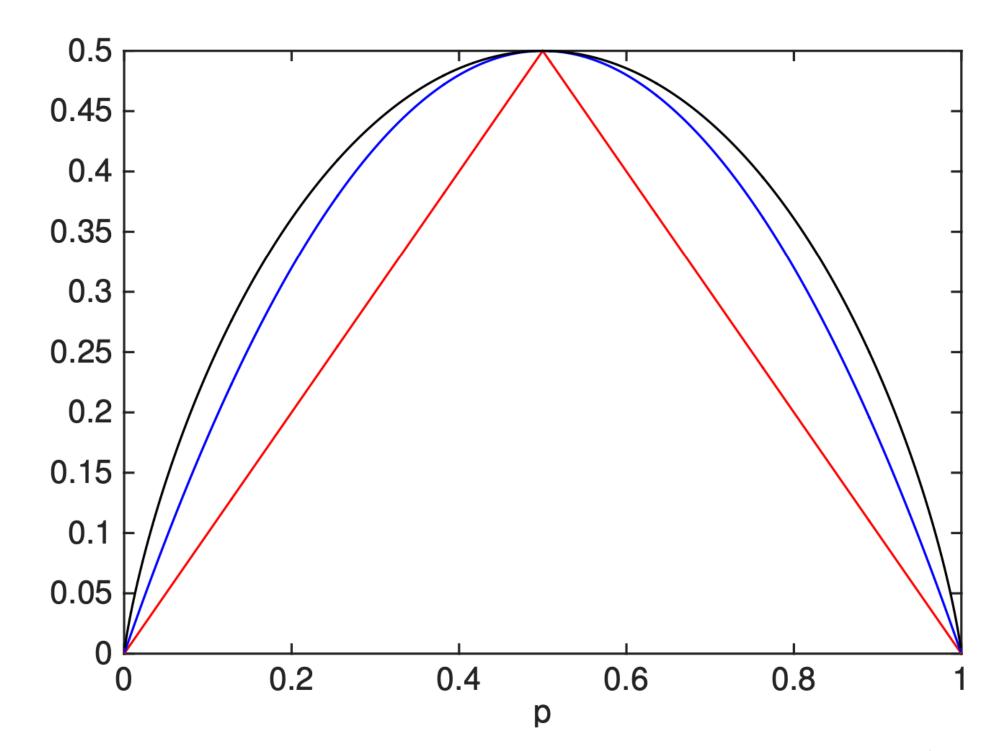
$$u(S) = \min\{p, 1 - p\}$$

Gini Index

$$u(S) = 2p(1-p)$$

Entropy

$$u(S) = p \log \frac{1}{p} + (1 - p) \log \frac{1}{1 - p}$$



(G, E are concave upper bounds on C)

#### **Example (Regression)**

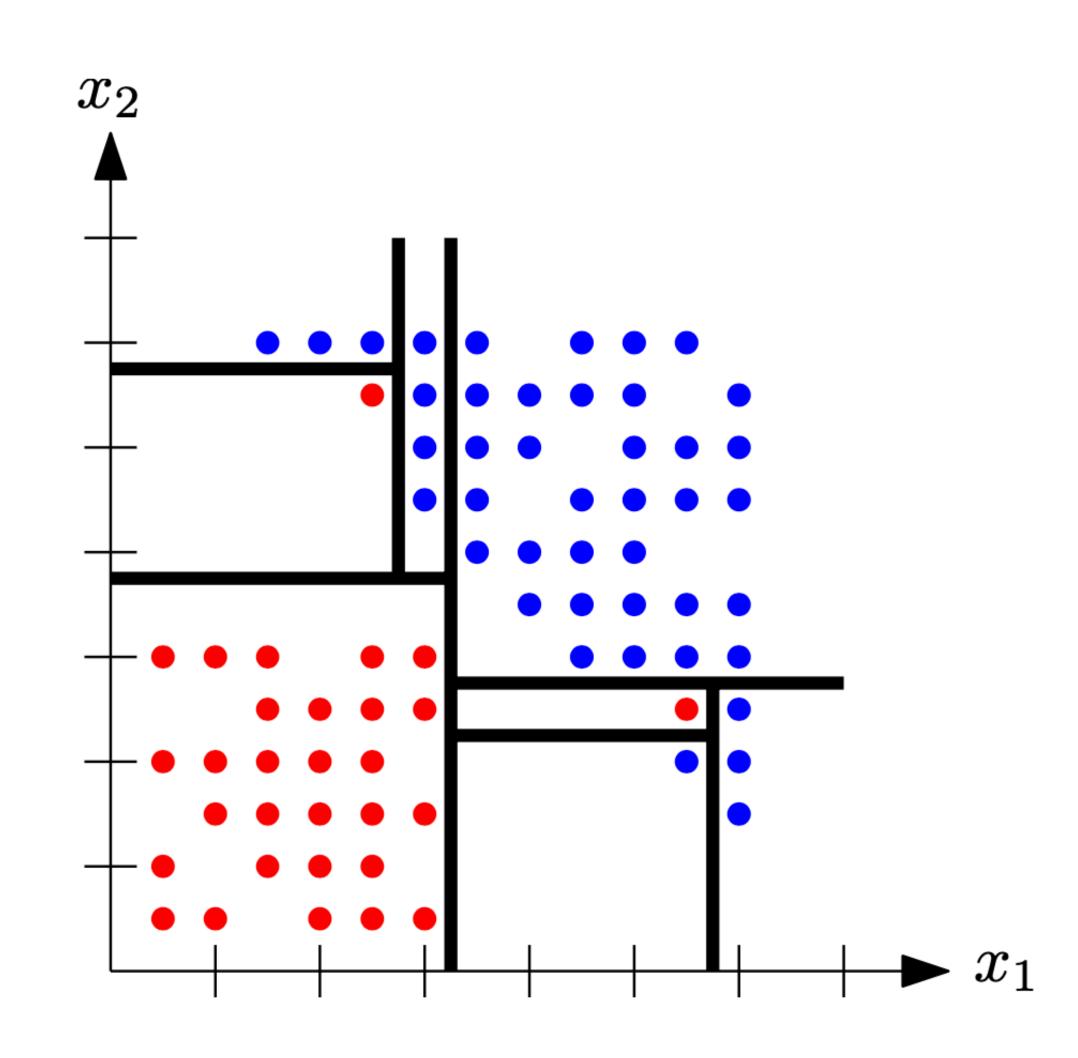
- We can simply use <u>variance</u>
  - the minimum mean squared error
  - i.e., the  $\ell^2$  error of the mean

• Similarly, we can use the minimum mean absolute error, ...

## Training: Stopping Rule

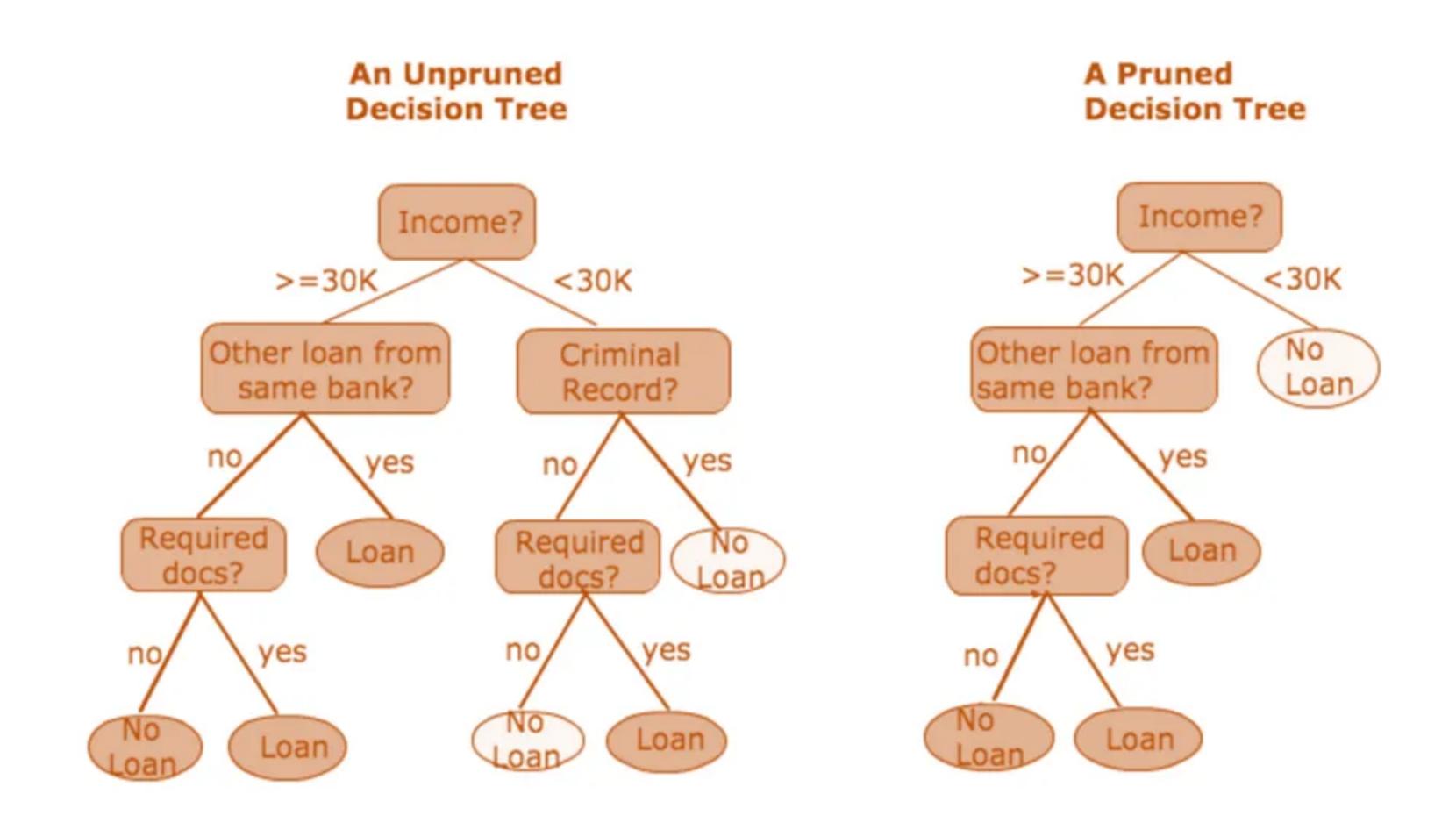
Determining when to stop growing a tree

- Many criteria:
  - If splitting does not reduce the uncertainty
  - Reaches some pre-specified size of the tree
  - Every leaf is "pure"
    - Very prone to overfitting



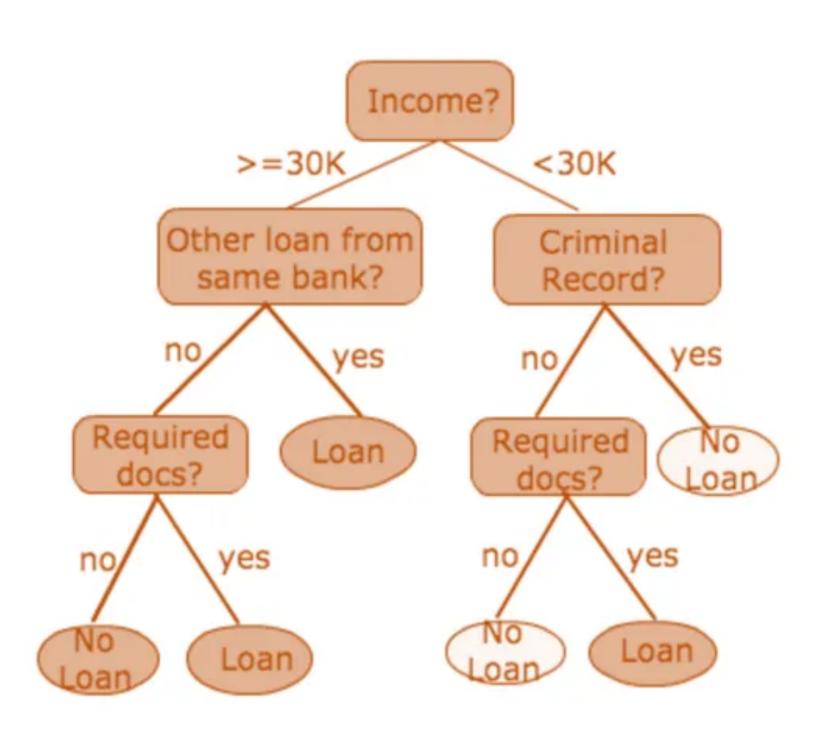
#### Pruning

- It is typical to prune the tree after growing
  - i.e., remove unnecessary split after training



### Pruning

- Algorithm.
  - Pick a bottom-level split
  - Remove it
    - If the validation error is improved, leave it pruned
    - Else, restore the subtree
  - Repeat



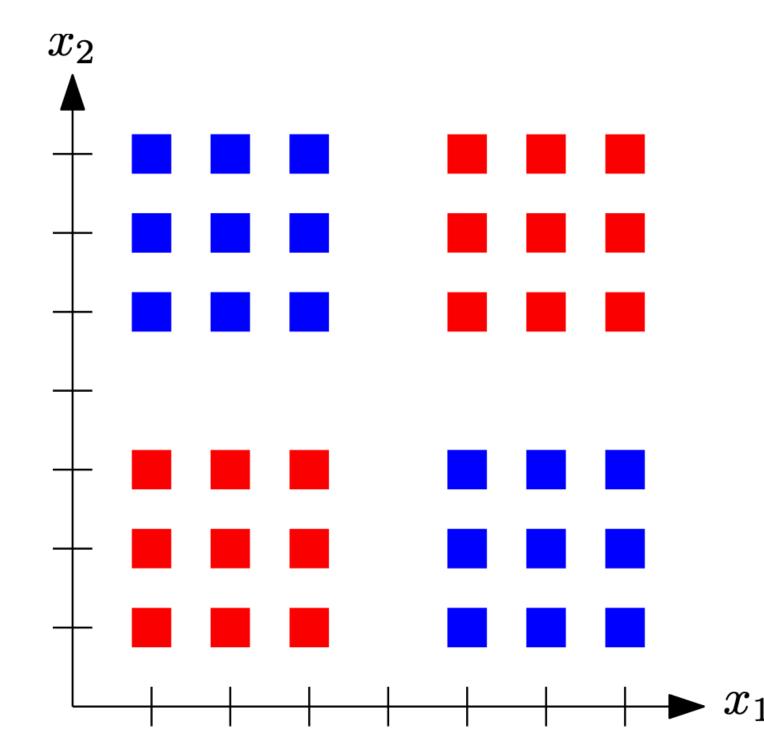
## Pruning

Note that the iterative algorithm is a "greedy" way to minimize the total uncertainty

$$u(\mathcal{T}) := \frac{1}{n} \sum_{\text{leaf } S \in \mathcal{T}} |S| \cdot u(S)$$

- Prone to falling in local minima:
  - Fails on XOR (indifferent to splits)

- Solution.
  - Do "random" splits occasionally
  - Then, prune the unnecessary splits



### Properties

- Advantages.
  - Easy to interpret
  - Fast to execute

- Limitations.
  - Difficult to scale up
    - Easy to overfit, if the tree is big

### Properties

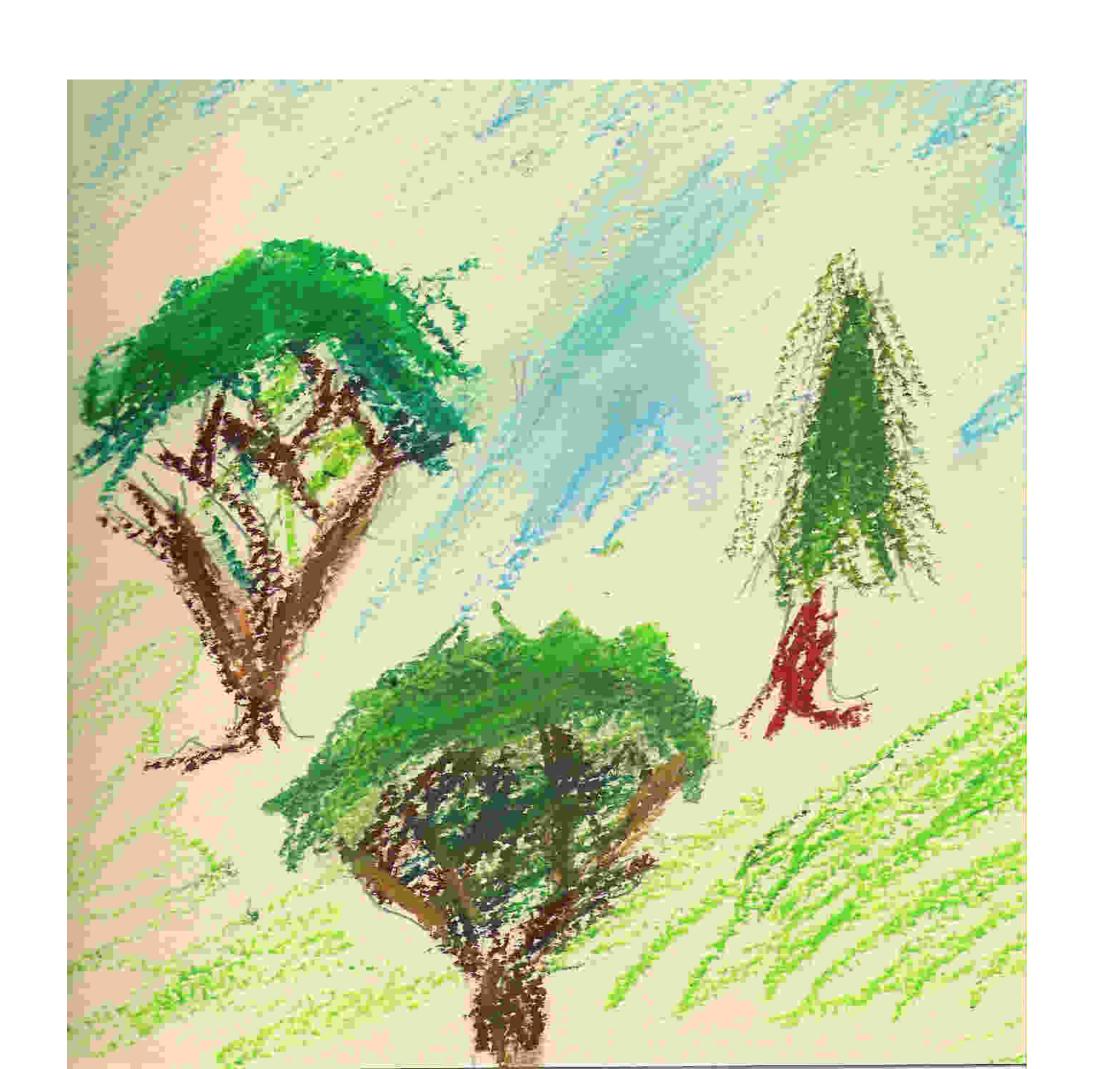
- Nonparametric
- Based on local regularity
  - Simple locally, complicated globally

In these senses, similar with nearest neighbors

## Forests

#### **Forests**

Scaling up decision trees can be done by growing multiple trees

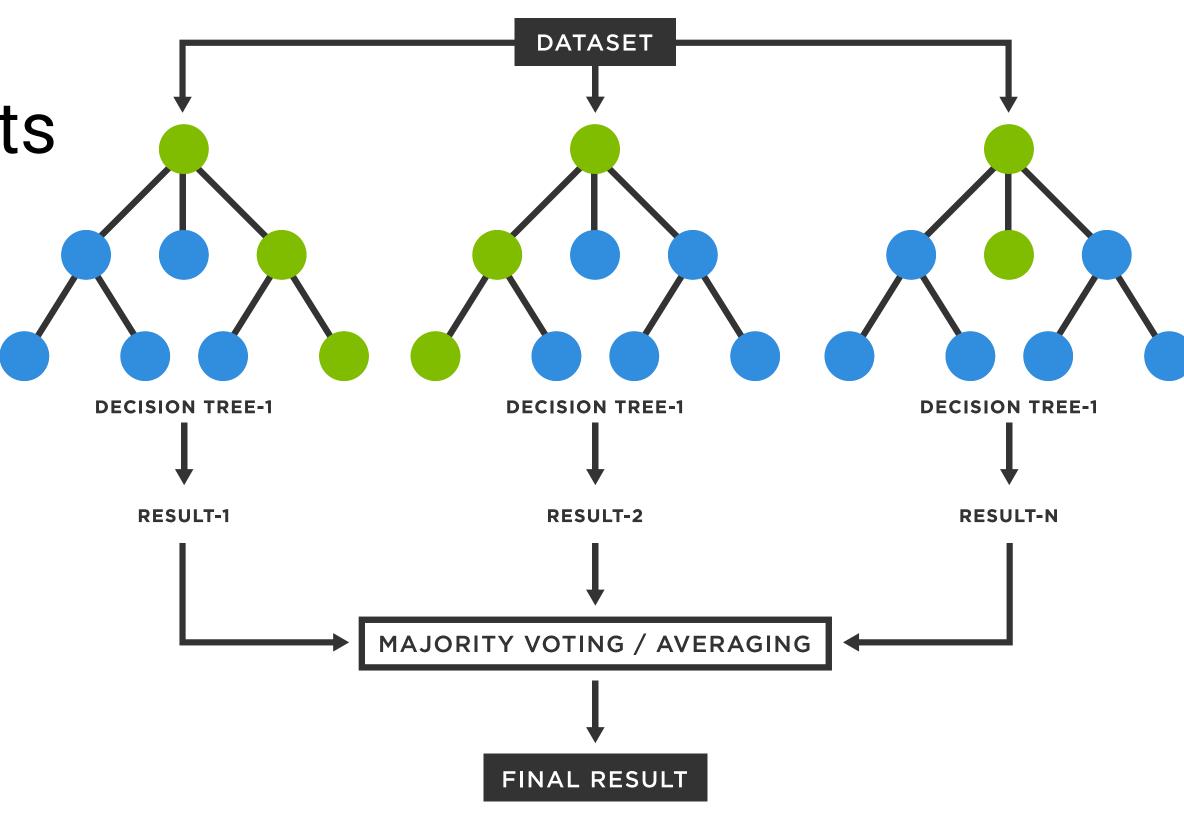


### Bagging

Stands for "Bootstrapped Aggregating"

• Idea. Split the data to multiple subsets

- Generate a tree for each subset
- Predictions of the trees are aggregate via
  - Majority voting
  - Averaging



#### Random Forest

- Problem. Bagging leads to highly correlated trees
  - That is, resulting trees look similar to each other

- Idea. Decorrelate the trees by using only a subset of features
  - To grow each node, randomly select a subset of features and choose the best one among this subset

```
RANDOMFOREST(\mathcal{D}; B, m, n)

1 for b = 1,..., B

2 Draw a bootstrap sample \mathcal{D}_b of size n from \mathcal{D}

3 Grow a tree T_b on data \mathcal{D}_b by recursively:

4 Select m variables at random from the d variables

5 Pick the best variable and split point among the m variables

6 Split the node

7 return tree T_b
```

#### Boosting

- Idea. Decorrelate by sequentially generating the trees
  - Assign higher weights to samples that other trees got wrong



## </le>