#### Support Vector Machines EECE454 Intro. to Machine Learning Systems



- Last class. Simple classifiers
  - Nearest neighbors
  - Naïve Bayes
  - Perceptrons
- Today. More linear models
  - Logistic Regression
  - Support Vector Machines

#### Today

#### Recap: Perceptrons

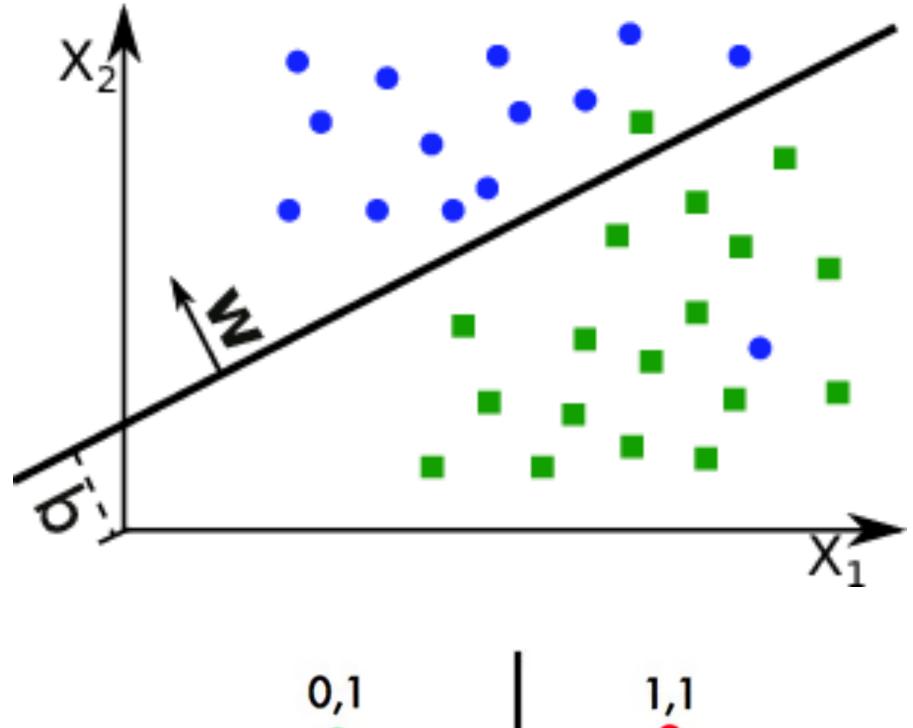
• **Classifier.** Linear model + indicator function

$$f_{\theta}(\mathbf{x}) = \mathbf{1} \left[ \theta^{\mathsf{T}} \tilde{\mathbf{x}} > 0 \right]$$

- **Problem.** Gradient is discrete
  - <u>Solution</u>. Use a surrogate loss function

 $\ell(\mathbf{y}, f_{\theta}(\mathbf{x})) = (f_{\theta}(\mathbf{x}) - \mathbf{y}) \cdot \theta^{\mathsf{T}} \mathbf{x}$ 

- Gave birth to some specialized algorithm
- Limitation. Cannot express complicated function (e.g., XOR)





Logistic Regression

#### Logistic regression

- Solve the classification, just like linear regression

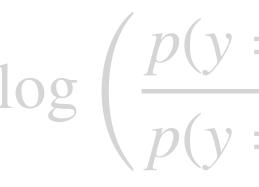
• Question. Why don't we simply predict  $p(y = 1 | \mathbf{x})$ ?

• Idea. Do not predict the label directly, but predict the log likelihood ratio (note the direction)

 $\log\left(\frac{p(y=1 | \mathbf{x})}{p(y=0 | \mathbf{x})}\right) \approx \theta^{\mathsf{T}} \tilde{\mathbf{x}}$ 

### Logistic regression

- Solve the classification, just like linear regression
  - Idea. Do not predict the label directly, but predict the log likelihood ratio (note the direction)



- Question. Why don't we simply predict  $p(y = 1 | \mathbf{x})$ ?
  - Answer. To utilize the full range;  $p(y = 1 | \mathbf{x}) \in [0,1]$ , but  $\theta^{\dagger} \tilde{\mathbf{x}} \in (-\infty, +\infty)$

 $\log\left(\frac{p(y=1 | \mathbf{x})}{p(y=0 | \mathbf{x})}\right) \approx \theta^{\mathsf{T}} \tilde{\mathbf{x}}$ 

## Logistic regression $\log\left(\frac{p(y=1 | \mathbf{x})}{p(y=0 | \mathbf{x})}\right) \approx \theta^{\mathsf{T}} \tilde{\mathbf{x}}$

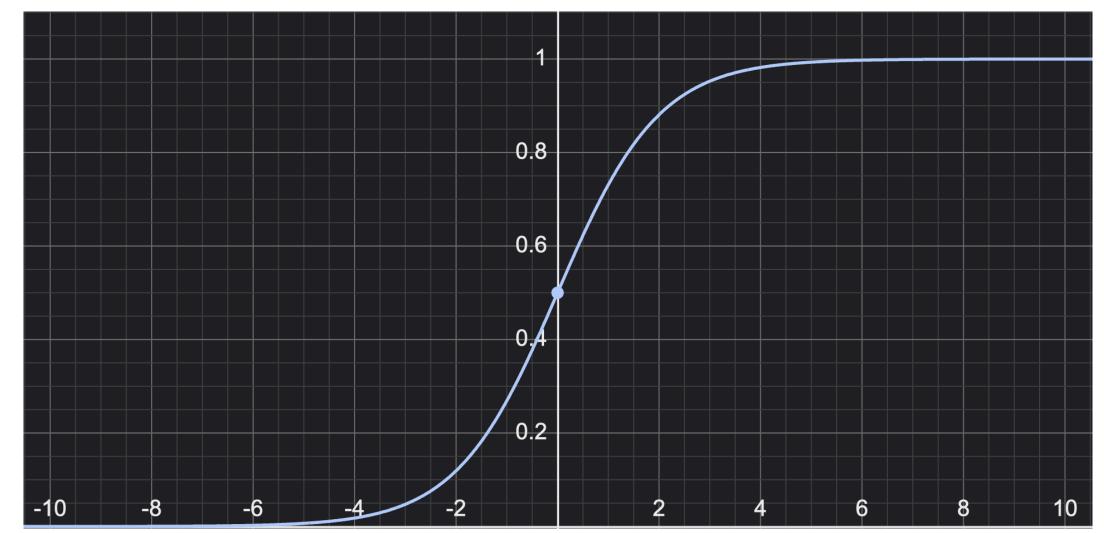
- In other words, we are modeling the posterior distribution as

 $p(y = 1 | \mathbf{x}) = \frac{1}{1 + \exp(-\theta^{\top} \tilde{\mathbf{x}})}$ 

## Logistic regression



#### • The function $\sigma(t) = 1/1 + \exp(-t)$ is called the logistic function



- $\log\left(\frac{p(y=1 | \mathbf{x})}{p(y=0 | \mathbf{x})}\right) \approx \theta^{\mathsf{T}} \tilde{\mathbf{x}}$
- $p(y = 1 | \mathbf{x}) = \frac{1}{1 + \exp(-\theta^{\mathsf{T}} \tilde{\mathbf{x}})}$

#### Training

• Training. Given the data  $D = \{(\mathbf{x}_i, y_i)\}_{i=1}^n$ , we maximize the log likelihood

- Equivalently, minimize the NLL loss

 $\max_{\theta} \frac{1}{n} \sum_{i=1}^{n} \log p(y_i \mid \mathbf{x}_i)$ 

 $\min_{\theta} \frac{1}{n} \sum_{i=1}^{n} \log\left(\frac{1}{p(y_i \mid \mathbf{x}_i)}\right)$ 

#### Training

- Equivalently again, solve an ERM with:
  - Hypothesis space  $\{f_{\theta}(\mathbf{x}) = \boldsymbol{\sigma}(\boldsymbol{\theta}^{\mathsf{T}} \tilde{\mathbf{x}})\}$
  - Loss is the cross-entropy  $\ell(y,t) = CE(\mathbf{1}_y, [t,1-t]) = \log(t)^{-y} + \log(1-t)^{y-1}$

#### Training

- Equivalently again, solve an ERM with:
  - Hypothesis space  $\{f_{\theta}(\mathbf{x}) = \sigma(\theta^{\mathsf{T}} \tilde{\mathbf{x}})\}$
- More tediously, minimize

$$\frac{1}{n} \sum_{i=1}^{n} (-y_i) \log(\sigma(\theta^{\mathsf{T}} \tilde{\mathbf{x}}_i))$$

Convex, but no general closed-form solution  $\rightarrow$  use gradient descent  $\bullet$ 

$$\theta^{(\text{new})} = \theta + \eta \cdot$$

#### • Loss is the cross-entropy $\ell(y,t) = CE(1_v, [t,1-t]) = \log(t)^{-y} + \log(1-t)^{y-1}$

#### $_{i})) + (y_{i} - 1)\log(1 - \sigma(\theta^{\dagger}\tilde{\mathbf{x}}_{i})))$

 $\frac{1}{n} \sum_{i=1}^{n} (y_i - \sigma(\theta^{\mathsf{T}} \tilde{\mathbf{x}}_i)) \tilde{\mathbf{x}}_i$ 

#### Remarks

- **Computation.** Relatively easy
  - <u>Training</u>. Requires solving GD, but is convex
  - Testing. Dot product, and apply some threshold

#### Remarks

- **Computation.** Relatively easy
  - <u>Training</u>. Requires solving GD, but is convex
  - Testing. Dot product, and apply some threshold

- Limitations. Again, limited expressive power
  - But will give you a working classifier anyways

Support Vector Machine

#### Some disclaimers



Peyman Milanfar 🤣 @docmilanfar

Of all the machine learning ideas I've been exposed to over the years, I think SVMs were by far the most boring; followed closely by PAC learning.



...

#### Some disclaimers



**Doc Xardoc** @andrewb10687674 · 1h ... I will always have a soft spot in my heart for SVM's because one of the first data science problems I worked on I struggled with for months and then ran it through an SVM and solved it within a half hour.

1 222 <u>,</u>Τ,

#### Some disclaimers

#### $\exists \mathbf{r} \forall \mathbf{v} > cs > arXiv:2308.16898$

#### **Computer Science > Machine Learning**

[Submitted on 31 Aug 2023 (v1), last revised 22 Feb 2024 (this version, v3)]

#### **Transformers as Support Vector Machines**

#### Davoud Ataee Tarzanagh, Yingcong Li, Christos Thrampoulidis, Samet Oymak

Since its inception in "Attention Is All You Need", transformer architecture has led to revolutionary advancements in NLP. The attention layer within the transformer admits a sequence of input tokens X and makes them interact through pairwise similarities computed as softmax(XQK<sup>T</sup>X<sup>T</sup>), where (K, Q) are the trainable keyquery parameters. In this work, we establish a formal equivalence between the optimization geometry of self-attention and a hard-margin SVM problem that separates optimal input tokens from non-optimal tokens using linear constraints on the outer-products of token pairs. This formalism allows us to characterize the implicit bias of 1-layer transformers optimized with gradient descent: (1) Optimizing the attention layer with vanishing regularization, parameterized by (K, Q), converges in direction to an SVM solution minimizing the nuclear norm of the combined parameter  $W = KQ^T$ . Instead, directly parameterizing by W minimizes a Frobenius norm objective. We characterize this convergence, highlighting that it can occur toward locally-optimal directions. Importantly, we show that overparameterization catalyzes global convergence by ensuring the feasibility of the SVM problem and by guaranteeing a benign optimization landscape devoid of stationary points. (3) While our theory applies primarily to linear prediction heads, we propose a more general SVM equivalence that predicts the implicit bias with nonlinear heads. Our findings are applicable to arbitrary datasets and their validity is verified via experiments. We also introduce several open problems and research directions. We believe these findings inspire the interpretation of transformers as a hierarchy of SVMs that separates and selects optimal tokens.

Comments:The proof of global convergence for gradient descent in the equal score setting has been fixed, referring to Theorem 2 of [TLZO23], and the experimental results have been extendedSubjects:Machine Learning (cs.LG); Artificial Intelligence (cs.Al); Computation and Language (cs.CL); Optimization and Control (math.OC)Cite as:arXiv:2308.16898 [cs.LG](or arXiv:2308.16898v3 [cs.LG] for this version)https://doi.org/10.48550/arXiv.2308.16898

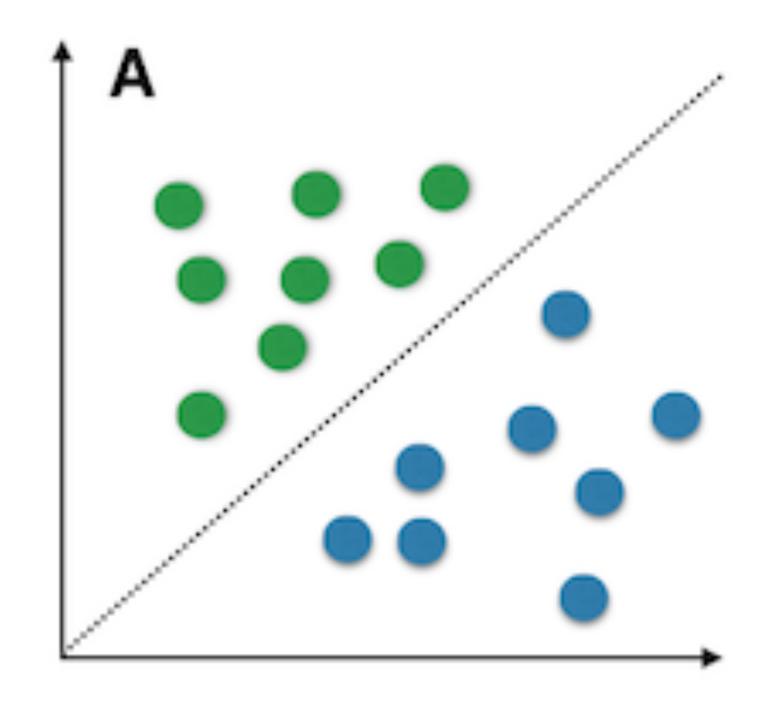
#### Submission history

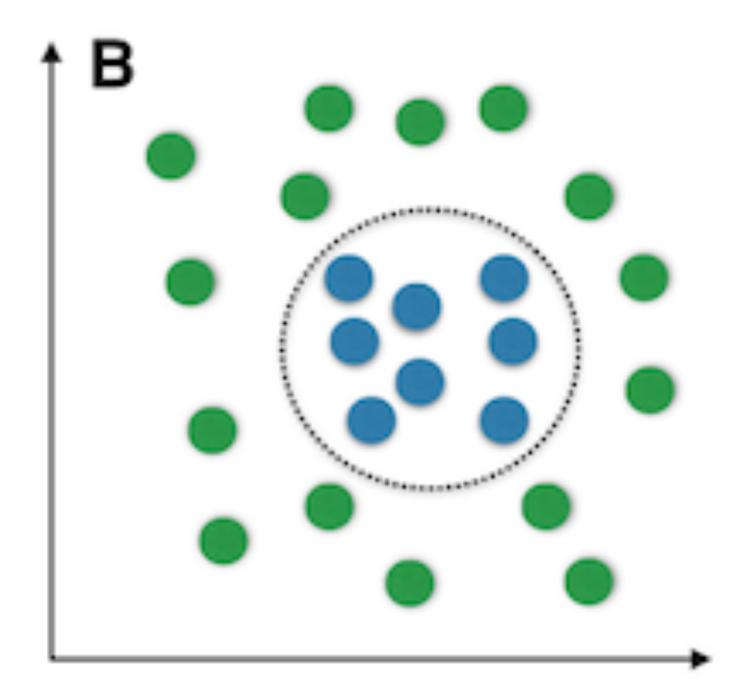
From: Yingcong Li [view email] [v1] Thu, 31 Aug 2023 17:57:50 UTC (1,671 KB) [v2] Thu, 7 Sep 2023 17:50:52 UTC (1,835 KB) [v3] Thu, 22 Feb 2024 18:38:14 UTC (1,081 KB)

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### Core philosophy

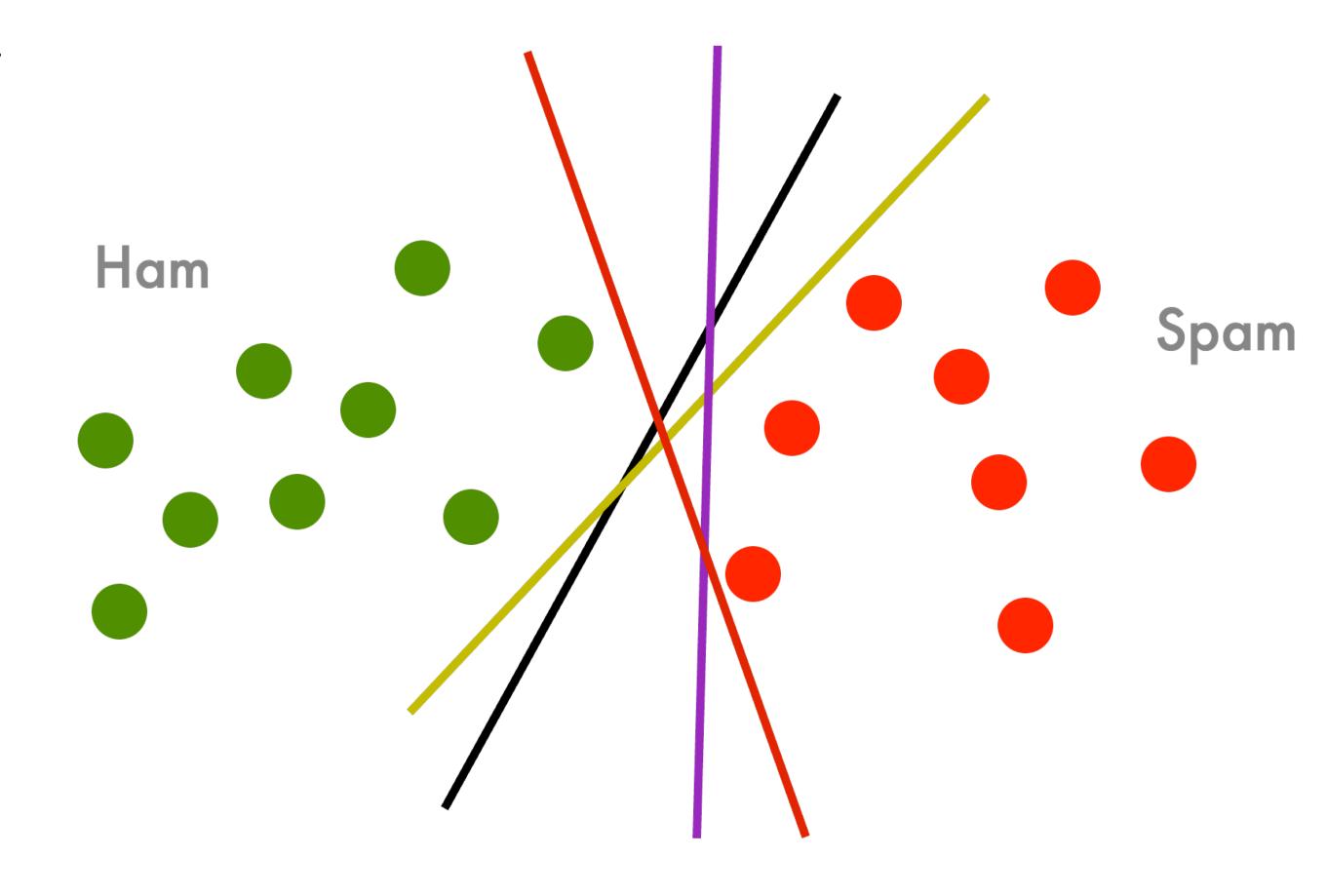
- Suppose that we have a linearly separable data
  - i.e., exists a linear classifier that perfectly classifies the training data.





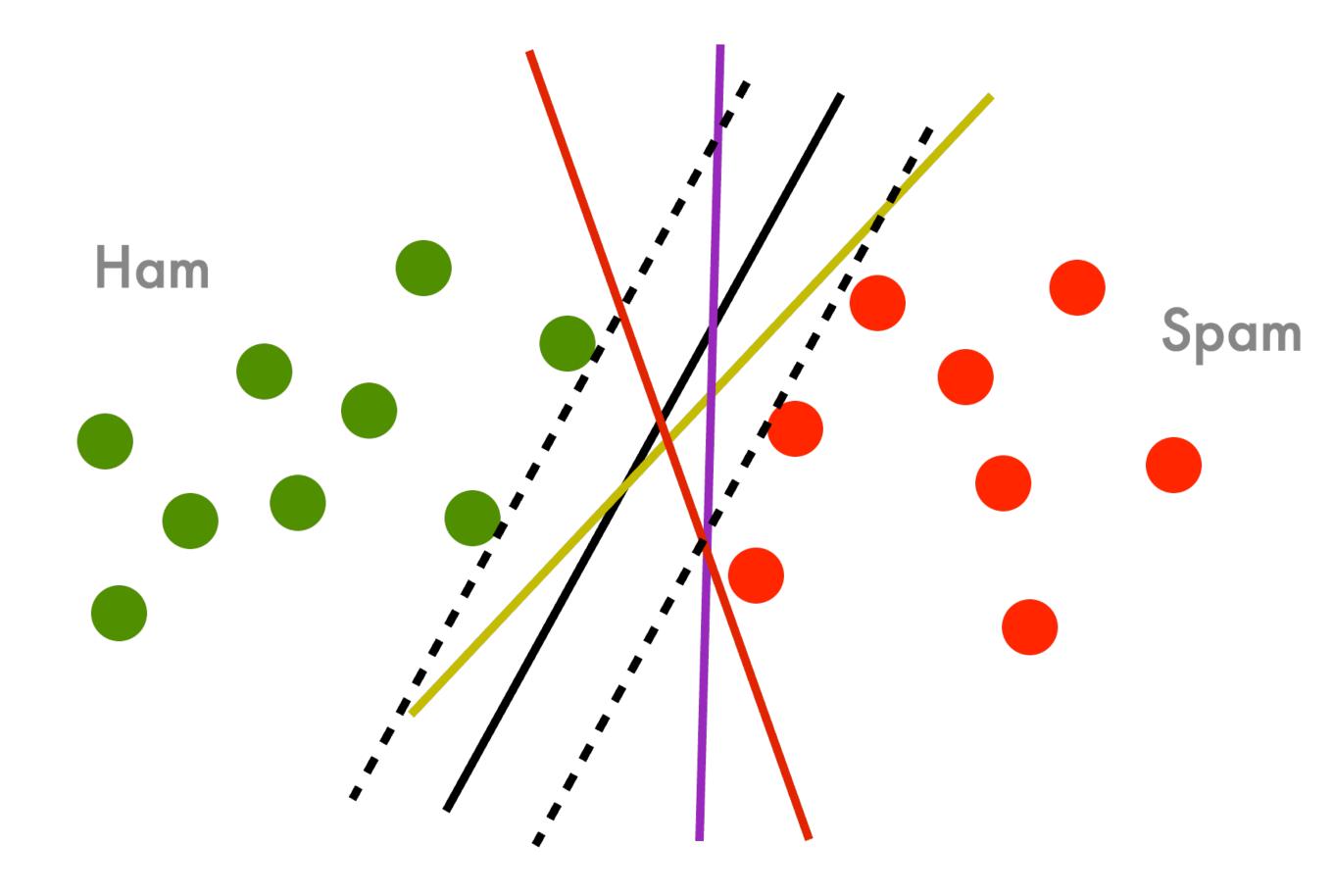
## Core philosophy

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- Then there could be <u>many correct</u> classifiers...
- **Question.** How should we choose one?

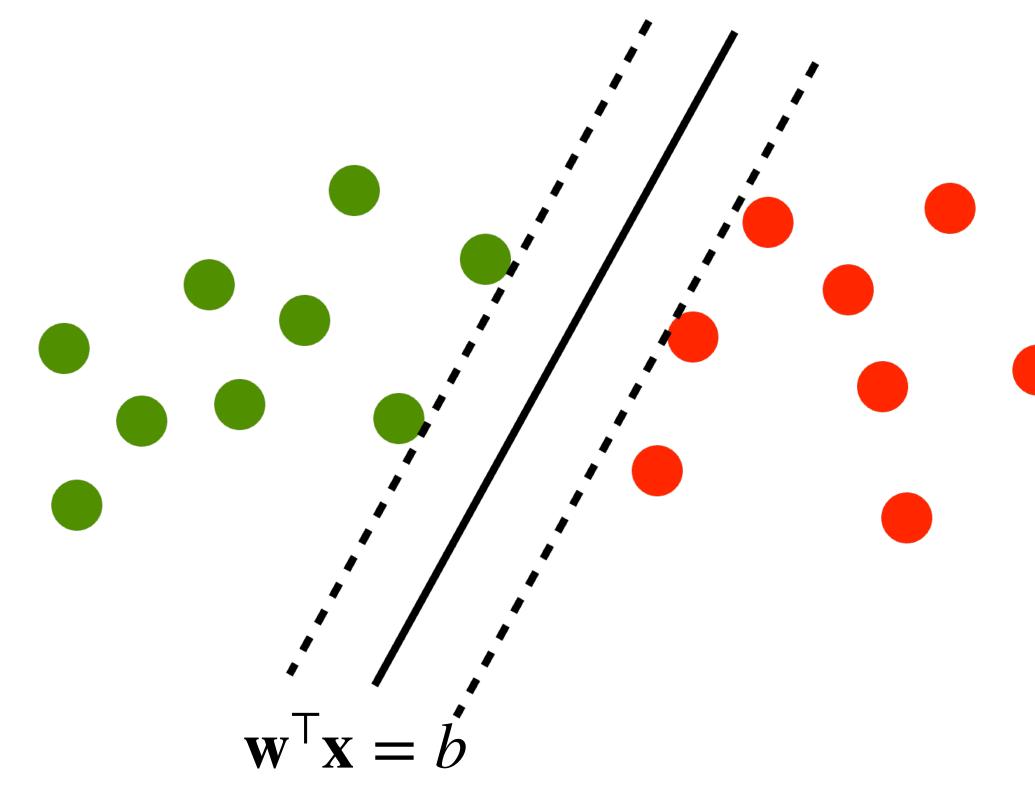


## Core philosophy

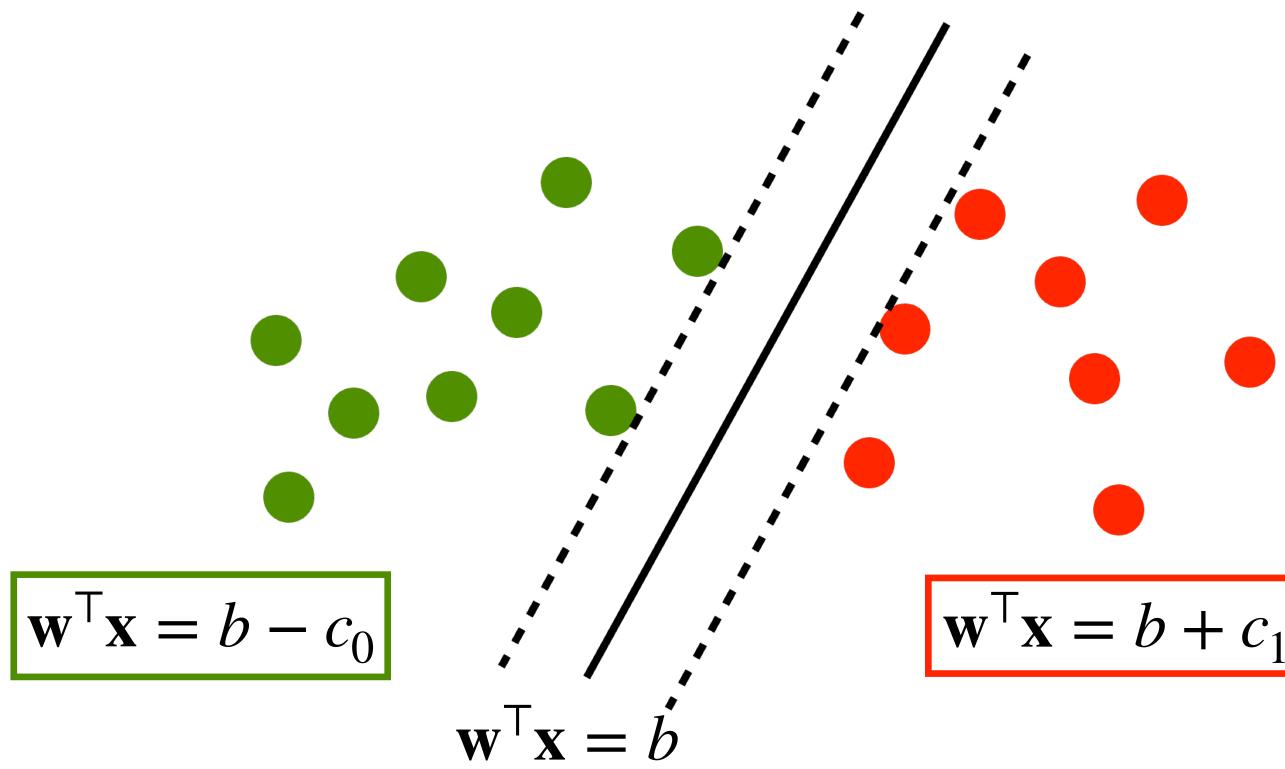
- Suppose that we have a **linearly separable** data
  - i.e., exists a linear classifier that perfectly classifies the training data.
- Then there could be <u>many correct</u> classifiers...
- **Question.** How should we choose one?
  - Idea. We should choose the maximum-margin classifier!
  - <u>Reason</u>. Robust to noise in test data • (there could be any noise in test data)



• **Question.** How do we formalize the concept of margin?

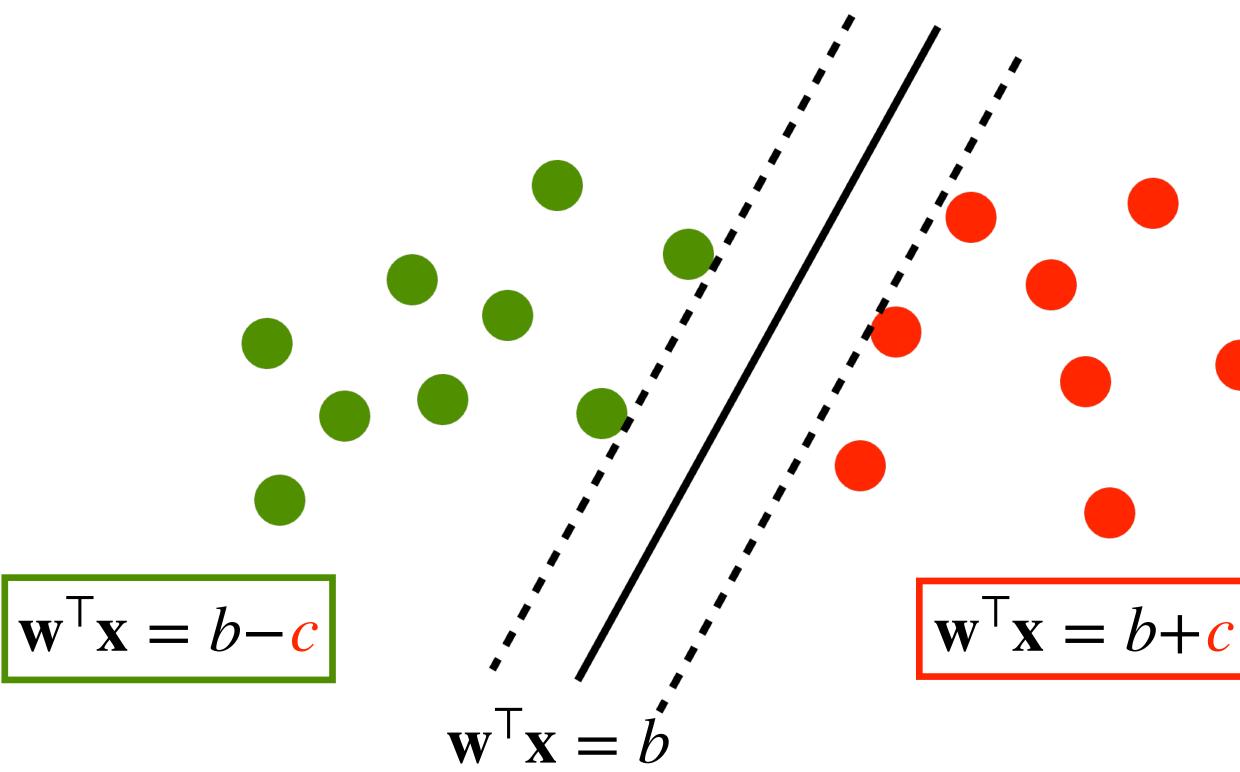


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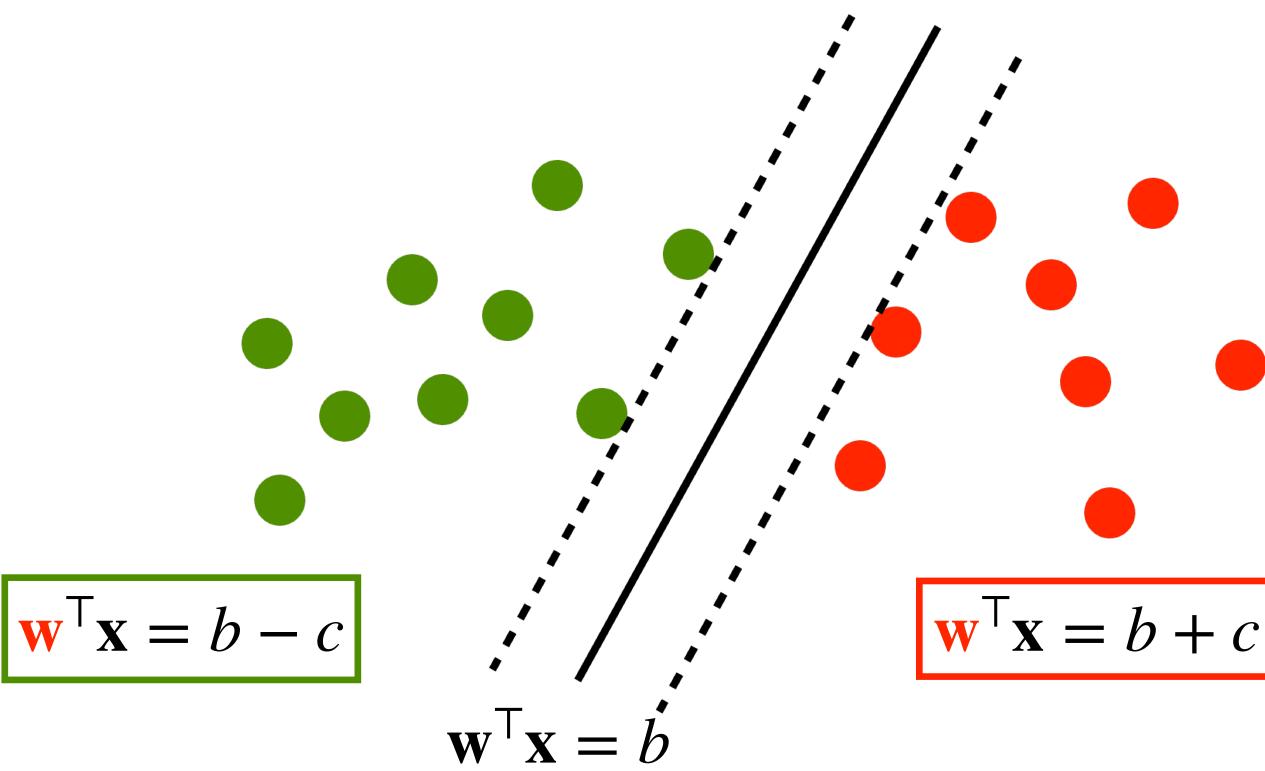


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  - We should take the midpoint:





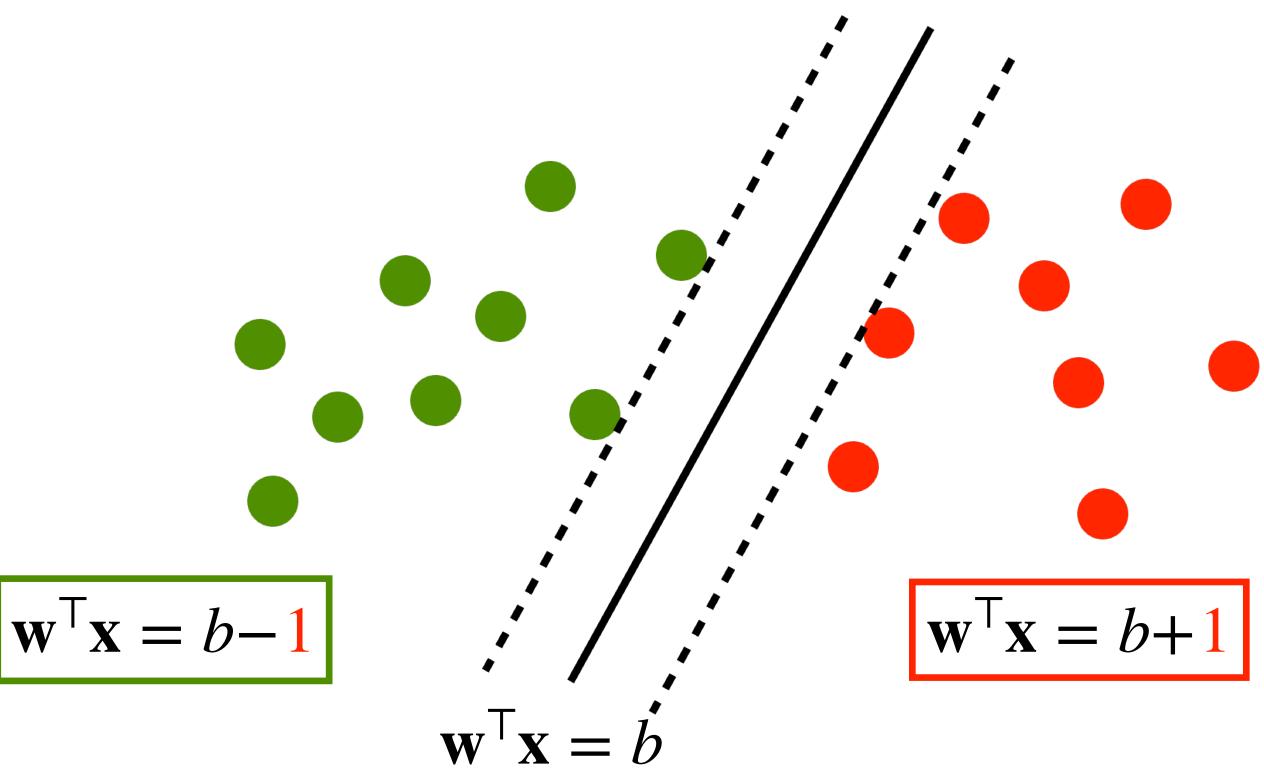
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  - We should normalize the size of **w** 
    - Otherwise the size of *c* can be arbitrarily large



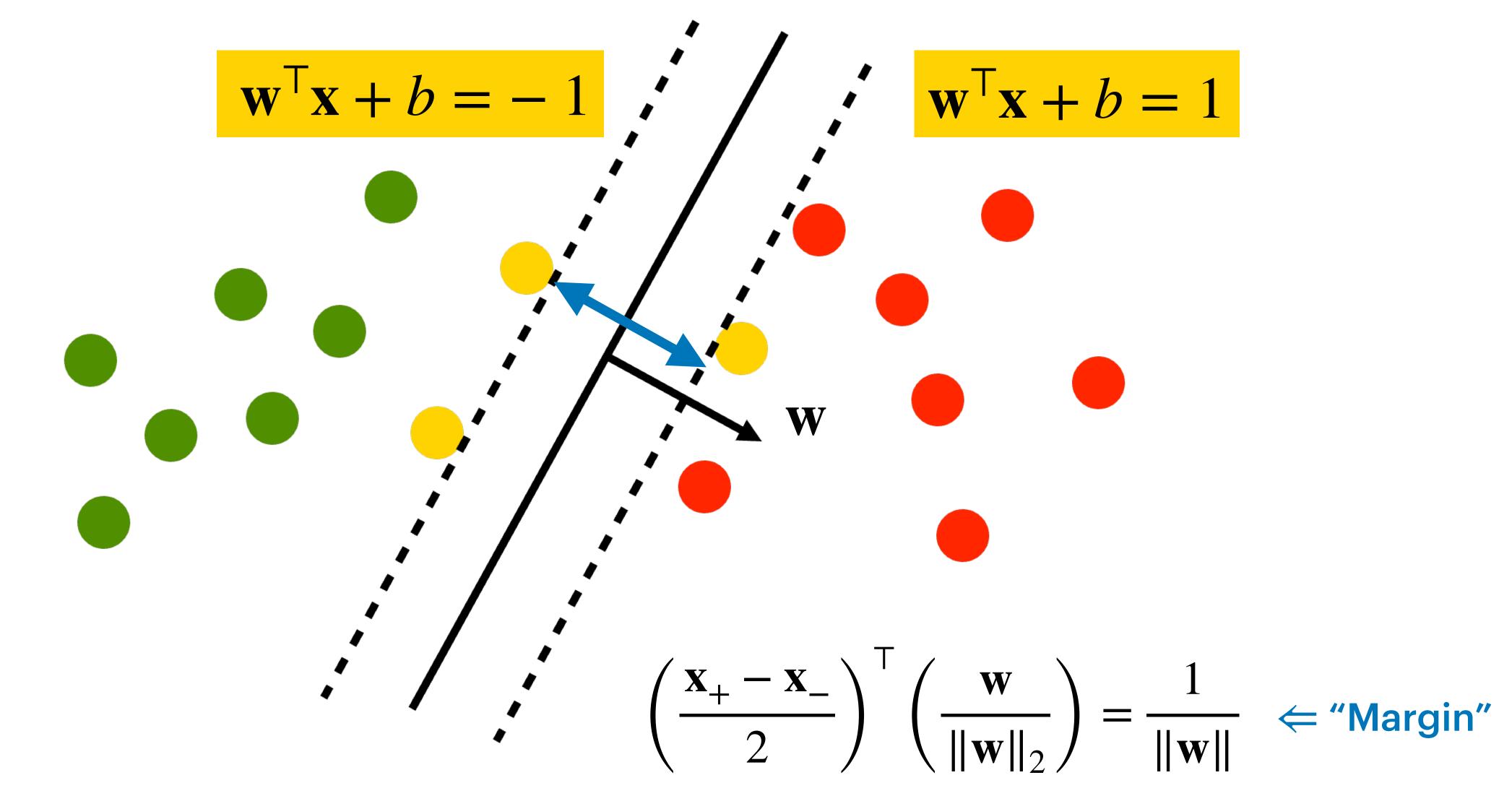


- Question. How do we formalize the concept of margin?
- Idea. Maximum shift that the classifier can withstand
  - We should take the midpoint
  - We should normalize the size of **w**

- Otherwise the size of *c* can be arbitrarily large
- Other way around, we can just fix c = 1, and look at the size of  $1/\|\mathbf{w}\|_2$



• Cleaner(?) intuition. Project it along the direction





#### Max Margin Classifiers

- **SVM.** Designed as a maximum-margin classifier
  - We solve the <u>constrained optimization</u> problem

$$\begin{array}{c} \text{maximize}_{\mathbf{w},b} & \frac{1}{\|\mathbf{w}\|_2} \end{array}$$

subject to  $y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) \ge 1$ 

(We use  $y_i \in \{-1, +1\}$ , instead of the usual  $\{0, 1\}$ )

### Max Margin Classifiers

- **SVM.** Designed as a maximum-margin classifier
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$$\begin{array}{c}1\\maximize_{\mathbf{w},b}\\\|\mathbf{w}\|_{2}\end{array}$$

- **Question.** How do we solve the constrained optimization?
  - <u>Remark</u>. As convention, we will slightly rephrase as a minimization problem ullet

$$\mathscr{C}^* = \min_{\mathbf{w}, b} \frac{\|\mathbf{w}\|_2^2}{2}$$

subject to  $y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) \ge 1$ 

#### (We use $y_i \in \{-1, +1\}$ , instead of the usual $\{0, 1\}$ )

subject to  $y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) \ge 1$ 

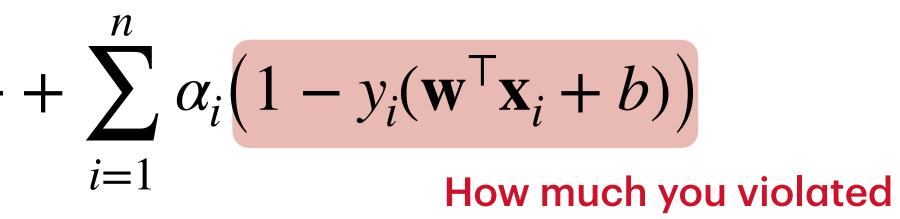
## Solving the Optimization: Dual $\mathscr{C}^* = \min_{\mathbf{w}, b} \frac{\|\mathbf{w}\|_2^2}{2} \quad \text{subject to}$

• **Solution.** Consider the Lagrangian dual of the problem

$$\mathscr{L}(\mathbf{w}, b, \alpha) = \frac{\|\mathbf{w}\|^2}{2}$$

$$y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) \ge 1$$

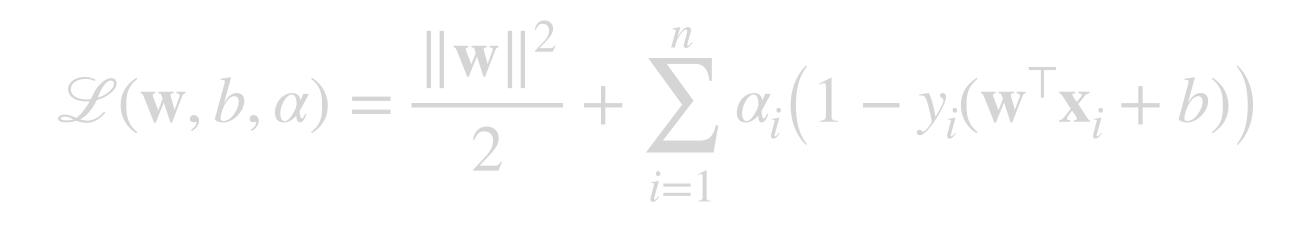
(the original problem is called "primal")





## Solving the Optimization: Dual $\mathscr{C}^* = \min_{\mathbf{w}, b} \frac{\|\mathbf{w}\|_2^2}{2} \quad \text{subject to} \quad y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b) \ge 1$

 Solution. Consider the Lagrangian dual of the problem (the original problem is called "primal")



• Then, interestingly, we know that the following duality holds:

• Question. Why?

```
\ell^* = \min \max_{\mathbf{w}, b} \mathcal{L}(\mathbf{w}, b, \alpha)
```



# Solving the Optimization: Dual • Primal. $\ell^* = \min_{\mathbf{w}, b} \frac{\|\mathbf{w}\|^2}{2}$ subject to $y_i(\mathbf{w}^\top \mathbf{x}_i + b) \ge 1$ Dual. $\ell^* = \min_{\mathbf{w}, b} \max_{\alpha \geq 0} \frac{\|\mathbf{w}\|^2}{2} + \sum_{i=1}^n \alpha_i (1 - y_i(\mathbf{w}^\top \mathbf{x}_i + b))$

• Interpretation. The adversary will gauge the quantity  $1 - y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b)$ 

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• If > 0:  $\dots \quad \alpha_i \to \infty$ 

infeasible for primal,  $\infty$  for dual



# Solving the Optimization: Dual • Primal. $\ell^* = \min_{\mathbf{w}, b} \frac{\|\mathbf{w}\|^2}{2}$ subject to $y_i(\mathbf{w}^\top \mathbf{x}_i + b) \ge 1$

Dual.  $\ell^* = \min_{\mathbf{w}, b} \max_{\alpha \ge 0} \frac{\|\mathbf{w}\|^2}{2} + \sum_{i=1}^n \alpha_i (1 - y_i(\mathbf{w}^\top \mathbf{x}_i + b))$ 

• Interpretation. The adversary will gauge the quantity  $1 - y_i(\mathbf{w}^{T}\mathbf{x}_i + b)$ 

• If > 0:  $\dots$   $\alpha_i \to \infty$ 

• If < 0:  $\cdots$   $\alpha_i = 0$ 

infeasible for primal,  $\infty$  for dual

primal = dual



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- Interpretation. The adversary will gauge the quantity  $1 y_i(\mathbf{w}^{\mathsf{T}}\mathbf{x}_i + b)$ 
  - If > 0:  $\dots \quad \alpha_i \to \infty$
  - If < 0:  $\cdots \alpha_i = 0$
  - If = 0any constant • • •

infeasible for primal,  $\infty$  for dual

primal = dual

primal = dual (margin points!)



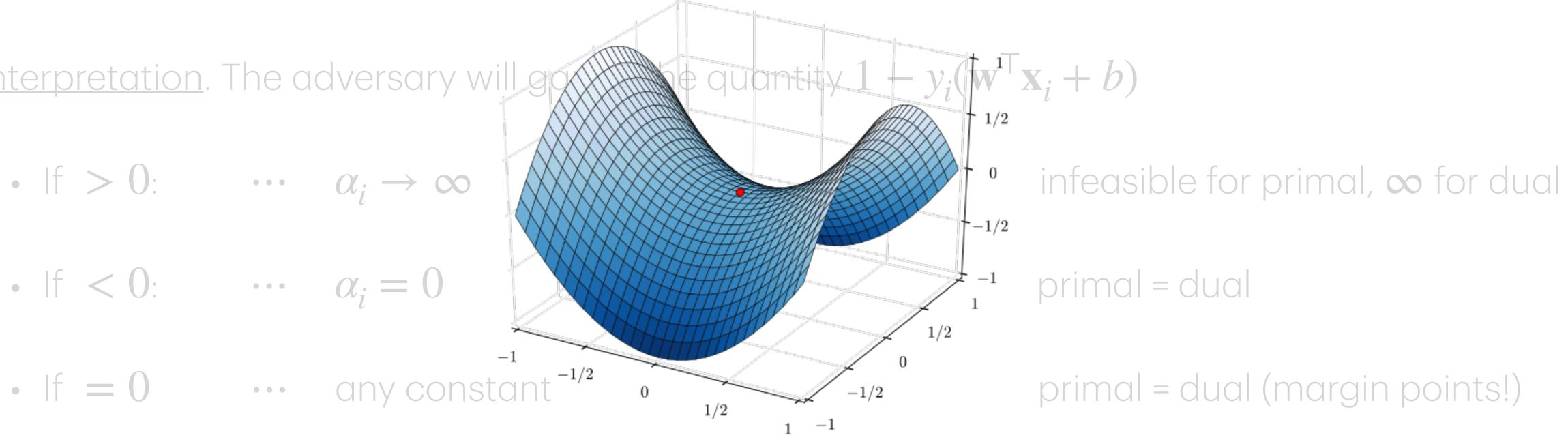


## Solving the Optimization: Dual

Primal.  $\ell^* = \min_{\mathbf{w}, b} \frac{\|\mathbf{w}\|^2}{2}$  subject to  $y_i(\mathbf{w}^\top \mathbf{x}_i + b) \ge 1$ 

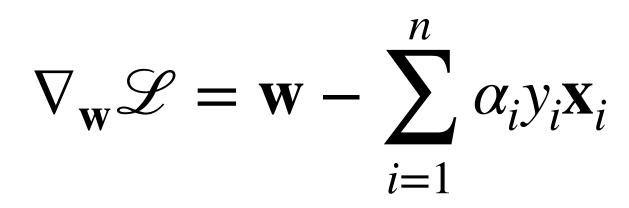
- Dual.  $\ell^* = \min_{\mathbf{w}, b} \max_{\alpha \ge 0} \frac{\|\mathbf{w}\|^2}{2} + \sum_{i=1}^n \alpha_i (1 y_i(\mathbf{w}^\top \mathbf{x}_i + b))$  Interpretation. The adversary will go • If > 0:  $\dots \quad \alpha_i \to \infty$ • If < 0:  $\cdots$   $\alpha_i = 0$ 

  - Thus, what remains is solving this minimax problem, finding the saddle point



#### Saddle point

• Of course, we look for the **critical point;** writing down the gradient, we get



$$\nabla_b \mathscr{L} = -\sum_{i=1}^n \alpha_i y_i$$

#### Saddle point

• Of course, we look for the **critical point**; writing down the gradient, we get

• Setting them equal to zero, we get

$$\mathbf{w}^* = \sum_{i=1}^n \alpha_i y_i \mathbf{x}_i$$

i=1

 $\nabla_{\mathbf{w}} \mathscr{L} = \mathbf{w} - \sum_{i=1}^{n} \alpha_{i} y_{i} \mathbf{x}_{i}$ 

$$\nabla_b \mathscr{L} = -\sum_{i=1}^n \alpha_i y_i$$

$$0 = \sum_{i=1}^{n} \alpha_i y_i$$

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i=1

 $\nabla_{\mathbf{w}} \mathscr{L} = \mathbf{w} - \sum_{i=1}^{n} \alpha_{i} y_{i} \mathbf{x}_{i}$ 

• Plugging  $\mathbf{W}^*$  back to Lagrangian, we get

$$\mathscr{L} = -\frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j \mathbf{x}_i^{\mathsf{T}} \mathbf{x}_j + \sum_{i=1}^n \alpha_i$$

$$\nabla_b \mathscr{L} = -\sum_{i=1}^n \alpha_i y_i$$

$$0 = \sum_{i=1}^{n} \alpha_i y_i$$

#### Saddle point as a quadratic program

• Summing up, our optimization problem becomes

$$\max_{\alpha} \left( -\frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j \mathbf{x}_i^{\mathsf{T}} \mathbf{x}_j + \sum_{i=1}^n \alpha_i \alpha_i y_i y_i y_j \mathbf{x}_i^{\mathsf{T}} \mathbf{x}_i \right)$$



subject to  $\sum_{i} \alpha_{i} y_{i} = 0, \quad \alpha_{i} \ge 0$ 

### Saddle point as a quadratic program

• Summing up, our optimization problem becomes

$$\max_{\alpha} \left( -\frac{1}{2} \sum_{i,j} \alpha_i \alpha_j y_i y_j \mathbf{x}_i^{\mathsf{T}} \mathbf{x}_j + \sum_{i=1}^n \alpha_i \alpha_i \alpha_j y_i y_j \mathbf{x}_i^{\mathsf{T}} \mathbf{x}_j \right)$$

• Slightly rephrased as a **quadratic program** over a convex polytope

$$\max_{\alpha} \left( -\frac{1}{2} \alpha^{\mathsf{T}} \mathbf{Z} \alpha + \mathbf{1}^{\mathsf{T}} \alpha \right)$$

- The solution @ critical point or the extreme points
- Use quadratic program solvers to get the optimal  $lpha^*$





 $\sum_{i} \alpha_{i} \alpha_{i} x_{i} = 0, \quad \alpha_{i} \ge 0$ 

subject to  $\alpha^{\mathsf{T}} \mathbf{y} = 0$ ,  $\alpha \geq 0$ 

### Solving for Bias

- Having computed the  $\alpha^*$ , our optimal weights become:

• **Question.** How about *b*\*?

Nonzero only for margin data (support vectors)

 $\mathbf{w}^* = \sum_{i=1}^{n} \alpha_i^* y_i \mathbf{x}_i$ i=1



### Solving for Bias

 $\mathbf{w}^* = \sum_{i=1}^{n} \alpha_i^* y_i \mathbf{X}_i$ 

i=1

• Having computed the  $\alpha^*$ , our optimal weights become:

- Question. How about *b*\*?
  - Answer. Plug in any support vector to

$$\mathbf{w}^{*\mathsf{T}}\mathbf{x} - b^* = \pm 1$$

Nonzero only for margin data (support vectors)



### Wrapping up

- Looked at a clever way to use linear classifier to solve classification
  - Idea. Maximize the margin
    - Putting in some extra condition to generalize better to test data (similar to what we did in k-NN, when deciding the hyperparameter)

## Wrapping up

- Looked at a clever way to use linear classifier to solve classification
  - Idea. Maximize the margin
    - Putting in some extra condition to generalize better to test data (similar to what we did in k-NN, when deciding the hyperparameter)

#### • Limitation.

- Messed up when outlier exists (yet)
- More generally, cannot handle nonlinear data

#### -> Soft SVM

-> Kernel SVM

### Cheers