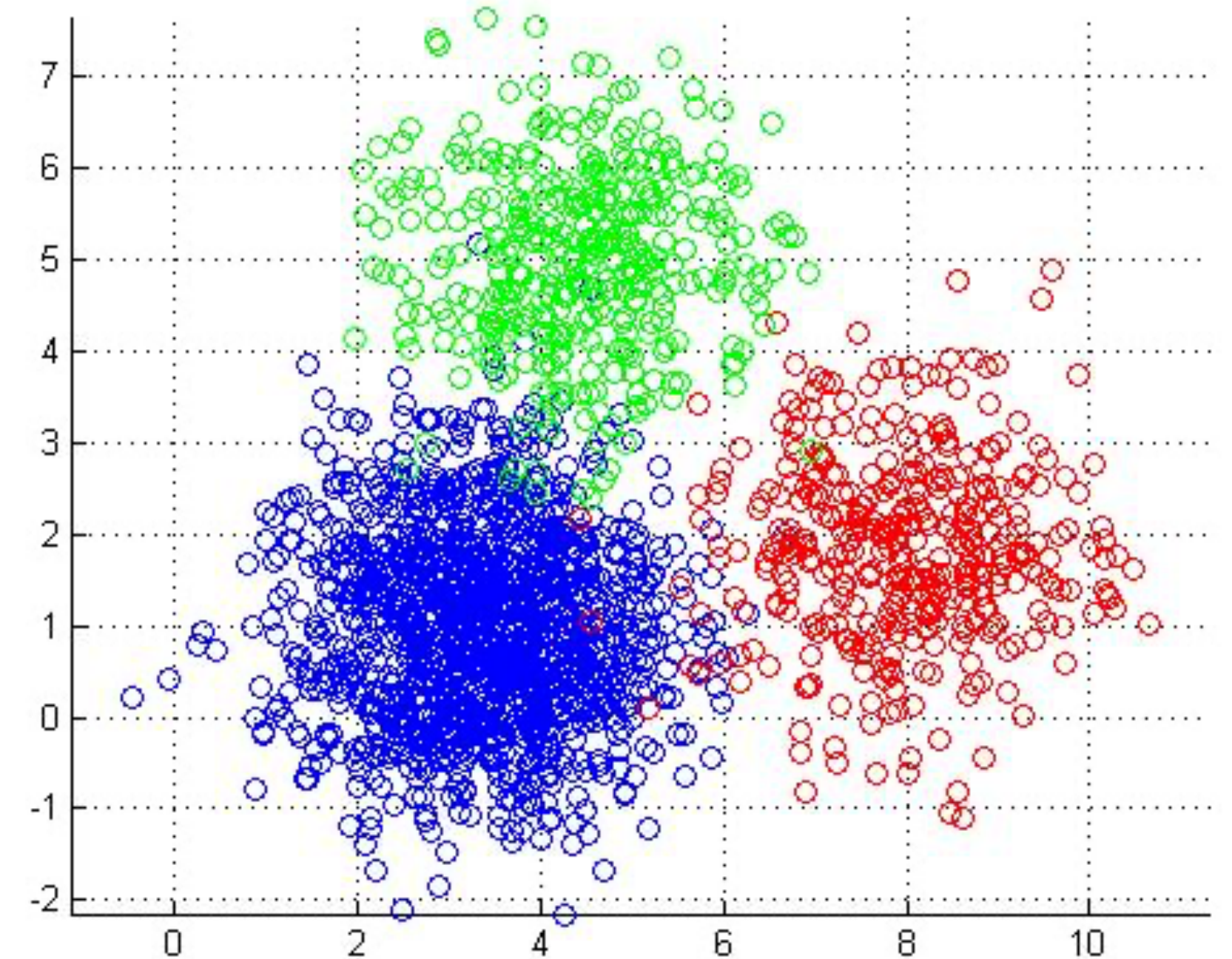


11. Dimensionality Reduction

**EECE454 Introduction to
Machine Learning Systems**

Recap: Unsupervised Learning

- Discover useful structure of the data, using **unlabeled data**.
 - K-means clustering
 - Gaussian Mixture Models
 - **Dimensionality Reduction** (this week)
 - Autoencoders, GANs, Diffusion models, ...



Dealing with high-dimensional data

- Many datasets are extremely high-dimensional, in its raw form.
- Suppose that you are an ML engineer at Google.
Then, you'd need to learn from these datasets:



YouTube Shorts

1920 x 1080 x 3 colors x 60 fps x 60 seconds
= 22.4 billion pixels (per video)

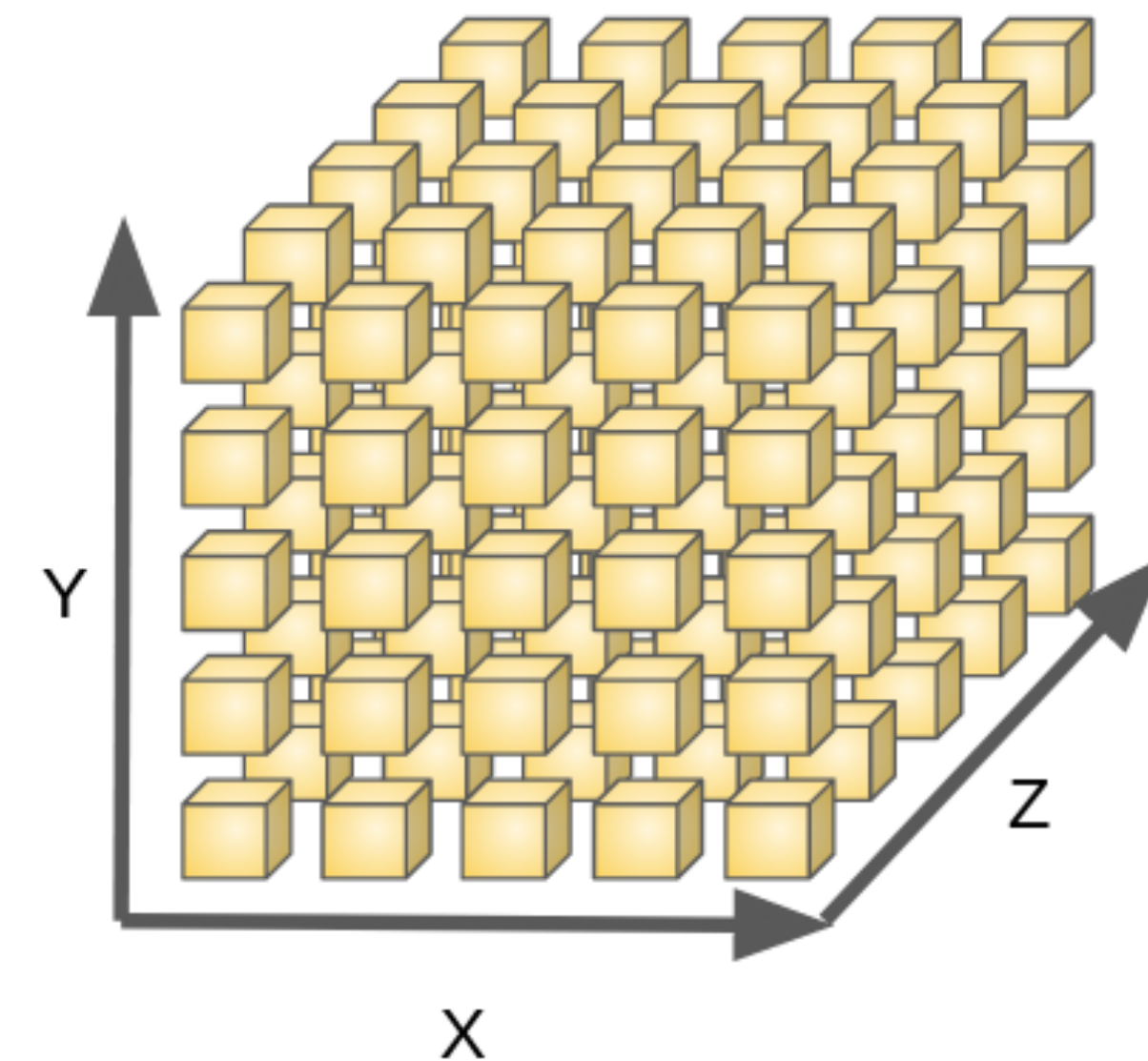
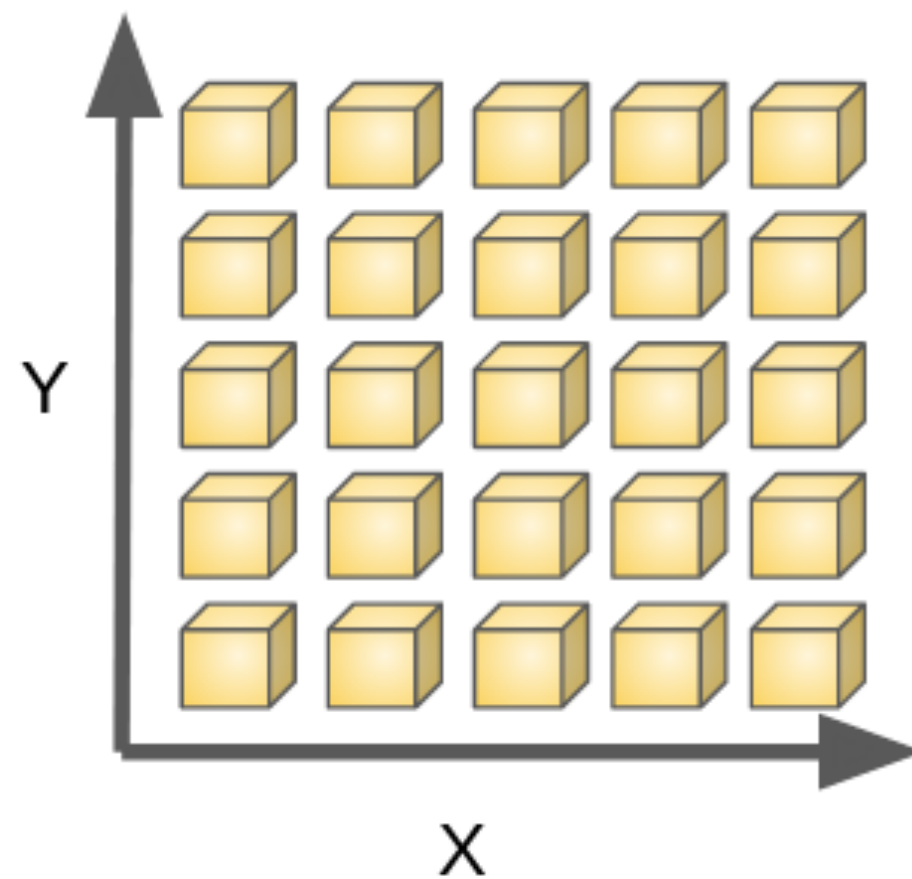
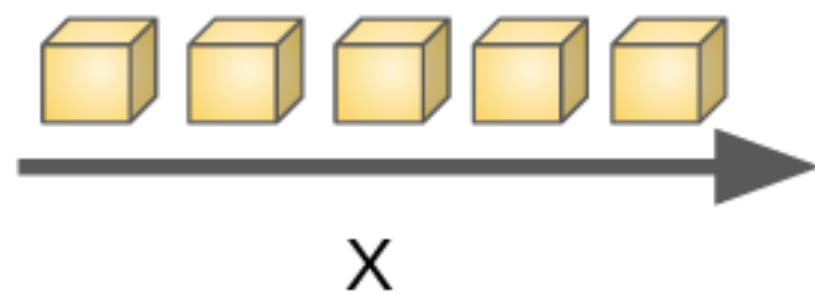


Gmail

1000s of words x sender info x receiver info x (images...)
= millions~billions real numbers (per mail)

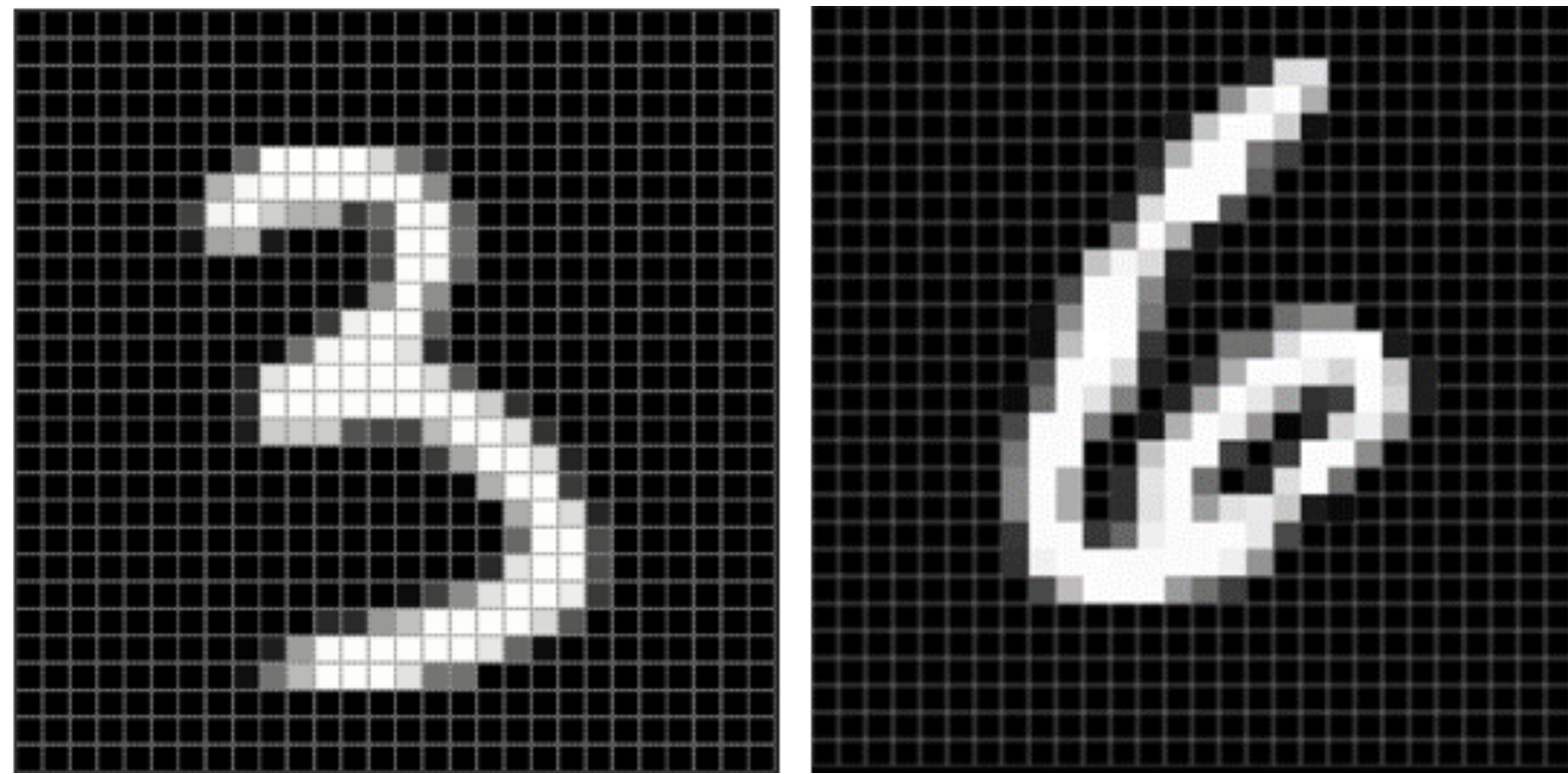
Curse of Dimensionality

- Higher-dimensional data are nasty to do ML on.
 - More computation.
 - Higher chance of noise.
 - Difficult to visualize (for human insight)
 - Difficult to find meaningful patterns.

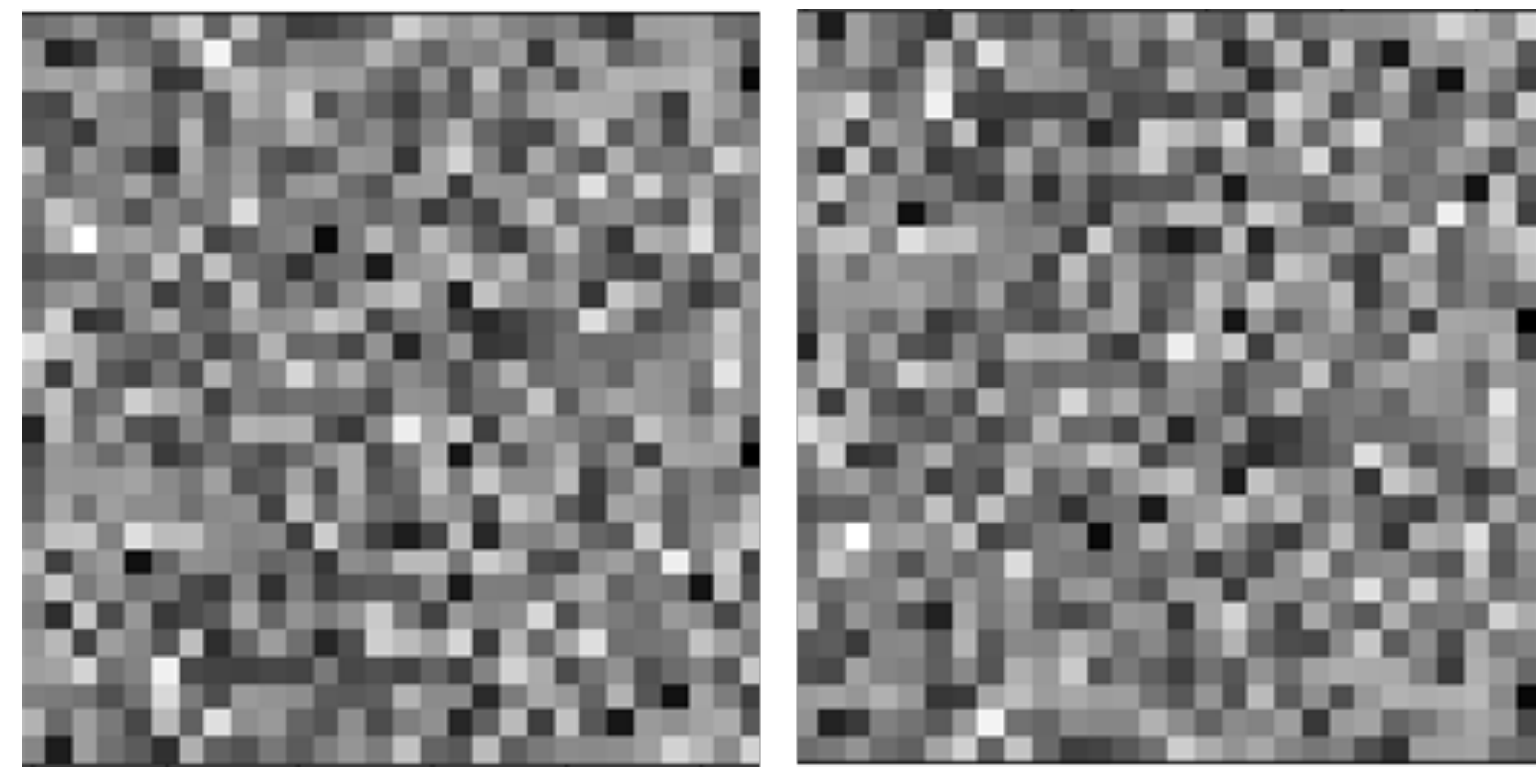


Dimensionality: Nominal vs. True

- But do we really need all dimensions?
 - Example. Handwritten Digit Recognition (MNIST, 28x28 image)



only looks like this



... and not like this

- That is, we may not need to **fully utilize** $\mathbb{R}^{28 \times 28} = \mathbb{R}^{784}$.

Dimensionality: Nominal vs. True

Hypothesis

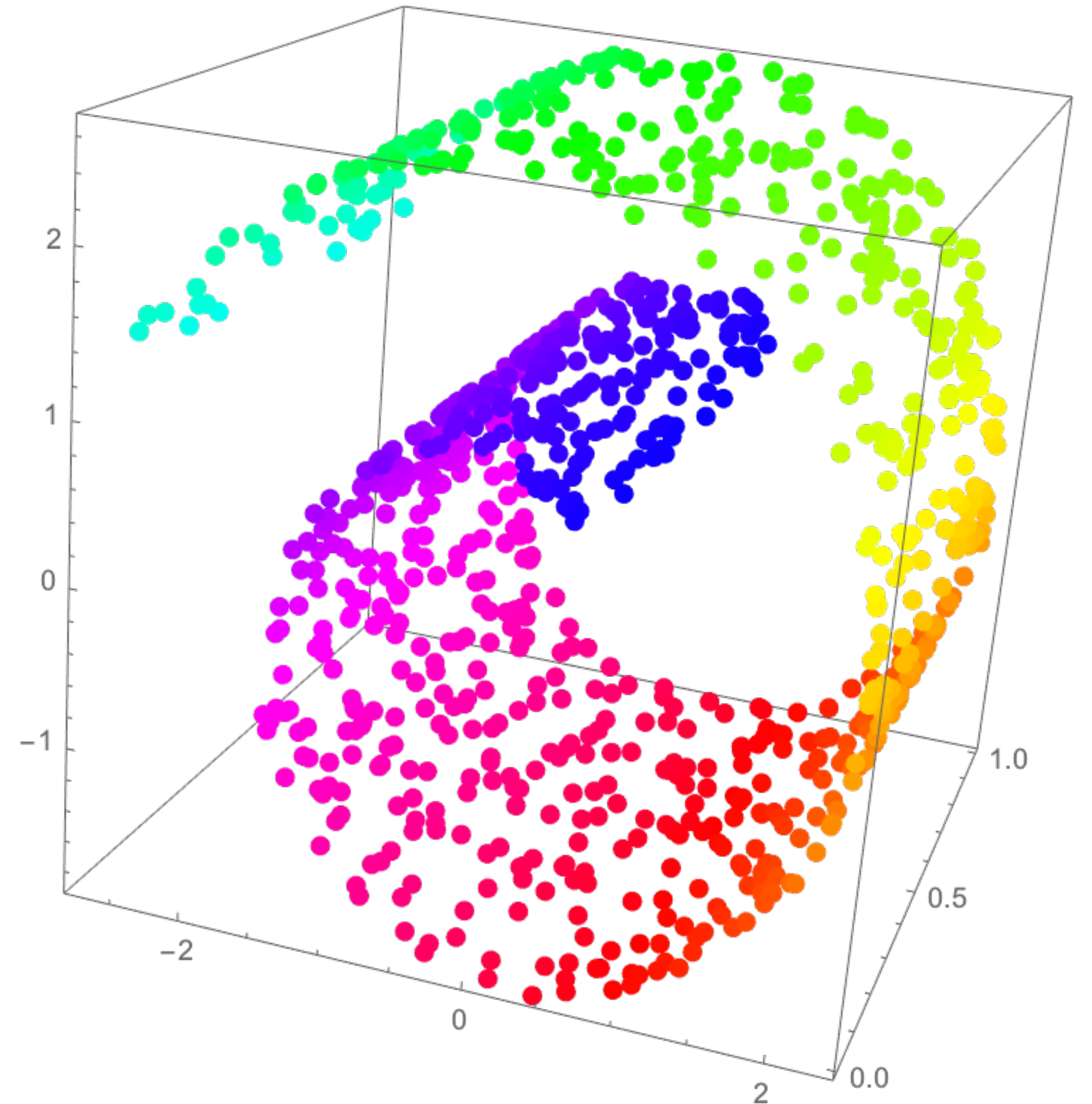
There is a **low-dimensional subspace** (or submanifold) in the high-d space where the real data lies on.

Important. Ignore small "noise" in each datum!

Dimensionality Reduction

Finding these high-d \rightarrow low-d mapping.

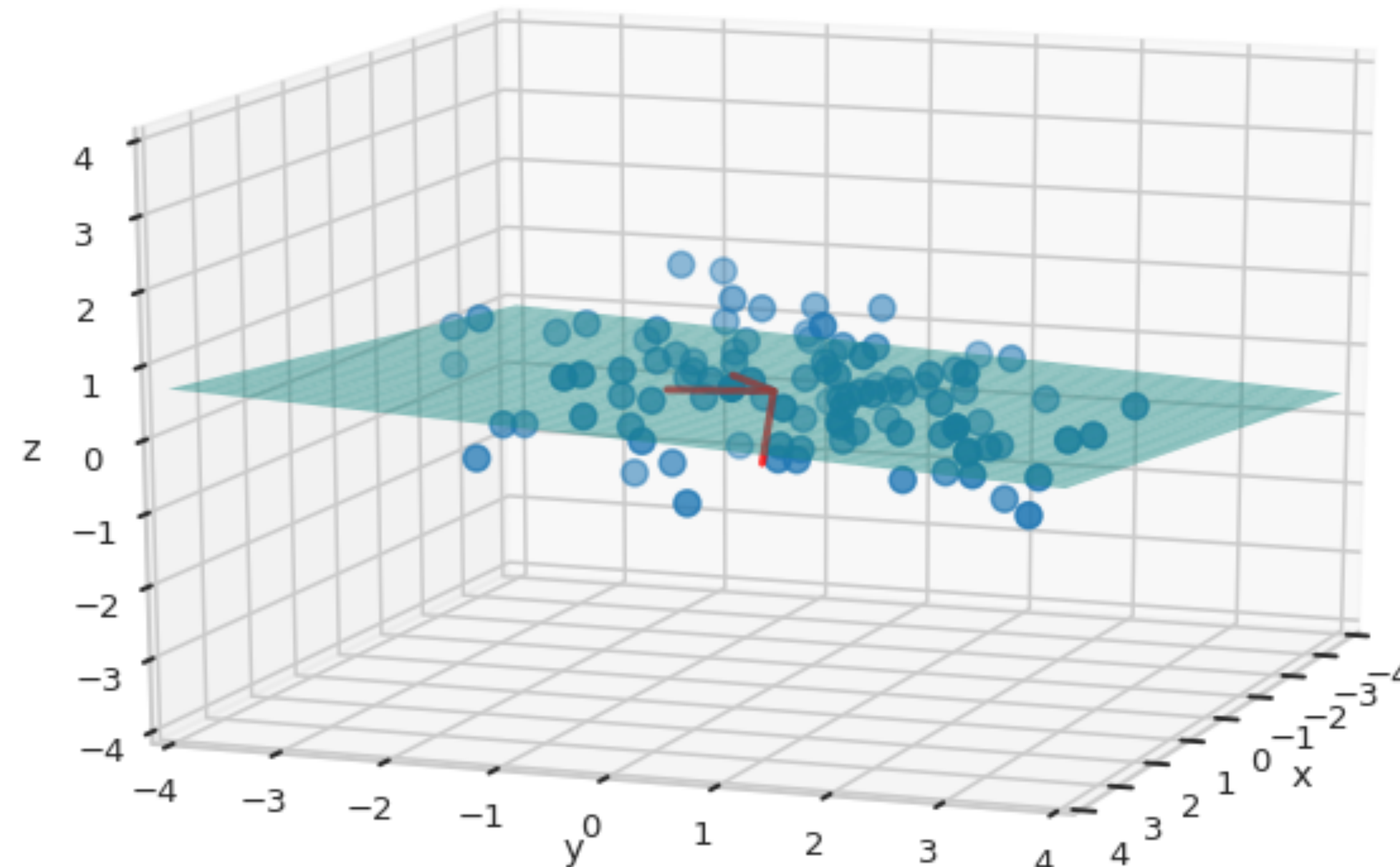
Note. No need for labels!



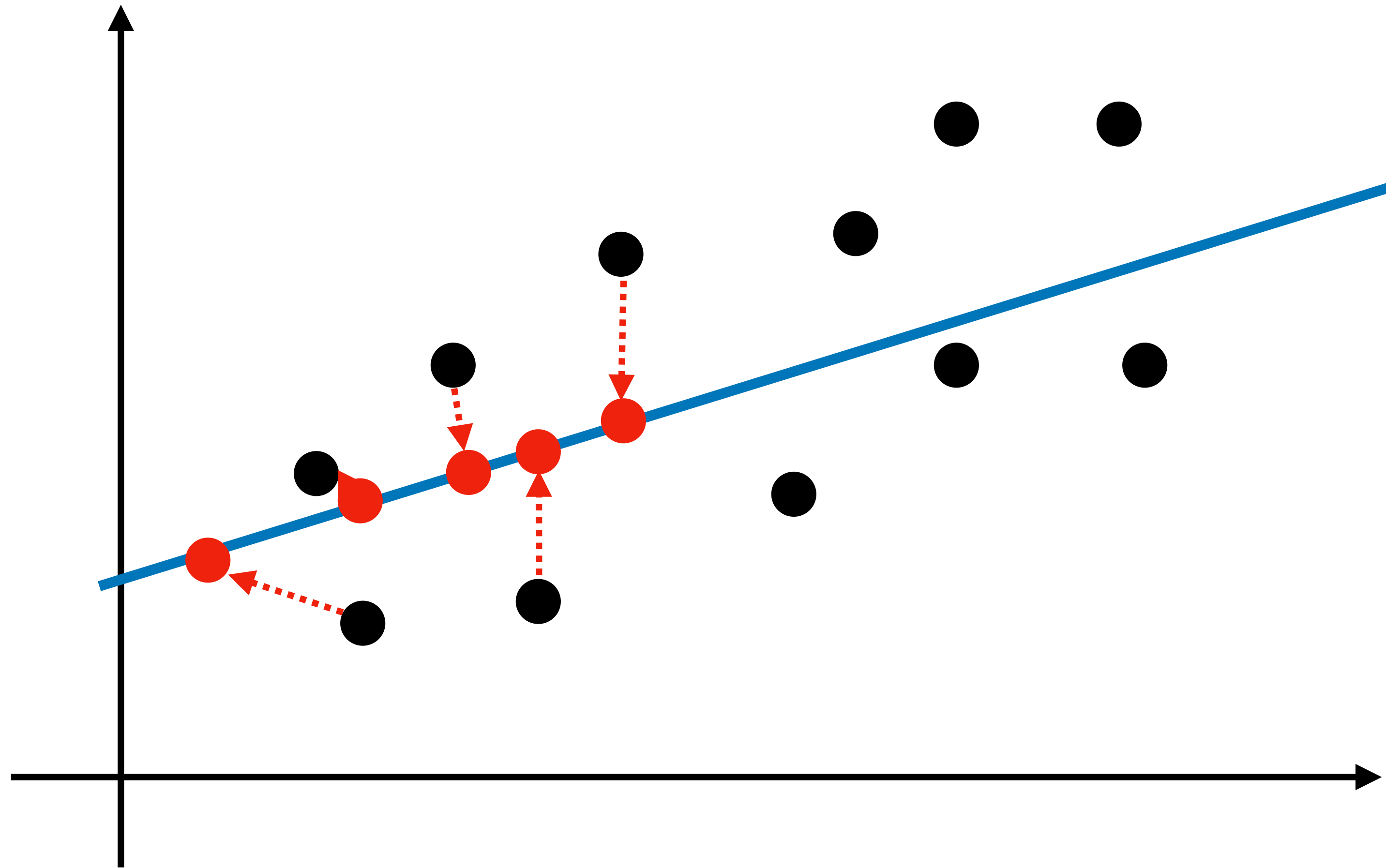
Principal Component Analysis

Principal Component Analysis

- Dimensionality reduction using a **affine subspace** of the original space
 - Invented by Karl Pearson (1909)
 - Many aliases, e.g., Karhunen-Loève Transform

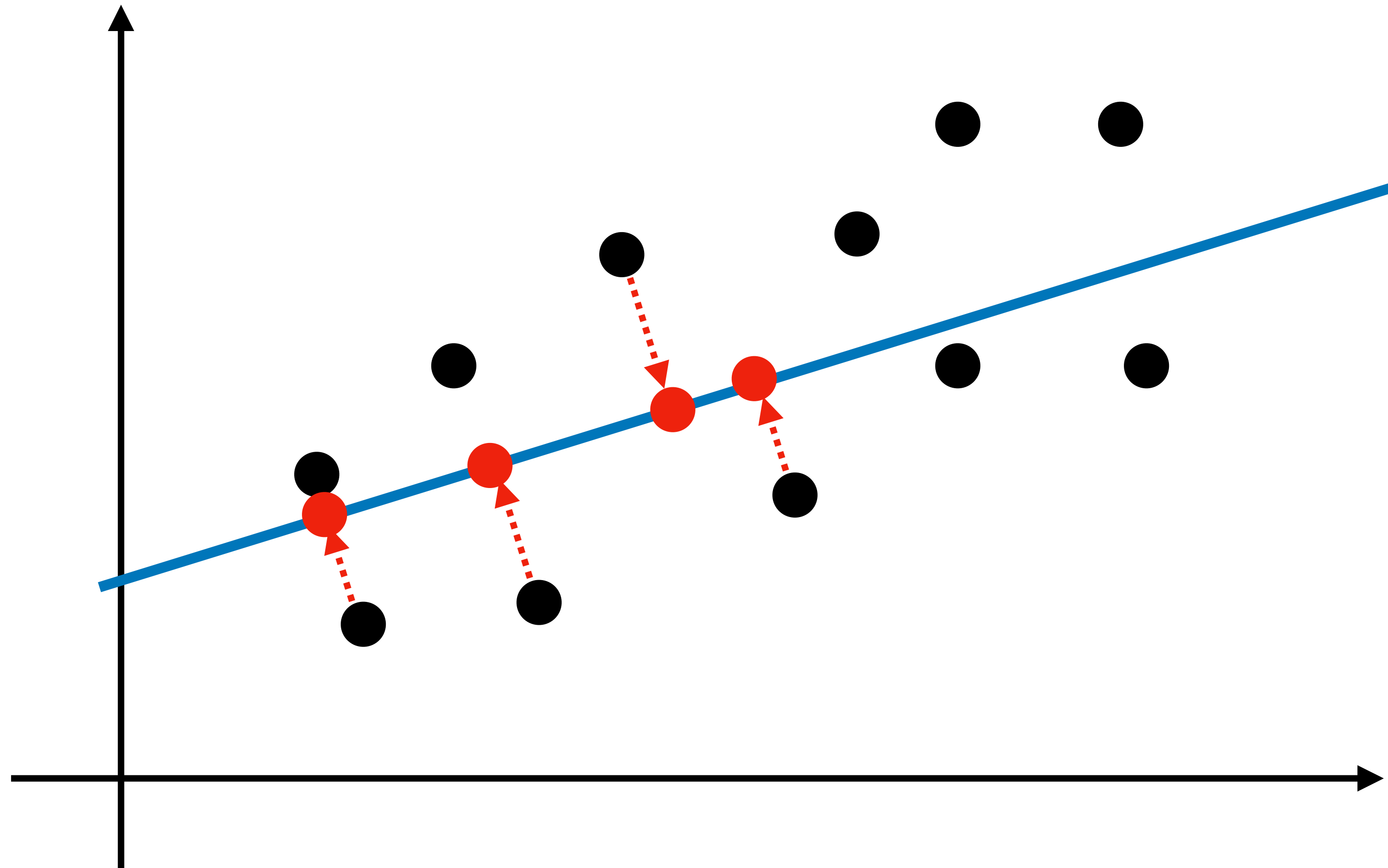


Suppose that we are given a 2D dataset—here, we want to find a **1D subspace** and a **mapping**, s.t. mapped data has **nice properties**.

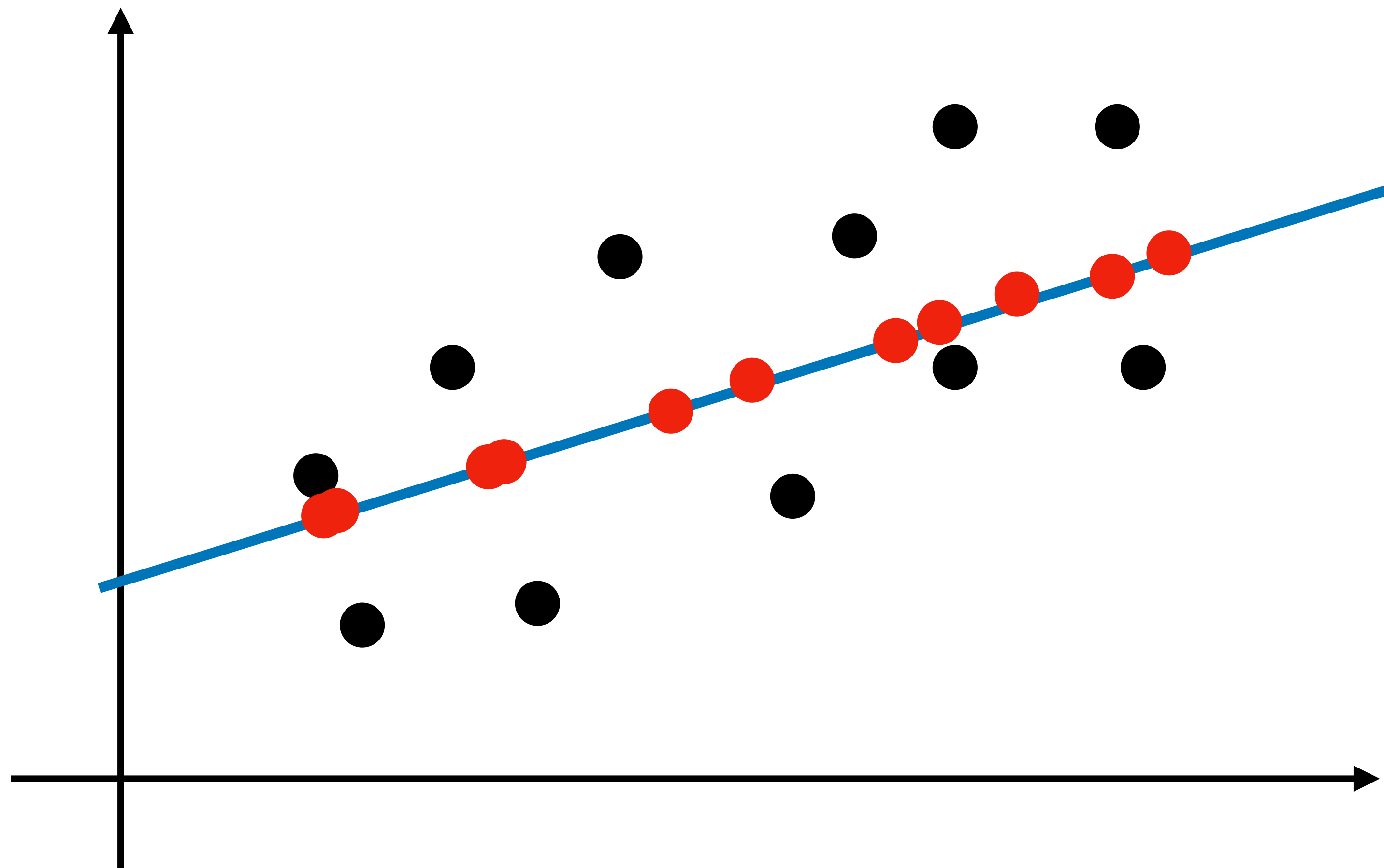


Suppose that we are given a 2D dataset—here, we want to find a 1D subspace and a **mapping**, s.t. mapped data has **nice properties**.

simplify \Rightarrow only consider **(orthogonal) projections** to the subspace.

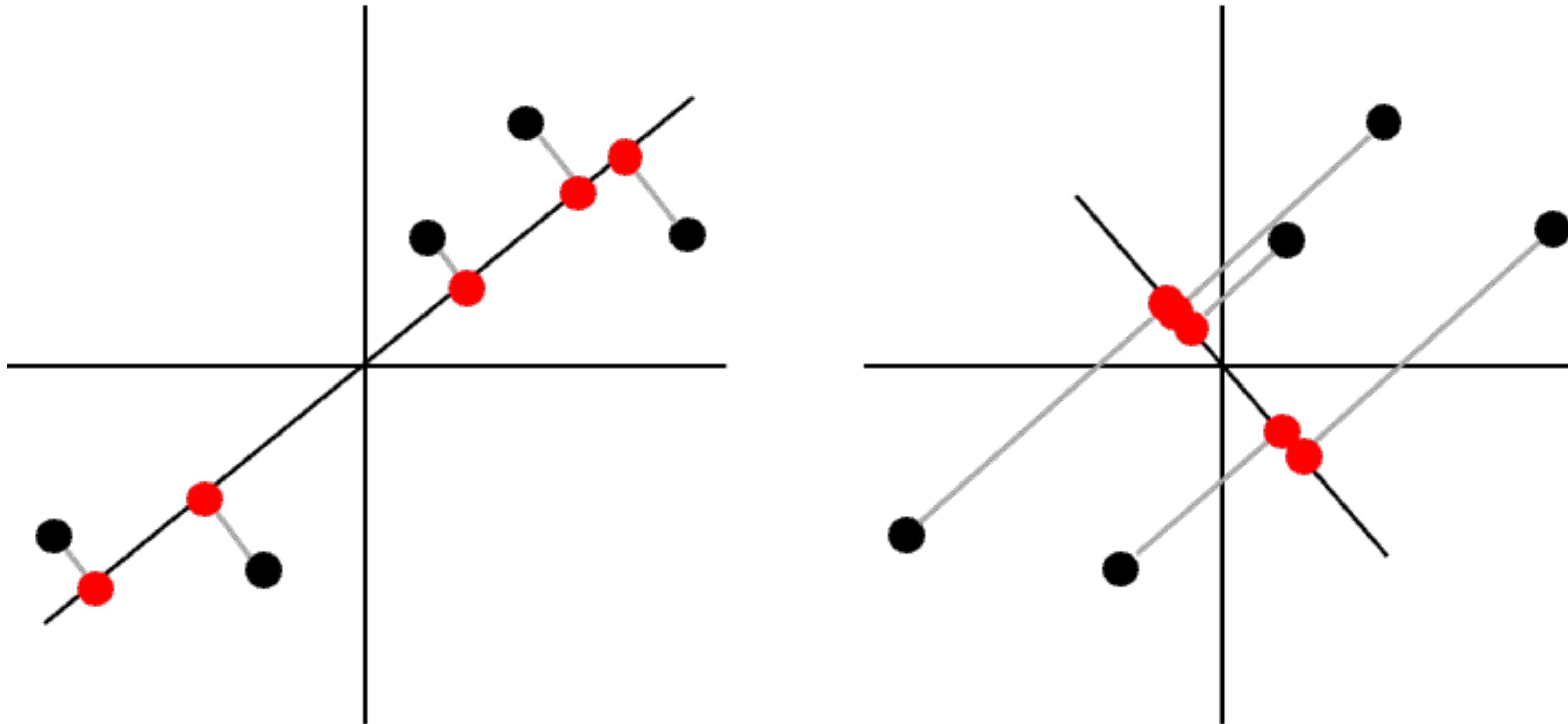


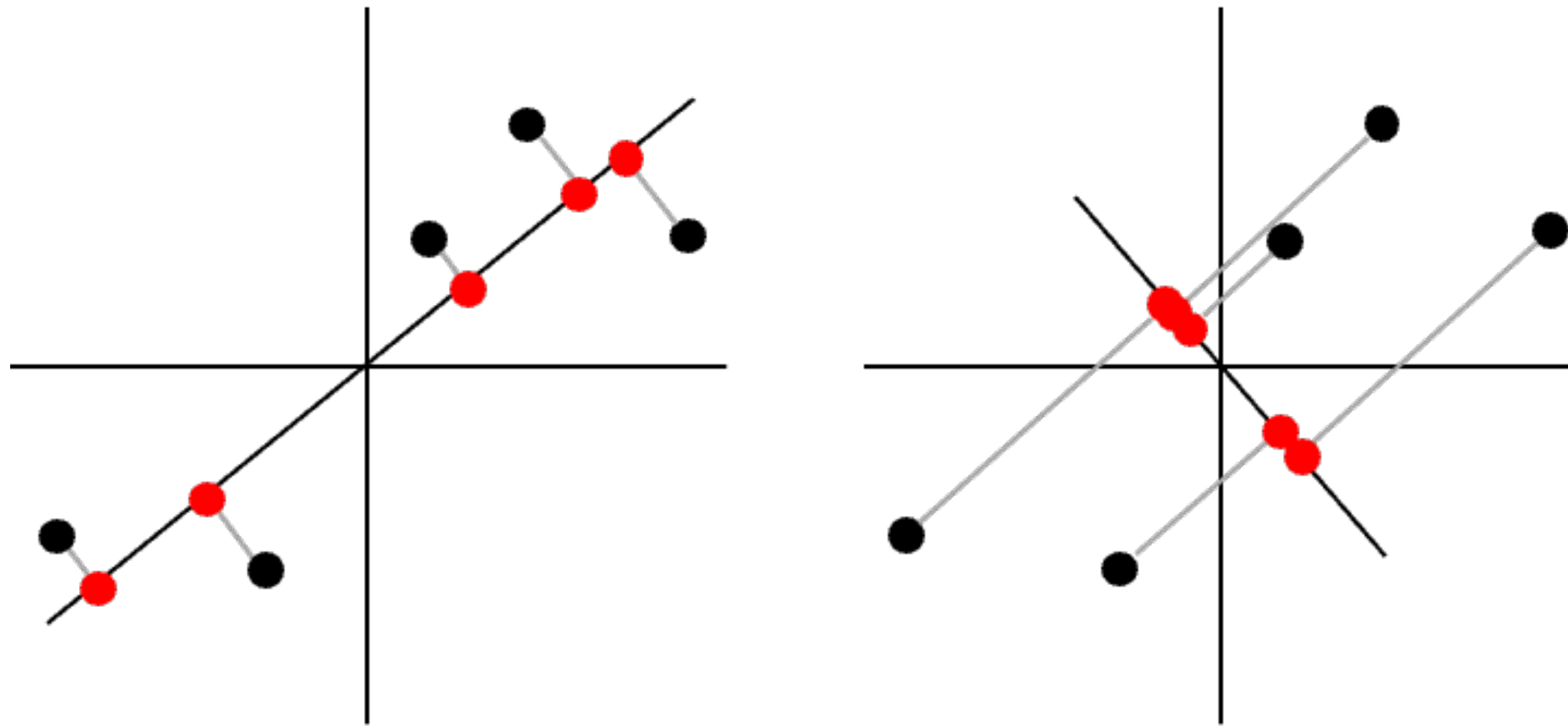
Suppose that we are given a 2D dataset—here, we want to find a **1D subspace**, s.t. the projected data has **nice properties**.



The Spirit

- We want to **preserve the information** as much as possible.
 - **Question.** Which projection contains more information?





- **Answer. Left!**

A. Projected points are more widely spread.

B. Original points (●) are closer to their projections (●)

(we will see that A and B are equivalent)

What PCA does, abstractly.

Suppose that we have the dataset $\mathbf{x}_1, \dots, \mathbf{x}_n \in \mathbb{R}^d$.

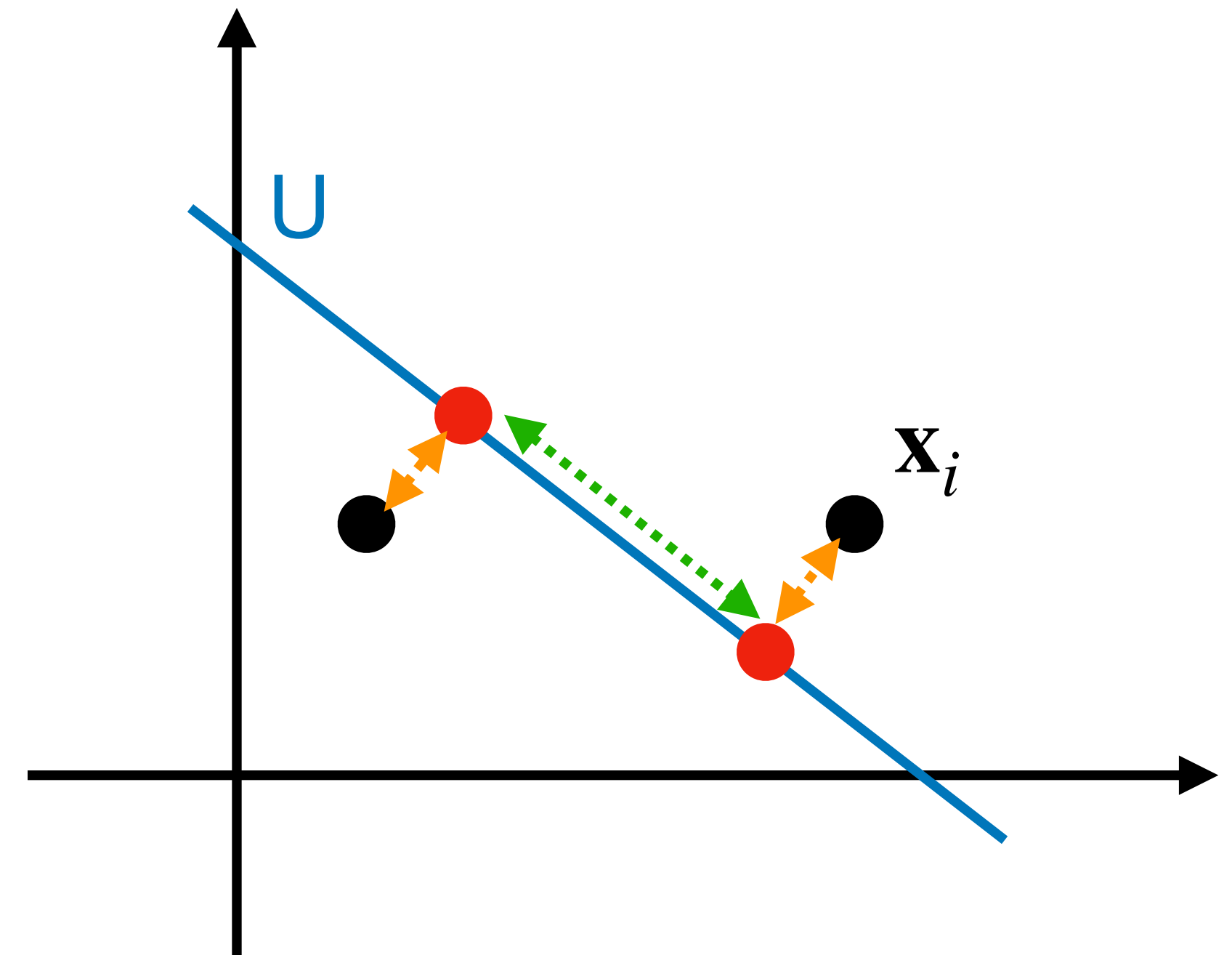
Goal. Find the k -dimensional subspace \mathbf{U} of \mathbb{R}^d such that:

- The projections has the **maximum variance**:

$$\max_{\mathbf{U}} \text{Var}(\pi_{\mathbf{U}}(\mathbf{x}_1), \dots, \pi_{\mathbf{U}}(\mathbf{x}_n))$$

- The **distortion** from projection is **minimized**:

$$\min_{\mathbf{U}} \sum_{i=1}^n \|\mathbf{x}_i - \pi_{\mathbf{U}}(\mathbf{x}_i)\|_2^2$$

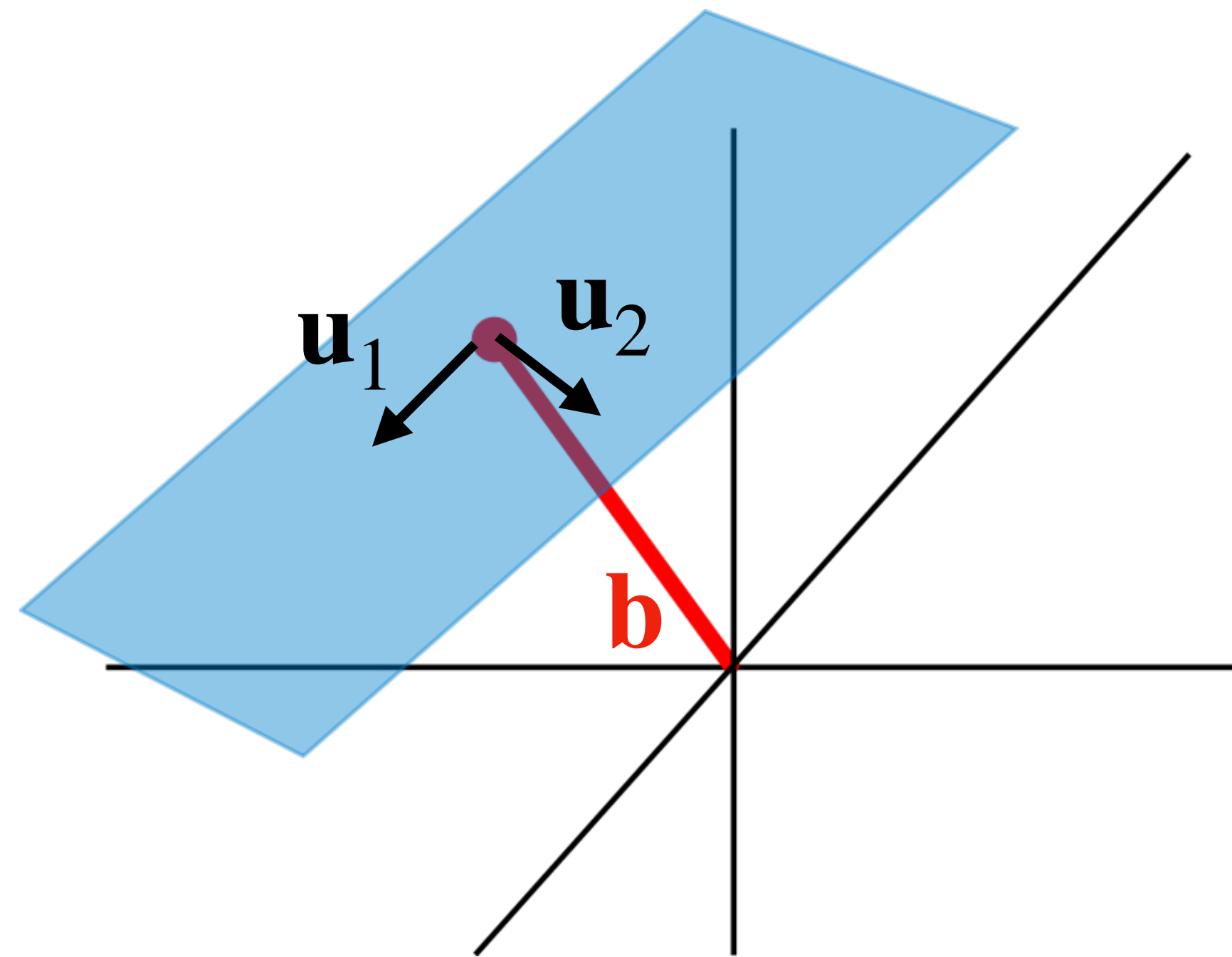


PCA as a Variance Maximization

Formalism: Affine Subspace

- A k -dimensional affine subspace $U \subset \mathbb{R}^d$ can be characterized by its orthonormal bases $\mathbf{u}_1, \dots, \mathbf{u}_k \in \mathbb{R}^d$ and an orthogonal bias $\mathbf{b} \in \mathbb{R}^d$ as

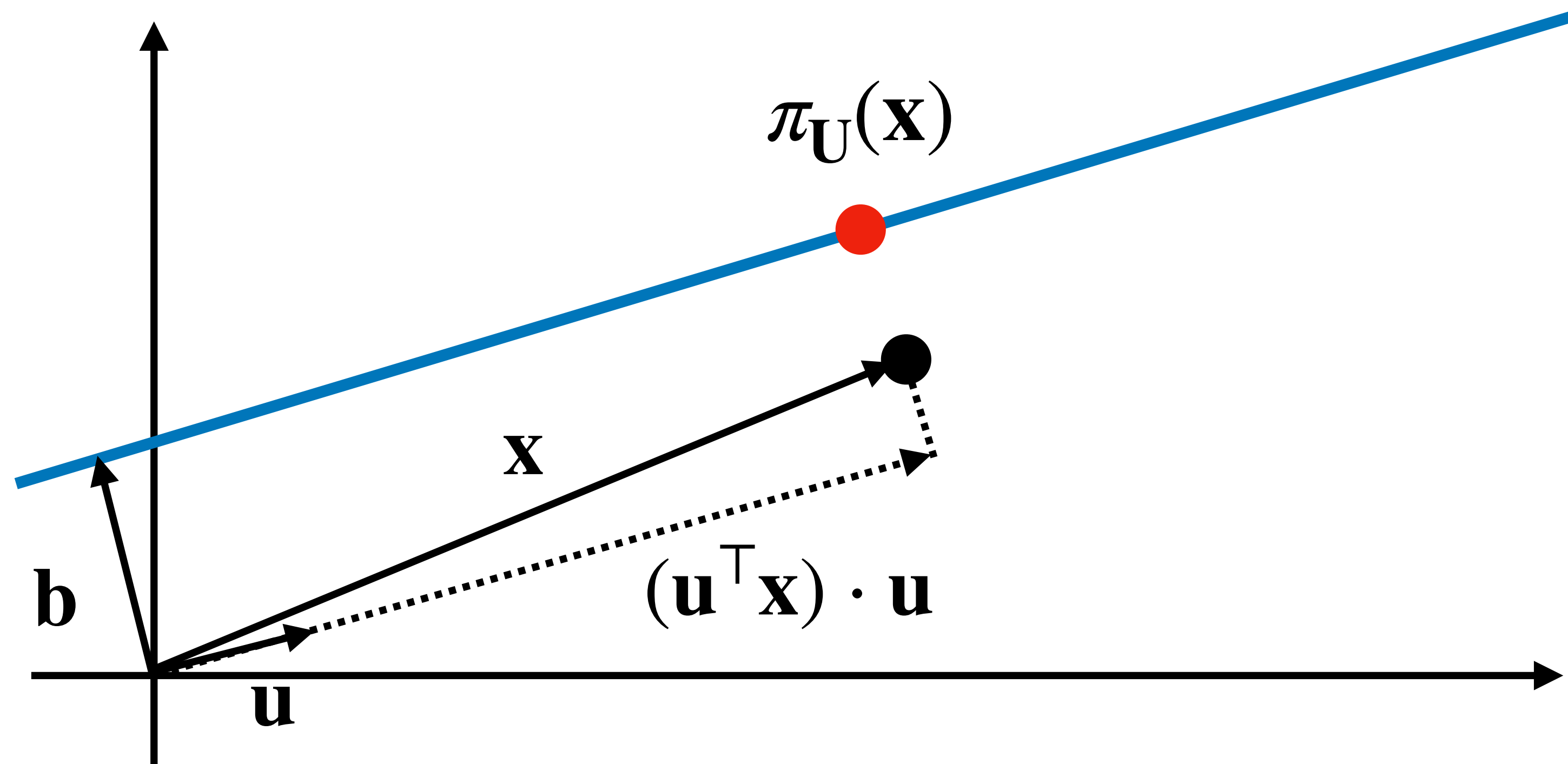
$$U = \{a_1 \mathbf{u}_1 + \dots + a_k \mathbf{u}_k + \mathbf{b} : a_i \in \mathbb{R}\}$$



Formalism: Projection

- A projection of a vector $\mathbf{x} \in \mathbb{R}^d$ to an affine subspace U is

$$\pi_U(\mathbf{x}) = \sum_{i=1}^k (\mathbf{u}_i^\top \mathbf{x}) \cdot \mathbf{u}_i + \mathbf{b}$$



Formalism: Projection

- This can be neatly written as a matrix form:

$$\begin{aligned}\pi_{\mathcal{U}}(\mathbf{x}) &= \sum_{i=1}^k (\mathbf{u}_i^{\top} \mathbf{x}) \cdot \mathbf{u}_i + \mathbf{b} \\ &= \left(\sum_{i=1}^k \mathbf{u}_i \mathbf{u}_i^{\top} \right) \mathbf{x} + \mathbf{b}\end{aligned}$$

$$=: \mathbf{U} \mathbf{x} + \mathbf{b}$$

 a $d \times d$ matrix with the rank k

Formalism: Projection

- The projection matrix has some useful properties.
 - $\mathbf{U}^T = \mathbf{U}$
 - $\mathbf{U}^T \mathbf{U} = \mathbf{U}$

(check by yourself!)

Variance maximization as a quadratic opt.

- Now, let's start looking into the variance maximization.

- We want to maximize the variance of the projected points, i.e.,

$$\text{Var}\left(\mathbf{U}\mathbf{x}_1 + \mathbf{b}, \dots, \mathbf{U}\mathbf{x}_n + \mathbf{b}\right)$$

- Because a constant term does not affect variance, this is equal to

$$\text{Var}\left(\mathbf{U}\mathbf{x}_1, \dots, \mathbf{U}\mathbf{x}_n\right)$$

Variance maximization as a quadratic opt.

$$\text{Var}\left(\mathbf{U}\mathbf{x}_1, \dots, \mathbf{U}\mathbf{x}_n\right)$$

- The mean of the $\{\mathbf{U}\mathbf{x}_i\}$ is $\mathbf{U}\bar{\mathbf{x}}$, where $\bar{\mathbf{x}}$ is the mean of $\{\mathbf{x}_i\}$.
- Thus, the variance is equal to

$$\begin{aligned}\frac{1}{n} \sum_{i=1}^n \|\mathbf{U}(\mathbf{x}_i - \bar{\mathbf{x}})\|_2^2 &= \frac{1}{n} \sum_{i=1}^n (\mathbf{x}_i - \bar{\mathbf{x}})^\top \mathbf{U}^\top \mathbf{U} (\mathbf{x}_i - \bar{\mathbf{x}}) \\ &= \frac{1}{n} \sum_{i=1}^n (\mathbf{x}_i - \bar{\mathbf{x}})^\top \mathbf{U} (\mathbf{x}_i - \bar{\mathbf{x}})\end{aligned}$$

Variance maximization as a quadratic opt.

$$\frac{1}{n} \sum_{i=1}^n (\mathbf{x}_i - \bar{\mathbf{x}})^\top \mathbf{U} (\mathbf{x}_i - \bar{\mathbf{x}})$$

- By definition of \mathbf{U} , we can re-write the above as

$$\begin{aligned} & \frac{1}{n} \sum_{i=1}^n \sum_{j=1}^k (\mathbf{x}_i - \bar{\mathbf{x}})^\top \mathbf{u}_j \mathbf{u}_j^\top (\mathbf{x}_i - \bar{\mathbf{x}}) \\ &= \sum_{j=1}^k \mathbf{u}_j^\top \left(\frac{1}{n} \sum_{i=1}^n (\mathbf{x}_i - \bar{\mathbf{x}}) (\mathbf{x}_i - \bar{\mathbf{x}})^\top \right) \mathbf{u}_j \\ & \quad = \text{sample covariance matrix } \mathbf{S} \\ & \quad \text{(positive-semidefinite)} \end{aligned}$$

Variance maximization as a quadratic opt.

- Thus, PCA is solving the **quadratic optimization**

$$\max_{\mathbf{u}_1, \dots, \mathbf{u}_k} \sum_{j=1}^k \mathbf{u}_j^T \mathbf{S} \mathbf{u}_j$$

subject to the **constraints**

$$\mathbf{u}_i^T \mathbf{u}_j = \begin{cases} 1 & \dots & i = j \\ 0 & \dots & i \neq j \end{cases}$$

Solving the quadratic optimization (k=1)

- Let us take a closer look at the problem.

$$\max_{\mathbf{u}_1, \dots, \mathbf{u}_k} \sum_{j=1}^k \mathbf{u}_j^\top \mathbf{S} \mathbf{u}_j, \quad \text{subject to} \quad \mathbf{u}_i^\top \mathbf{u}_j = \mathbf{1}\{i = j\}$$

- Consider **the simplest case where $k = 1$** , i.e.,

$$\max_{\mathbf{u}} \mathbf{u}^\top \mathbf{S} \mathbf{u}, \quad \text{subject to} \quad \|\mathbf{u}\|_2 = 1$$

- We see that the \mathbf{u} should be the **eigenvector** of \mathbf{S} corresponding to the **largest eigenvalue** (i.e., the principal component) **why?**

Why principal component?

(Version 1) Routine answer

To solve the constrained optimization

$$\max_{\mathbf{u}} \mathbf{u}^T \mathbf{S} \mathbf{u}, \quad \text{subject to} \quad \|\mathbf{u}\|_2 = \mathbf{u}^T \mathbf{u} = 1,$$

consider the Lagrangian relaxation

$$\max_{\mathbf{u}} \mathbf{u}^T \mathbf{S} \mathbf{u} + \alpha(1 - \mathbf{u}^T \mathbf{u}).$$

The critical point is at the point $\mathbf{S} \mathbf{u} = \alpha \mathbf{u}$ holds (i.e., eigenvectors).

Choosing the principal coefficient maximizes the value of $\mathbf{u}^T \mathbf{S} \mathbf{u}$

Why principal component?

(Version 2) If you don't like Lagrangian... (difficult to extend to $k=2$)

Let $(\mathbf{e}_1, \dots, \mathbf{e}_d)$ be the unit-norm eigenvectors of \mathbf{S} ,
with eigenvalues $(\lambda_1, \dots, \lambda_d)$ in the descending order.

Any choice of \mathbf{u} can be written as a *mixture of eigenvectors*

$$\mathbf{u} = w_1 \mathbf{e}_1 + \dots + w_d \mathbf{e}_d$$

with the weights $w_1^2 + \dots + w_d^2 = 1$. (energy in each direction, with total budget 1)

Why principal component?

The system \mathbf{S} scales each eigenvectors, i.e.,

$$\begin{aligned}\mathbf{S}\mathbf{u} &= \mathbf{S}(w_1\mathbf{e}_1 + \cdots + w_d\mathbf{e}_d) \\ &= w_1\mathbf{S}\mathbf{e}_1 + \cdots + w_d\mathbf{S}\mathbf{e}_d \\ &= w_1\lambda_1\mathbf{e}_1 + \cdots + w_d\lambda_d\mathbf{e}_d\end{aligned}$$

Thus, we have

$$\mathbf{u}^\top\mathbf{S}\mathbf{u} = w_1^2\lambda_1 + \cdots + w_d^2\lambda_d.$$

Optimal choice. Assign all weights to w_1 , i.e., $\mathbf{u} = \mathbf{e}_1$.

The Next Component

- Now, consider the case where $k = 2$.

$$\max_{\mathbf{u}_1, \mathbf{u}_2} \mathbf{u}_1^\top \mathbf{S} \mathbf{u}_1 + \mathbf{u}_2^\top \mathbf{S} \mathbf{u}_2, \quad \text{subject to } \|\mathbf{u}_1\| = \|\mathbf{u}_2\| = 1, \mathbf{u}_1^\top \mathbf{u}_2 = 0$$

- View this as a nested optimization problem

$$\max_{\|\mathbf{u}_1\|=1} \left(\mathbf{u}_1^\top \mathbf{S} \mathbf{u}_1 + \max_{\|\mathbf{u}_2\|=1, \mathbf{u}_2 \perp \mathbf{u}_1} (\mathbf{u}_2^\top \mathbf{S} \mathbf{u}_2) \right).$$

- Then, take a look at the inner maximization problem.

$$\max_{\|\mathbf{u}_2\|=1, \mathbf{u}_2 \perp \mathbf{u}_1} (\mathbf{u}_2^\top \mathbf{S} \mathbf{u}_2)$$

The Next Component

- The Lagrangian of the inner maximization becomes

$$\mathbf{u}_2^T \mathbf{S} \mathbf{u}_2 + \alpha \cdot (1 - \mathbf{u}_2^T \mathbf{u}_2) - \beta \cdot (\mathbf{u}_1^T \mathbf{u}_2)$$

- The critical point condition is where:

$$\mathbf{S} \mathbf{u}_2 = \alpha \mathbf{u}_2 + \frac{\beta}{2} \mathbf{u}_1$$

- Multiplying \mathbf{u}_1^T on both sides, we get

$$\begin{aligned} \mathbf{u}_1^T \mathbf{S} \mathbf{u}_2 &= \alpha \mathbf{u}_1^T \mathbf{u}_2 + \frac{\beta}{2} \mathbf{u}_1^T \mathbf{u}_1 \\ &= \mathbf{0} \qquad \qquad = \mathbf{0} \end{aligned}$$

... and thus $\beta = 0$

The Next Component

- Plugging in $\beta = 0$, we get

$$\mathbf{S}\mathbf{u}_2 = \alpha\mathbf{u}_2$$

- Thus, we should also select \mathbf{u}_2 as an eigenvector.
 - Selecting $\mathbf{u}_1, \mathbf{u}_2$ as eigenvectors for top-2 eigenvalues is optimal.

PCA, with k principal components

- Similarly, we can select the affine subspace spanned by

$$\{\mathbf{e}_1, \dots, \mathbf{e}_k\},$$

where $\mathbf{e}_1, \dots, \mathbf{e}_k$ are k principal components of the sample covariance matrix $\mathbf{S} = \frac{1}{n} \sum_{i=1}^n (\mathbf{x}_i - \bar{\mathbf{x}})(\mathbf{x}_i - \bar{\mathbf{x}})^\top$.

- This can be done by performing SVD on the data matrix

$$\mathbf{X} = [\mathbf{x}_1 - \bar{\mathbf{x}} \mid \dots \mid \mathbf{x}_n - \bar{\mathbf{x}}] = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^\top$$

and selecting the columns of \mathbf{U} for top- k singular values.

Cheers

- Next up. PCA as minimum reconstruction error, Kernel PCA, t-SNE, ...